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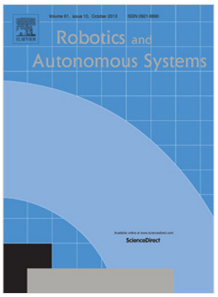

Collision risk assessment of occluded vehicle based on the motion predictions using the precise road map

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PII: S0921-8890(17)30874-6
DOI: https://doi.org/10.1016/j.robot.2018.05.005
Reference: ROBOT 3028

To appear in: *Robotics and Autonomous Systems*

Received date : 5 December 2017
Revised date : 20 March 2018
Accepted date : 7 May 2018

Please cite this article as: M. Lee, M. Sunwoo, K. Jo, Collision risk assessment of occluded vehicle based on the motion predictions using the precise road map, *Robotics and Autonomous Systems* (2018), https://doi.org/10.1016/j.robot.2018.05.005

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