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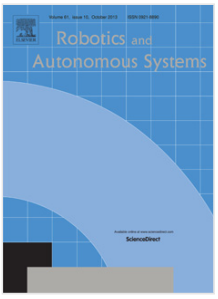

Joint localization and target tracking with a monocular camera

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Research Highlights

1. Joint localization fuses target dynamics and pursuit robot kinematics to improve trajectories estimation.
2. An adaptive histogram similarity threshold correctly suspend tracking and localization when target is occluded.
3. A fast target redetection method avoids false detections and improves accuracy.
4. Redetection successfully reinitialize visual tracking and state estimation correction.