Accepted Manuscript

DEICTIC: a Compositional and Declarative Gesture Description based on Hidden Markov Models

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 PII:
 S1071-5819(18)30508-1

 DOI:
 https://doi.org/10.1016/j.ijhcs.2018.09.001

 Reference:
 YIJHC 2241

To appear in: International Journal of Human-Computer Studies

Received date:1 June 2017Revised date:4 June 2018Accepted date:1 September 2018

Please cite this article as: Alessandro Carcangiu, Lucio Davide Spano, Giorgio Fumera, Fabio Roli, DEICTIC: a Compositional and Declarative Gesture Description based on Hidden Markov Models, *International Journal of Human-Computer Studies* (2018), doi: https://doi.org/10.1016/j.ijhcs.2018.09.001

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Research Highlights

- Declarative composition of HMMs for recognizing stroke gestures.
- Support for sub-gestures identification and prediction.
- Supports the implementation of feedback and feedforward with an effert comparable to heurist approaches, together with a definition procedure and accuracy comparable to machine learning approaches.
- High accuracy in recognising composite gestures training only the primitives.

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