

Accepted Manuscript

Reactive control architecture for mobile robot autonomous navigation

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PII: S0921-8890(16)30541-3
DOI: <http://dx.doi.org/10.1016/j.robot.2016.09.001>
Reference: ROBOT 2694

To appear in: *Robotics and Autonomous Systems*

Received date : 17 March 2015
Revised date : 23 August 2016
Accepted date : 1 September 2016

Please cite this article as: E. Baklouti, et al., Reactive control architecture for mobile robot autonomous navigation, *Robotics and Autonomous Systems* (2016), <http://dx.doi.org/10.1016/j.robot.2016.09.001>

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Highlights

- Reactive control architecture for autonomous wheelchair mobile robot navigation is proposed.
- Interactions between elementary controllers goal tracking, obstacle avoidance and hybrid localization provide autonomous, safe and smooth wheelchair navigation.
- 3D Deformable Virtual Zone approach allows 3D, dynamic and suspended obstacles detection.

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