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Location and mobility-aware routing for multimedia streaming in disaster telemedicine

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ABSTRACT

Disaster telemedicine leverages communications networks to provide remote diagnosis of injured persons in areas affected by disasters such as earthquakes. However, telemedicine relies heavily on infrastructure, and in a disaster scenario there is no guarantee that such infrastructure will be intact. In an ad-hoc network, devices form a network amongst themselves and forward packets for each other without infrastructure. Ad-hoc networks could be deployed in a disaster scenario to enable communications between responders and base camp to provide telemedicine services. However, most ad-hoc routing protocols cannot meet the necessary standards for streaming multimedia because they do not attempt to manage Quality of Service (QoS). Node mobility adds an additional layer of complexity leading to potentially detrimental effects on QoS. Geographic routing protocols use physical locations to make routing decisions and are typically lightweight, distributed, and require only local network knowledge. They are thus less susceptible to the effects of mobility, but are not impervious. Location-prediction can be used to enhance geographic routing, and counter the negative effects of mobility, but this has received relatively little attention. Machine Learning algorithms have been deployed for predicting locations in infrastructure networks with some success, but such algorithms require modifications for use in ad-hoc networks. This paper outlines the use of an Artificial Neural Network (NN) to perform location-prediction in an ad-hoc network.

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1. Introduction

Millions of people are affected every year by both natural and manmade disasters. These lead not only to death and injury, but also the devastation of communities and sometimes entire nations. A common feature of such events is people trapped in an area, either those who physically cannot be moved or are cut-off from the outside world, and who require treatment. Even when such people can be reached it may not always be possible for the appropriate medical services to reach them on time. The explosion of the Internet and other communications networks, has seen the field

of telemedicine go from a relatively obscure military system, to a disruptive service that millions of people around the world use to access medical care remotely. Today applications of telemedicine range from performing appointments over video conferencing to remote operation of medical equipment in surgery (Roine, Ohinmaa and Hailey, 2001). Telemedicine can therefore be of great benefit in providing services to people who are unable to access them directly, or allowing institutes to provide treatments they normally wouldn't be able to. In essence telemedicine seems perfect for use in disaster recovery scenarios. If doctors cannot attend an injured person then they can consult remotely, perform a diagnosis, provide instructions on treatment to others, and monitor the patients' condition. Telemedicine has been utilised during disasters, but its use so far is limited. After an earthquake in North Pakistan a field hospital was set up

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28 and webcams and computers used to communicate with re- 89
29 mote specialists. Of the patients seen at the hospital a total 90
30 of 28 patients were treated in some way via telemedicine 91
31 [7]. Another example of telemedicine being utilised in the 92
32 wake of a natural disaster is the University of Texas' existing 93
33 telemedicine being damaged by a hurricane and a temporary 94
34 telemedicine system being set up in its place [20]. However 95
35 both of these systems, although being deployed in disaster 96
36 recovery scenarios, made use of existing infrastructure albeit 97
37 limited infrastructure in the case of the latter. Unfortunately 98
38 communications infrastructure is not always available after a 99
39 disaster. Cell towers and wired connections are all prone to 100
40 damage. Even when some infrastructure is intact, it may not 101
41 always be suitable for performing telemedicine. When you 102
42 are treating a patient remotely a certain quality of video is 103
43 required, and a damaged network may not always be able to 104
44 deliver it. 105

