Contents lists available at ScienceDirect

Computational Geometry: Theory and Applications

www.elsevier.com/locate/comgeo

# The non-pure version of the simplex and the boundary of the simplex

### Nicolás A. Capitelli

Departamento de Matemática-IMAS, FCEyN, Universidad de Buenos Aires, Buenos Aires, Argentina

#### ARTICLE INFO

Article history: Received 14 July 2015 Accepted 4 May 2016 Available online 10 May 2016

Keywords: Simplicial complexes Combinatorial manifolds Alexander dual

#### 1. Introduction

ABSTRACT

We introduce the non-pure versions of simplicial balls and spheres with minimum number of vertices. These are a special type of non-homogeneous balls and spheres (*NH*-balls and *NH*-spheres) satisfying a minimality condition on the number of facets. The main result is that *minimal NH*-balls and *NH*-spheres are precisely the simplicial complexes whose iterated Alexander duals converge respectively to a simplex or the boundary of a simplex. © 2016 Elsevier B.V. All rights reserved.

A simplicial complex *K* of dimension *d* is *vertex-minimal* if it is a *d*-simplex or it has d + 2 vertices. It is not hard to see that a vertex-minimal homogeneous (or pure) complex of dimension *d* is either an elementary starring  $(\tau, a)\Delta^d$  of a *d*-simplex or the boundary  $\partial\Delta^{d+1}$  of a (d+1)-simplex. On the other hand, a general non-pure complex with minimum number of vertices has no precise characterization. However, since vertex-minimal pure complexes are either balls or spheres, it is natural to ask whether there is a non-pure analogue to these polyhedra within the theory of non-homogeneous balls and spheres. In [5] G. Minian and the author introduced *NH*-manifolds, a generalization of the concept of manifold to the non-pure setting (somewhat similar to Björner and Wachs's extension of the shellability definition to non-pure complexes [3]). In this theory, *NH*-balls and *NH*-spheres are the non-pure versions of combinatorial balls and spheres.

The purpose of this article is to study *minimal* NH-balls and NH-spheres, which are respectively the non-pure counterpart of vertex-minimal balls and spheres. Note that  $\partial \Delta^{d+1}$  is not only the *d*-sphere with minimum number of vertices but also the one with minimum number of facets. For non-pure spheres, this last property is strictly stronger than vertex-minimality and it is convenient to define minimal NH-spheres as the ones with minimum number of facets. With this definition, minimal NH-spheres with the homotopy type of a *k*-sphere are precisely the non-pure spheres whose nerve is  $\partial \Delta^{k+1}$ , a property that also characterizes the boundary of simplices. On the other hand, an NH-ball B is minimal if it is part of a decomposition of a minimal NH-sphere, i.e. if there exists a combinatorial ball L with  $B \cap L = \partial L$  such that B + L is a minimal NH-sphere. This definition is consistent with the notion of vertex-minimal simplicial ball (see Lemma 4.1 below).

Surprisingly, minimal *NH*-balls and *NH*-spheres can be characterized by a property involving Alexander duals. Denote by  $K^*$  the Alexander dual of a complex K relative to the vertices of K. Set inductively  $K^{*(0)} = K$  and  $K^{*(m)} = (K^{*(m-1)})^*$ . Thus, in each step  $K^{*(i)}$  is computed relatively to its own vertices, i.e. as a subcomplex of the boundary of the simplex of minimum dimension containing it. We call  $(K^{*(m)})_{m \in \mathbb{N}_0}$  the sequence of iterated Alexander duals of K. The main result of the article is the following.

http://dx.doi.org/10.1016/j.comgeo.2016.05.002 0925-7721/© 2016 Elsevier B.V. All rights reserved.







*E-mail address:* ncapitel@dm.uba.ar.

#### Theorem 1.1. Let K be a finite simplicial complex.

- (i) There is an  $m \in \mathbb{N}_0$  such that  $K^{*(m)}$  is the boundary of a simplex if and only if K is a minimal NH-sphere.
- (ii) There is an  $m \in \mathbb{N}_0$  such that  $K^{*(m)}$  is a simplex if and only if K is a minimal NH-ball.

In any case, the number of iterations needed to reach the simplex or the boundary of the simplex is bounded above by the number of vertices of *K*.

Note that  $K^* = \Delta^d$  if and only if K is a vertex-minimal d-ball which is not a simplex, so (*ii*) describes precisely all complexes *converging* to vertex-minimal balls. Theorem 1.1 characterizes the classes of  $\Delta^d$  and  $\partial \Delta^d$  in the equivalence relation generated by  $K \sim K^*$ .

#### 2. Preliminaries

#### 2.1. Notation and definitions

All simplicial complexes that we deal with are assumed to be finite. Given a set of vertices V, |V| will denote its cardinality and  $\Delta(V)$  the simplex spanned by its vertices.  $\Delta^d := \Delta(\{0, \dots, d\})$  will denote a generic *d*-simplex and  $\partial \Delta^d$  its boundary. The set of vertices of a complex *K* will be denoted  $V_K$  and we set  $\Delta_K := \Delta(V_K)$ . A facet of a complex *K* is a simplex which is not a proper face of any other simplex of *K*. We denote by f(K) the number of facets in *K*. A *ridge* is a maximal proper face of a facet. A complex is *pure* or *homogeneous* if all its facets have the same dimension.

