Accepted Manuscript

Multi-sensor Fusion Methodology for Enhanced Land Vehicle Positioning

Xu Li, Wei Chen, Chingyao Chan, Bin Li, Xianghui Song

 PII:
 S1566-2535(16)30156-7

 DOI:
 10.1016/j.inffus.2018.04.006

 Reference:
 INFFUS 976

To appear in: Information Fusion

Received date:	15 November 2016
Revised date:	23 March 2017
Accepted date:	25 April 2018

Please cite this article as: Xu Li, Wei Chen, Chingyao Chan, Bin Li, Xianghui Song, Multisensor Fusion Methodology for Enhanced Land Vehicle Positioning, *Information Fusion* (2018), doi: 10.1016/j.inffus.2018.04.006

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Highlights

- A novel EITF algorithm is proposed to de-noise the MEMS IMU.
- A novel interval thresholding scheme is designed to improve the filtering performance.
- A LSSVM-NARX/KF hybrid strategy is proposed to compensate the INS position errors.

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