



Modeling and control of hybrid photovoltaic wind power system with battery storage



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ABSTRACT

In this paper, the model and the control of hybrid power system is presented. It comprises wind and photovoltaic sources with battery storage supplying a load via an inverter. First, the design and the identification of the hybrid power system components has been made, then the proposed system is modeled and simulated under Matlab/Simulink Package. Finally, the power control of the hybrid system is introduced, by using LabVIEW Software. The proposed control strategy has been experimentally implemented and practical results are presented to show the effectiveness of the proposed hybrid system.

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1. Introduction

Hybrid systems with wind and photovoltaic energy sources have received considerable attention for last decades [1–25]. In addition to energy sources, a hybrid system may also include DC or AC converters, a storage system, filters and a control system for load management. All these components can be connected in different architectures [1,2,16]. Data-acquisition systems are widely used in renewable energy source applications in order to collect data regarding the installed system performance and for evaluation purposes. The collected data is first conditioned using exact electronic circuits and then interfaced to a PC using a data-acquisition card [1,2]. LabVIEW is an environmental development program, developed by National Instruments (NI). It is similar to C and BASIC's environment development. There is an obvious difference between LabVIEW and other computer languages: Other computer languages are used to generate based code on the language of the text, whereas LabVIEW uses a graphical editing language G. The resulting program is the form of block diagram [19,20].

A control and a power management of a standalone hybrid renewable energy system comprising wind and photovoltaic sources with battery storage are introduced. The development of

a data acquisition system for electrical hybrid systems parameters is described. The LabVIEW program is used for further process, display and storage of the collected data in a hard disk PC. The sizing of the proposed system is detailed. It depends mainly on the site location that dictates the average wind speed, the turbine orientation, the solar irradiance and the average energy consumption of the application. An identification of all components of the proposed system has been made. The obtained results using LabVIEW Software are presented to demonstrate the effectiveness of the proposed system.

2. Hybrid system description

The studied system consists of six photovoltaic panels (with 175 W_c for each panel) connected in parallel, and wind turbine of 1 kW, batteries bank, inverter, and sensors measurement (Fig. 1).

2.1. Photovoltaic power system

2.1.1. Measured sensors

The block diagram of the climatic measurement card consists of a sensor solar radiation, a temperature sensor and a symmetrical power supplying (Fig. 2). We opted for a temperature sensor LM35-type semiconductor, the sensor has a sensitivity of 10 mV/°C. To avoid transmission losses, it is proposed to amplify the output voltage with a amplifier:

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Nomenclature

A	ideality factor of the junction	R_{batt}	internal battery resistance
$C_p(\lambda)$	power coefficient	R_{se}	series resistor
C_{10}	rated capacity	R_{sh}	shunt resistor
E_{batt}	voltage source	SOC	state of charge
E_s	insolation in the panel plane	t	discharging time
E_{sref}	reference insolation (1000 W/m ²)	T_{aero}	aerodynamic torque
f	viscous frictions	T_j	junction temperature of the modules
f_r	frequency 50 Hz	T_{jref}	reference module temperature (25 °C)
I_{batt}	battery current	T_g	machine torque shaft
I_{ph}	photocurrent of the PV generator	T_{visq}	torque due to frictions
I_{pv}	photovoltaic current	U_{batt}	battery voltage
I_s	cell reverse saturation current	V_{pv}	photovoltaic voltage
J	total inertia	u_{wind}	wind velocity
K	Boltzman's constant	X_{batt}	battery reactance
G	gearbox	Z_{batt}	battery impedance
n_{batt}	battery cells	ρ	air density
N_p	number of parallel modules	ρ_{batt}	phase-shift between current and voltage battery
N_s	number of series modules	Ω_{mec}	mechanical speed
PV	photovoltaic	$\Omega_{\text{mec-ref}}$	reference mechanical speed
P_{pv}	photovoltaic power	Ω_{turbine}	turbine speed
q	elementary charge	λ	tip speed ratio
R	turbine radius		

$$G_{\text{voltage}} = \frac{U_{\text{out}}}{U_{\text{in}}} = \frac{R_9 + R_7}{R_9} \quad (1)$$

The key component is the electronic circuit for the photodiode under the influence of light, the photodiode generates a very low order of micro current, we had to convert current to voltage and amplified more, using a LM358 amplifier with:

$$G_{\text{LM358}} = \frac{R_1 * R_3}{R_2} \quad (2)$$

The realized solar radiation and temperature sensors are represented in Fig. 3.

The output measure is given in Fig. 4.

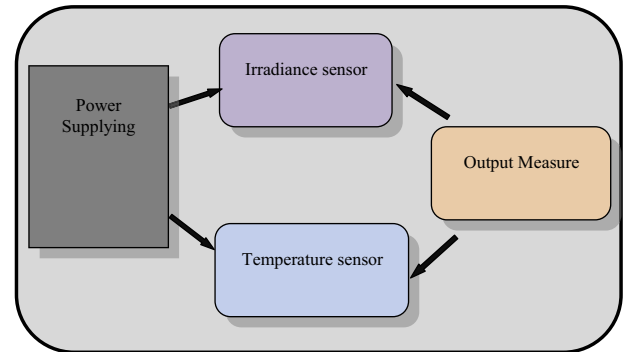


Fig. 2. Climatic measurement card.

2.1.2. Photovoltaic panel model

A photovoltaic (PV) power system consists of six solar panels (NT175E1) of 175 W_c (Fig. 5). The parameters of PV panels are given in Table 1.

The model studied in this work is represented by an equivalent circuit. This one consists of a single diode for the cell polarization function and two resistors (series and shunt) for the losses (Fig. 6). Thus, it can be named “one diode model”. This model runs

under the technical characteristics of the solar cells given by the manufacturers (data sheets).

The $I_{\text{pv}}(V_{\text{pv}})$ characteristic of this model is given by the following equation [1,4,9,13]:



Fig. 1. Installed hybrid wind-photovoltaic system.



Fig. 3. Realized solar radiation and temperature sensors.

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