Accepted Manuscript

Programmable actuating systems based on swimming fiber robots

Hao Sun, Meng Liao, Jianfeng Li, Chao Zhou, Jue Deng, Xuemei Fu, Songlin Xie, Bo Zhang, Yizheng Wu, Bingjie Wang, Xuemei Sun, Huisheng Peng

PII: S0008-6223(18)30622-5

DOI: 10.1016/j.carbon.2018.06.056

Reference: CARBON 13261

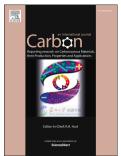
To appear in: Carbon

Received Date: 27 February 2018

Revised Date: 16 June 2018 Accepted Date: 24 June 2018

Please cite this article as: H. Sun, M. Liao, J. Li, C. Zhou, J. Deng, X. Fu, S. Xie, B. Zhang, Y. Wu, B. Wang, X. Sun, H. Peng, Programmable actuating systems based on swimming fiber robots, *Carbon* (2018), doi: 10.1016/j.carbon.2018.06.056.

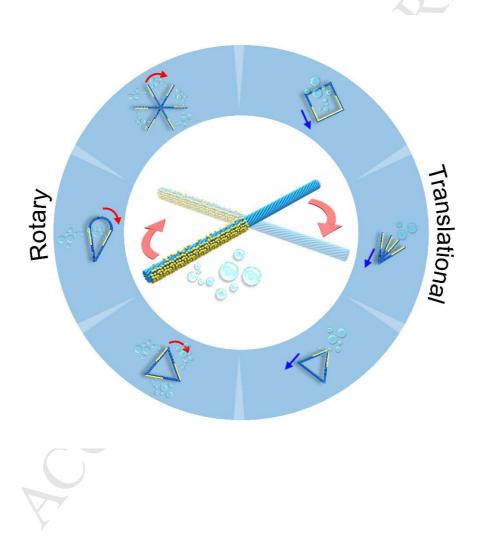
This is a PDF file of an unedited manuscript that has been accepted for publication. As a service to our customers we are providing this early version of the manuscript. The manuscript will undergo copyediting, typesetting, and review of the resulting proof before it is published in its final form. Please note that during the production process errors may be discovered which could affect the content, and all legal disclaimers that apply to the journal pertain.



ACCEPTED MANUSCRIPT

The Table of Content

A new family of bio-inspired programmable actuating systems have been made from carbon nanotube/platinum swimming fiber robots (SFRs). The SFRs demonstrate hetero-sectional structures that offer rapid and stable rotations in fuel solution. They can be assembled into programmable actuating systems that move in rotation and translation or switch between them. This assembling methodology may open up a new direction for microrobotics on system level.



Download English Version:

https://daneshyari.com/en/article/7847187

Download Persian Version:

https://daneshyari.com/article/7847187

<u>Daneshyari.com</u>