Accepted Manuscript

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 PII:
 S0893-9659(18)30311-2

 DOI:
 https://doi.org/10.1016/j.aml.2018.08.024

 Reference:
 AML 5635

To appear in: *Applied Mathematics Letters*

Received date : 9 May 2018 Revised date : 25 August 2018 Accepted date : 25 August 2018

Please cite this article as: M. Abbaszadeh, Error estimate of second-order finite difference scheme for solving the Riesz space distributed-order diffusion equation, Appl. Math. Lett. (2018), https://doi.org/10.1016/j.aml.2018.08.024

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Error estimate of second-order finite difference scheme for solving the Riesz space distributed-order diffusion equation

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August 23, 2018

Abstract

In the current paper, an error estimate has been proposed to find a second-order finite difference scheme for solving the Riesz space distributed-order diffusion equation. The convergence order of the proposed method is $\mathcal{O}(\tau^2 + h^2)$. The numerical results show the efficiency of the new technique.

Keywords: Finite difference method, Riesz space distributed-order diffusion equation, unconditional stability, convergence.

Mathematics Subject Classication: 65L60, 65L20, 65M70.

1 Introduction

Applications of the fractional partial differential equations (PDEs) can be found in [27, 43]. The fractional equations with the distributed-order have been studied by many researchers for example Caputo [4] proposed the application of differential equations with distributed-order derivatives for generalizing stress-strain relations of unelastic media. Also, Caputo in [5, 6] discussed distributed-order time fractional differential equations and distributed-order space fractional differential equations, respectively and derived the solutions with closed form formulae of the classic problems. Authors of [10, 39] gave out diffusion-like equations with distributed-order time and space fractional derivatives for the kinetic description of anomalous diffusion and relaxation phenomena [29]. Author of [26] applied distributed-order diffusion equation to discuss ultraslow and lateral diffusion processes. Also, the applications of fractional equations with space distributed-order can be found in [1, 20, 33, 38, 40].

In the current investigation, we consider the following model [22, 29, 32]

$$\begin{cases} \frac{\partial u(x,t)}{\partial t} = \int_{1}^{2} \varpi(\alpha) \frac{\partial^{\alpha} u(x,t)}{\partial |x|^{\alpha}} d\alpha + f(x,t), & x \in \Omega, \\ u(x,0) = u_{0}(x), & x \in \Omega, \\ u(x,t) = 0, & x \in \partial\Omega, \quad 0 < t < T, \end{cases}$$
(1.1)

in which the Riesz fractional derivative is [21, 37]

$$\frac{\partial^{\alpha} u(x,t)}{\partial |x|^{\alpha}} = \frac{-1}{2\cos(\alpha\pi/2)} \left({}^{RL}_{x} \mathfrak{D}^{\alpha}_{L} u(x,t) + {}^{RL}_{x} \mathfrak{D}^{\alpha}_{R} u(x,t) \right), \qquad (1.2)$$

and also [21, 37]

$${}_{x}^{RL}\mathfrak{D}_{L}^{\alpha}u(x,t) = \frac{1}{\Gamma(2-\alpha)}\frac{d^{2}}{dx^{2}}\int_{a}^{x}(x-\xi)^{1-\alpha}u(s,t)d\xi,$$
(1.3)

$${}^{RL}_{x}\mathfrak{D}^{\alpha}_{R}u(x,t) = \frac{1}{\Gamma(2-\alpha)} \frac{d^{2}}{dx^{2}} \int_{x}^{b} (\xi-x)^{1-\alpha} u(s,t)d\xi,$$
(1.4)

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