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Multi-label learning of part detectors for occluded pedestrian detection

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Highlights

- We propose a multi-label learning approach to jointly learn part detectors which share decision trees to exploit correlations among parts and also reduce the computational cost of applying these part detectors;
- We explore several integration methods to integrate the part detectors learned by the proposed approach for occlusion handling;
- We exploit context to further improve the performance for pedestrian detection.

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