DEICTIC: a Compositional and Declarative Gesture Description based on Hidden Markov Models

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Research Highlights

- Declarative composition of HMMs for recognizing stroke gestures.
- Support for sub-gestures identification and prediction.
- Supports the implementation of feedback and feedforward with an effert comparable to heurist approaches, together with a definition procedure and accuracy comparable to machine learning approaches.
- High accuracy in recognising composite gestures training only the primitives.