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Multimodal integration learning of robot behavior using deep neural networks

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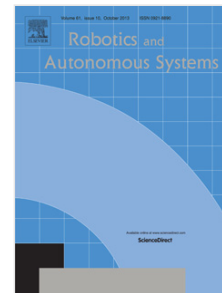
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**Highlights**

- Novel computational framework for sensory-motor integration learning.
- Cross-modal memory retrieval utilizing a deep autoencoder.
- Noise-robust behavior recognition utilizing acquired multimodal features.
- Multimodal causality acquisition and sensory-motor prediction.

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