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Multi-Object Tracking Through Learning Relational Appearance Features and Motion Patterns

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## Highlights

- A new MOT system based on discriminative relational features-based data association is proposed.
- Both linear and non-linear motion patterns learning is adopted to facilitate the MOT system.
- Comparisons with the state-of-the-art MOT systems on public datasets show that the significance of the proposed MOT system in terms of both accuracy and execution time.

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