# All roots spectral methods: Constraints, floating point arithmetic and root exclusion 

John P. Boyd ${ }^{a, *}$, Călin-Ioan Gheorghiu ${ }^{\text {b }}$<br>${ }^{\text {a }}$ Department of Climate 8 Space Sciences and Engineering, University of Michigan, 2455 Hayward Avenue, Ann Arbor, MI 48109, United States<br>b Romanian Academy, "T. Popoviciu" Institute of Numerical Analysis, Cluj-Napoca, Romania

## A R T I C L E I N F O

## Article history:

Received 14 October 2016
Received in revised form 29
November 2016
Accepted 30 November 2016
Available online 7 December 2016

## Keywords:

Chebyshev polynomials
Nonlinear ordinary differential equations
Two-point boundary value problem Lemniscate elliptic function
Computer algebra

## A B S T R A C T

The nonlinear two-point boundary value problem (TPBVP for short)

$$
u_{x x}+u^{3}=0, u(0)=u(1)=0
$$

offers several insights into spectral methods. First, it has been proved a priori that $\int_{0}^{1} u(x) d x=\pi / \sqrt{2}$. By building this constraint into the spectral approximation, the accuracy of $N+1$ degrees of freedom is achieved from the work of solving a system with only $N$ degrees of freedom. When $N$ is small, generic polynomial system solvers, such as those in the computer algebra system Maple, can find all roots of the polynomial system, such as a spectral discretization of the TPBVP. Our second point is that floating point arithmetic in lieu of exact arithmetic can double the largest practical value of $N$. (Rational numbers with a huge number of digits are avoided, and eliminating $M$ symbols like $\sqrt{2}$ and $\pi$ reduces $N+M$-variate polynomials to polynomials in just the $N$ unknowns.) Third, a disadvantage of an "all roots" approach is that the polynomial solver generates many roots - $\left(3^{N}-1\right)$ for our example - which are genuine solutions to the $N$-term discretization but spurious in the sense that they are not close to the spectral coefficients of a true solution to the TPBVP. We show here that a good tool for "root-exclusion" is calculating $\rho \equiv \sqrt{\sum_{n=1}^{N} b_{n}^{2}}$; spurious roots have $\rho$ larger than that for the physical solution by at least an order of magnitude. The $\rho$-criterion is suggestive rather than infallible, but root exclusion is very hard, and the best approach is to apply multiple tools with complementary failings.
© 2016 Elsevier Ltd. All rights reserved.

## 1. Introduction

The two-point boundary-value problem

$$
\begin{equation*}
u_{x x}+u^{3}=0, \quad u(0)=u(1)=0 \tag{1}
\end{equation*}
$$

[^0]has the exact solution
\[

$$
\begin{equation*}
u=2 \mathcal{K} \mathrm{cn}(2 \mathcal{K}(x-1 / 2), 1 / \sqrt{2}), \quad \mathcal{K}=1.85407 \tag{2}
\end{equation*}
$$

\]

where "cn" is the usual Jacobian elliptic function and $\mathcal{K}=K(1 / \sqrt{2})$ is the complete elliptic integral for an elliptic modulus $k=1 / \sqrt{2}$. Boyd showed that the problem is "cryptoperiodic" in the sense the most efficient spectral basis is a Fourier basis [1] because the elliptic function is periodic. Here, we apply a polynomial basis partly for comparison and partly and more importantly because polynomial approximations are more widely used than the Fourier basis.

Although difficult problems require $N$ very large where $N$ is the number of degrees of freedom, spectral methods are so powerful that they are often accurate even for very small $N$. This makes it possible to bypass Newton's iteration and its ilk by applying a polynomial system solver to find all its zeros. This system of $N$ equations in $N$ unknowns is the spectral discretization of the TPBVP and the unknowns are the coefficients of the Chebyshev polynomial approximation [1,2].

## 2. Imposing an integral constraint

$N$ can be minimized by incorporating symmetry and boundary conditions into the form of the approximation. Here $u(x)$ is symmetric with respect to reflection about the midpoint of the interval [1]; this symmetry can be imposed by including only basis functions with the same symmetry, that is, only even degree (shifted) Chebyshev polynomials, yielding

$$
\begin{equation*}
u_{N}(x)=x(1-x)\left\{b_{0}+\sum_{n=1}^{N} b_{n} T_{2 n}(2 x-1)\right\} \tag{3}
\end{equation*}
$$

Independent of the coefficients $b_{n}, u_{N}(0)=u_{N}(1)=0$ and $u_{N}(1-x)=u_{N}(x)$.
Gheorghiu and Trif [3] observed that

$$
\begin{equation*}
\int_{0}^{1} u(x) d x=\pi / \sqrt{2} . \tag{4}
\end{equation*}
$$

This can be used to express $b_{0}$ in terms of the other $b_{n}$. We assume that the two boundary conditions will be incorporated into the algorithm also. Thus, although the approximation contains only $N$ degrees of freedom, it is a polynomial of degree $(N+2)$ and thus a polynomial with $(N+3)$ coefficients.

Table 1 shows that for this smooth problem, albeit a cubically nonlinear problem, the four degree of freedom approximation has a maximum pointwise error which is only $1 / 14,600$ of the maximum of $u(x)$. The complete Maple listing is given in Table 2.

The theory and practice of low degree polynomial spectral methods are described in Chapter 20 of [4], Chapter 2 of [5], Chapters 1 through 6 of [6], the review [7] and [1,7,8].

## 3. The downside of exact arithmetic

In our Maple 15 system running in Windows 7, the largest feasible number of degrees of freedom was limited by system crashes to $N_{\text {feasible }}=2$ when exact arithmetic was used as far as possible in the computation. $N_{\text {feasible }}$ was doubled by altering a single line:

$$
\begin{equation*}
r[m]->\operatorname{evalf}(r[m]) \tag{5}
\end{equation*}
$$

where $r[m]$ is the $m$ th equation of Galerkin system and where "evalf" is the Maple command to force replacement of symbols like $\sqrt{2}, \pi$ and $\operatorname{Bessel} J(0)$ by their floating equivalents. Why does "evalf" make such a difference?

# https://daneshyari.com/en/article/5471636 

Download Persian Version:

## https://daneshyari.com/article/5471636

## Daneshyari.com


[^0]:    * Corresponding author.

    E-mail addresses: jpboyd@umich.edu (J.P. Boyd), ghcalin@ictp.acad.ro (C.-I. Gheorghiu).

