## Accepted Manuscript

An adaptive fuzzy predictive control of nonlinear processes based on Multi-Kernel least squares support vector regression

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PII: $\quad$ S1568-4946(18)30509-X
DOI: https://doi.org/10.1016/j.asoc.2018.08.044
Reference: ASOC 5078

To appear in: Applied Soft Computing Journal
Received date: 3 August 2017
Revised date: 25 August 2018
Accepted date: 28 August 2018

Please cite this article as: I. Boulkaibet, et al., An adaptive fuzzy predictive control of nonlinear processes based on Multi-Kernel least squares support vector regression, Applied Soft Computing Journal (2018), https://doi.org/10.1016/j.asoc.2018.08.044

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## Highlights

1) An adaptive Takagi-Sugeno system based on Multi-Kernel Least Squares Support Vector Regression (adaptive TS-LSSVR) was introduced for system identification.
2) The adaptive TS-LSSVR system was integrated within the generalized predictive controller (GPC).
3) The proposed adaptive TS-LSSVR GPC controller was used to control nonlinear systems.
4) The adaptive TS-LSSVR GPC controller has shown good performance in controlling nonlinear systems. Also, the proposed controller copes well with additional disturbances.

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