

## Accepted Manuscript

A necessary and sufficient condition for designing formation of discrete-time multi-agent systems with delay

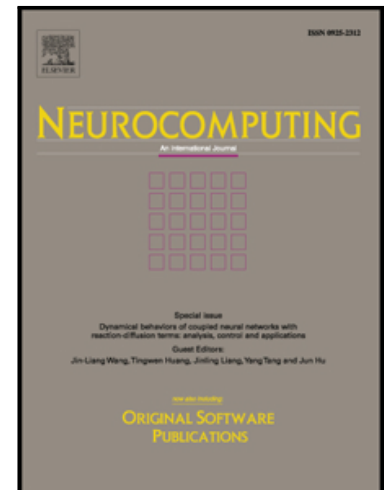
Gesheng Xu, Chi Huang, Guisheng Zhai

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## Highlights

- Compared with previous results on formation control and communication delay, the contributions of this paper are threefold. First, by establishing the appropriate control input, we transform the formation problem into an asymptotically stabilization problem, which is equivalent to designing a Schur polynomial (whose zeros are inside the open unit disk) with complex coefficients. Secondly, by using the bilinear transformation and Hurwitz polynomials with complex coefficients, we obtain a necessary and sufficient condition for our design problem. Thirdly, we discuss precisely how to simplify and solve the condition efficiently for both complex and real eigenvalues of the Laplacian matrix.

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