We denote by  $\sigma * \tau$  the join of the faces  $\sigma, \tau \in K$  (if  $\sigma \cap \tau = \emptyset$ ) and by K \* L the join of the complexes K and L (if  $V_K \cap V_L = \emptyset$ ). By convention, if  $\emptyset$  is the empty simplex and  $\{\emptyset\}$  the complex containing only the empty simplex then  $K * \{\emptyset\} = K$  and  $K * \emptyset = \emptyset$ . Note that  $\partial \Delta^0 = \{\emptyset\}$ . For  $\sigma \in K$ ,  $lk(\sigma, K) = \{\tau \in K : \tau \cap \sigma = \emptyset, \tau * \sigma \in K\}$  denotes its *link* and  $st(\sigma, K) = \sigma * lk(\sigma, K)$  its *star*. The union of two complexes K, L will be denoted by K + L. A subcomplex  $L \subseteq K$  is said to be *top generated* if every facet of L is also a facet of K.

The notation  $K \searrow L$  will mean that K (simplicially) collapses to L. A complex is *collapsible* if it collapses to a single vertex and *PL-collapsible* if it has a subdivision which is collapsible. The *simplicial nerve*  $\mathcal{N}(K)$  of K is the complex whose vertices are the facets of K and whose simplices are the finite subsets of facets of K with non-empty intersection.

Two complexes are *PL-isomorphic* if they have a common subdivision. A *combinatorial d-ball* is a complex *PL-isomorphic* to  $\Delta^d$ . A *combinatorial d-sphere* is a complex *PL-isomorphic* to  $\partial \Delta^{d+1}$ . By convention,  $\partial \Delta^0 = \{\emptyset\}$  is a sphere of dimension -1. A *combinatorial d-manifold* is a complex *M* such that lk(v, M) is a combinatorial (d - 1)-ball or (d - 1)-sphere for every  $v \in V_M$ . A (d - 1)-simplex in a combinatorial *d*-manifold *M* is a face of at most two *d*-simplex. Combinatorial *d*-balls and *d*-spheres are combinatorial *d*-manifolds. The boundary of a combinatorial *d*-ball is a combinatorial (d - 1)-sphere.

#### 2.2. Non-homogeneous balls and spheres

In order to make the presentation self-contained, we recall first the definition and some basic properties of non-homogeneous balls and spheres. For a comprehensive exposition of the subject, the reader is referred to [5] (see also  $[6, \S2.2]$  for a brief summary).

*NH*-balls and *NH*-spheres are special types of *NH*-manifolds, which are the non-pure versions of combinatorial manifolds. *NH*-manifolds have a local structure consisting of regularly-assembled pieces of Euclidean spaces of different dimensions. In Fig. 1 we show some examples of *NH*-manifolds and their underlying spaces. *NH*-manifolds, *NH*-balls and *NH*-spheres are defined as follows.

**Definition.** An *NH*-manifold (resp. *NH*-ball, *NH*-sphere) of dimension 0 is a combinatorial manifold (resp. ball, sphere) of dimension 0. An *NH*-sphere of dimension -1 is, by convention, the complex { $\emptyset$ }. For  $d \ge 1$ , we define by induction:

- An *NH-manifold* of dimension *d* is a complex *M* of dimension *d* such that lk(v, M) is an *NH*-ball or an *NH*-sphere (possibly of dimension -1) for all  $v \in V_M$ .
- An *NH*-ball of dimension *d* is a PL-collapsible *NH*-manifold of dimension *d*.
- An *NH-sphere* of dimension *d* and *homotopy dimension k* is an *NH*-manifold *S* of dimension *d* such that there exist a top generated *NH*-ball *B* of dimension *d* and a top generated combinatorial *k*-ball *L* such that B + L = S and  $B \cap L = \partial L$ . We say that S = B + L is a *decomposition* of *S* and write dim<sub>h</sub>(*S*) for the homotopy dimension of *S*.

The definitions of *NH*-ball and *NH*-sphere are motivated by the classical theorems of Whitehead [9] and Newman [7] (see e.g. [8, Corollaries 3.28 and 3.13]). Just like for classical combinatorial manifolds, it can be seen that the class of *NH*-manifolds (resp. *NH*-balls, *NH*-spheres) is closed under subdivision and that the link of *every* simplex in an *NH*-manifold is an *NH*-ball or an *NH*-sphere. Also, the homogeneous *NH*-manifolds (resp. *NH*-balls, *NH*-spheres) are

Download English Version:

## https://daneshyari.com/en/article/414540

Download Persian Version:

https://daneshyari.com/article/414540

Daneshyari.com