



Spectral analysis and global well-posedness for a viscous tropical climate model with only a damp term



Caochuan Ma^a, Renhui Wan^{b,*}

^a Department of mathematics, Tianshui Normal University, Tianshui 741001, Gansu, China

^b School of Mathematical Sciences, Nanjing Normal University, Nanjing 210032, China

ARTICLE INFO

Article history:

Received 4 August 2016

Received in revised form 12 January 2017

Accepted 9 August 2017

Keywords:

Tropical climate model

Global well-posedness

Spectral analysis

ABSTRACT

Tropical climate model derived by Frierson–Majda–Pauluis in Frierson et al. (2004) has been studied by many works (see, e.g., Li and Titi (2016); Li and Titi (2016); Wan (2016)). In this paper, we consider the Cauchy problem for the viscous tropical climate model with only a damp term and obtain the global well-posedness for the small data. The estimate of $\int_0^t \|\nabla\theta\|_{L^\infty}^2 d\tau$ is the main difficulty. To achieve our goal, we need using the spectral analysis to the system and constructing a new energy estimate of u in Besov space.

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1. Introduction

In this paper, we consider the Cauchy problem for the viscous tropical climate model with only one damp term which reads as follows:

$$\begin{cases} \partial_t u + u \cdot \nabla u - \Delta u + \nabla p = -\operatorname{div}(v \otimes v), \\ \partial_t v + u \cdot \nabla v + v \cdot \nabla u + v = \nabla \theta, \\ \partial_t \theta + u \cdot \nabla \theta = \operatorname{div} v, \\ \operatorname{div} u = 0, \\ (u, v, \theta)(t, x)|_{t=0} = (u_0(x), v_0(x), \theta_0(x)), \end{cases} \quad (1.1)$$

where $(t, x) \in \mathbb{R}^+ \times \mathbb{R}^2$, $u = (u^1, u^2)$, $v = (v^1, v^2)$ stand for the barotropic mode and the first baroclinic mode of the vector velocity, respectively, p , θ represent the scalar pressure, scalar temperature, respectively. We call $-\Delta u$ the viscous term or the Laplacian term, while the fourth term v of the left-hand side of (1.1)₂ is the damped term. Let us note that u satisfies the divergence free condition.

By performing a Galerkin truncation to the hydrostatic Boussinesq equations, Frierson–Majda–Pauluis in [1] derived the original version of (1.1) without any Laplacian terms, of which the first baroclinic mode had

* Corresponding author.

E-mail addresses: ma.caochuan@yahoo.com (C. Ma), rhwanmath@zju.edu.cn (R. Wan).

been originally used in some studies of tropical atmosphere in [2,3]. For more details on the first baroclinic mode, we refer to Sections 1 and 2 in [1] and references therein.

Li–Titi [4] had proved the global well-posedness for a tropical climate model with two Laplacian terms which can be derived from replacing v in (1.1)₂ by $-\Delta v$. In that paper, one can see it is difficult to get the gradient estimate of (u, v, θ) directly due to the absence of thermal diffusion. But via constructing a new unknown \mathfrak{w} ,

$$\mathfrak{w} \stackrel{def}{=} v - \nabla(-\Delta)^{-1}\theta,$$

they improved the regularity of u , and then obtained the gradient estimate of (u, v, θ) . It is clear that the Laplacian term $-\Delta u$ plays a key role in their proof. We also refer to a related work [5].

Provided without the Laplacian term $-\Delta v$, it seems difficult to obtain the gradient estimate of (u, v, θ) . And adding a damping term v does not appear to be sufficient to overcome this difficulty. To the best of our knowledge, many damped models such as damped Navier–Stokes equations [6], compressible Euler equations [7] and MHD equations [8] have been studied. Due to (1.1)₃ without any damping or dissipation, one can see it is a involved problem to establish the global well-posedness for (1.1) even with small initial data. Our aim here is for small global strong solution.

Very recently, the author [9] studied a new model given by

$$\begin{cases} \partial_t u + u \cdot \nabla u + \alpha u + \nabla p = -\operatorname{div}(v \otimes v), \\ \partial_t v + u \cdot \nabla v + v \cdot \nabla u + \alpha v - \eta \Delta v = \nabla \theta, \\ \partial_t \theta + u \cdot \nabla \theta = \operatorname{div} v, \\ \operatorname{div} u = 0, \\ (u(0, x), v(0, x), \theta(0, x)) = (u_0(x), v_0(x), \theta_0(x)) \end{cases}$$

and obtained the global well-posedness with small data. The difficulty is that we need a temperature diffusion to close the estimate of the nonlinear term $u \cdot \nabla \theta$. By a new analysis of the linear key part

$$\begin{cases} \partial_t v + \alpha v - \eta \Delta v - \nabla \theta = 0, \\ \partial_t \theta - \operatorname{div} v = 0 \end{cases}$$

and a new unknown

$$\Omega \stackrel{def}{=} \mathcal{R}v + \eta \Delta \theta,$$

where $\mathcal{R} := \Lambda^{-1} \operatorname{div}$, the hidden temperature diffusion was obtained.

Now, let us show our main result.

Denote

$$E_1(t) := \sup_{0 \leq \tau \leq t} \|(u, v, \theta)(\tau)\|_{H^s}^2 + \int_0^t \|(\nabla u, v)(\tau)\|_{H^s}^2 d\tau,$$

$$E_2(t) := \sup_{0 \leq \tau \leq t} \|u(\tau)\|_{\dot{B}_{2,1}^0} + \int_0^t \|u(\tau)\|_{\dot{B}_{2,1}^2} d\tau,$$

and

$$E_1(0) := \|(u_0, v_0, \theta_0)\|_{H^s}^2, \quad E_2(0) := \|u_0\|_{\dot{B}_{2,1}^0}.$$

Theorem 1.1. Consider (1.1) with the initial data (u_0, v_0, θ_0) satisfying

$$(u_0, v_0, \theta_0) \in H^s(\mathbb{R}^2), \quad s > 3 \text{ and } u_0 \in \dot{B}_{2,1}^0(\mathbb{R}^2), \quad \operatorname{div} u_0 = 0.$$

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