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Synchronization criteria for delayed Lur'e systems and randomly occurring sampled-data controller gain

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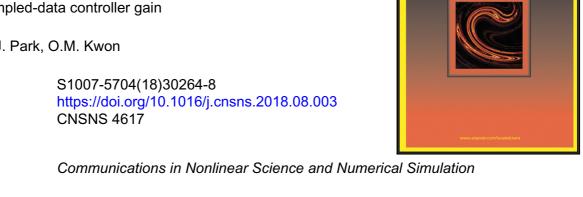
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Highlights

- A concept of stochastic parameter uncertainties is applied to a sampled-data control method to present a realistic system.
- A novel t_k -dependent double integral term of LKFs, $(t_{k+1} t) \int_{t_k}^t \int_s^t \omega_3^T(u) R\omega_3(u) du ds$, is proposed and a bound of its time derivative is estimated by utilizing Wirtinger-based double inequality and a maximum value of a function.
- Two novel LKFs, $2(t_{k+1} t) \sum_{i=1}^{l} \int_{0}^{d_{i}^{T}x(t)} \left[k_{1,i}(\psi_{i}(s) \gamma_{i}^{-}s) + k_{2,i}(\gamma_{i}^{+}s \psi_{i}(s))\right] ds$, and $2(t t_{k}) \sum_{i=1}^{l} \int_{0}^{d_{i}^{T}x(t)} \left[k_{3,i}(\psi_{i}(s) \gamma_{i}^{-}s) + k_{4,i}(\gamma_{i}^{+}s \psi_{i}(s))\right] ds$, are proposed for the first time through a condition of a nonlinear function to enhance the feasible region of synchronization criteria.
- The effectiveness and less conservatism of our results are illustrated via three numerical examples.



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