45 Where communication between people in the disaster 106
46 area or the vicinity of it is desired then ad-hoc networks 107
47 could be a potential solution. Ad-hoc networks are an 108
48 infrastructure-free model for networking in which devices 109
49 wishing to communicate with each other form a network 110
50 amongst themselves. Routing is then performed on a multi- 111
51 hop basis where nodes forward a packet to each other until 112
52 it reaches the destination. Thus all connected nodes are 113
53 not only end-users, but also routers. Ad-hoc networks are 114
54 considered to be distributed and decentralised as there is no 115
55 infrastructure or servers. This can be seen as either an advan- 116
56 tage or disadvantage, as the lack of control can lead to issues 117
57 in ensuring all nodes behave correctly, but it can also prevent 118
58 attackers from being able to destroy the network by targeting 119
59 infrastructure. While an ad-hoc network cannot bridge a 120
60 divide between the disaster area and the outside world, it 121
61 can facilitate communication within it. Even if medical 122
62 personnel are present they may not be able to attend directly 123
63 to every injured person. If a first responder with some basic 124
64 medical training could communicate with a doctor located 125
65 at base-camp, the doctor could then relay instructions to 126
66 the responder on how to handle the patient. Where some 127
67 infrastructure is intact this could be incorporated into the 128
68 network to allow devices who are able to connect to the 129
69 ad-hoc network to access the outside world via it. The 130
70 traditional ad-hoc model does not make any provision for 131
71 this, but a sub-type the Hybrid Wireless Mesh (HWM) does. 132
72 HWMs are similar to ad-hoc networks in that devices form 133
73 a multi-hop network, but where they differ is their ability to 134
74 incorporate infrastructure that can then be accessed through 135
75 the multi-hop network by devices. In a disaster recovery 136
76 scenario this would allow devices able to connect to the Internet 137
77 to share their connection with other devices in the network. 138
78 A significant problem limiting the use of ad-hoc networks for 139
79 disaster telemedicine is QoS. To provide a suitable streaming 140
80 service, strict levels of packet loss, delay, and jitter must 141
81 be maintained. Ad-hoc network protocols are typically best 142
82 effort, with the primary aim being to forward every packet 143
83 to the destination. As such, ad-hoc networking protocols do 144
84 not typically mechanisms such as classification and resource 145
85 reservation found in infrastructure networks. As ad-hoc net- 146
86 works are not centrally managed implementing such policies 147
87 is fraught with a number of organisational difficulties. Simi- 148
88 larly, another technique used to manage QoS in infrastructure 149

networks is inappropriate; overprovisioning, whereby sig- 89
nificantly more capacity than is typically required is installed 90
to provide redundancy. That is not to say that managing 91
QoS and achieving standards suitable for streaming media in 92
ad-hoc networks is impossible. However existing paradigms 93
developed for infrastructure networks may be inappropriate, 94
and thus new techniques must be devised. 95

Such approaches must overcome not only the challenge of 96
decentralisation, but also other factors that make ad-hoc net- 97
works unique. One such factor is the potential for dynamic 98
behaviour. While individual devices in an infrastructure net- 99
work may fail, it is highly unlikely that such devices will be 100
removed at random, and there will probably be some form of 101
contingency measure. In an ad-hoc network nodes may leave 102
or join at any point. This can have a disastrous effect, as the 103
loss of one node can leave a node without a path, resulting 104
in potentially wasted transmissions and the need to find an- 105
other path. This problem is compounded in instances where 106
mobility is permissible. Such networks are typically referred 107
to as Mobile Ad-hoc Networks (MANETs). In contrast to static 108
ad-hoc networks, MANETs are significantly more dynamic as 109
node mobility can have a huge effect on connectivity. Even 110
where a user does not wish to leave the network, if they move 111
outside the range of another node the connection is lost. If 112
ad-hoc networks are deployed in disaster recovery scenarios 113
then it is likely they will take the form of a MANET. Even if the 114
users of the stream remain static, there is no guarantee that 115
the users of the other device that comprise the network con- 116
necting them will remain immobile. Thus mobility is liable 117
to play a significant factor in the performance of any disaster 118
recovery ad-hoc network. 119

If end-user applications are able to make use of a device's 120
location and mobility data then it is logical to consider 121
the possibility of using such information at the network- 122
layer. Geographic routing covers a broad range of protocols 123
that make use of such information varying extents. Geograph- 124
ic routing originates from a technical paper published by (Finn, 125
1987) that suggest the use of physical location in 126
forwarding decisions. In its most basic form, greedy geograph- 127
ic forwarding, geographic routing forwards packets to 128
neighbours based on their proximity to the destination. In 129
addition to making use of physical locations, greedy routing 130
is also lightweight as nodes do not store routing tables or 131
topology. Instead nodes maintain a list of directly connected 132
neighbours and perform forwarding on per-hop basis, select- 133
ing the neighbour closest to the destination and dropping 134
the packet if no neighbour closer to the destination than the 135
node itself can be found. This is done so as to avoid the possi- 136
bility of routing loops where a packet travels backwards. 137
Other approaches to geographic routing include face routing 138
based on the Compass II protocol (Kranakis, 1999) where 139
nodes traverse a planar graph and which theoretically guar- 140
antees delivery, but is considerably less efficient than greedy 141
routing, as well as hybrid greedy–face protocols that comb- 142
ine the two approaches such as Greedy Perimeter Stateless 143
Routing (GPSR) [9]. Geographic (or location-aware) protocols 144
can also utilise location information to optimise specific cri- 145
teria, such as in [17] where location is used to compute the 146
connection time between two nodes, and [16] where mobil- 147
ity serves as an indicator of delay and jitter. These two proto- 148
cols are interesting applications of how physical locations can 149

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