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Development of computer aided clamping system design for workpieces with freeform surfaces

Mohammad Javad Nategh, Hadi Parvaz

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Highlights:

- Development of mathematics for automated clamping system design for NURBS surfaces
- Introduction of contrariety and repelling intensity factors for efficient design
- Application of minimum norm principle to stability check needed for NURBS surfaces
- Ensuring use of minimum number of clamps to keep contact between part and locators

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