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## Thin hybrid linearly piezoelectric junctions

### *Les jonctions minces hybrides linéairement piézoélectriques*

Patcharakorn Viriyasrisuwattana<sup>b</sup>, Christian Licht<sup>a,b</sup>, Somsak Orankitjaroen<sup>b</sup>,  
Thibaut Weller<sup>a,\*</sup>

<sup>a</sup> LMGC, UMR–CNRS 5508, Université Montpellier-2, case courrier 048, place Eugène-Bataillon, 34095 Montpellier cedex 5, France

<sup>b</sup> Department of Mathematics, Faculty of Science, Mahidol University, Bangkok 10400, Thailand

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#### ABSTRACT

We extend our previous study [1] devoted to thin linearly piezoelectric junctions to the case when the elastic, piezoelectric and dielectric coefficients of the junction are not of the same order of magnitude.

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#### R É S U M É

Nous étendons notre étude [1] consacrée aux jonctions minces linéairement piézoélectriques au cas où les coefficients élastiques, piézoélectriques et diélectriques de la jonction ne sont pas du même ordre de grandeur.

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## 1. Introduction

Due to the wide range of values taken by the elastic, piezoelectric and dielectric coefficients of various devices, it is worthwhile to extend our previous study [1] devoted to thin linearly piezoelectric junctions to the case when the elastic, piezoelectric and dielectric coefficients of the junction *are not of the same order of magnitude*. Our various asymptotic models for a thin piezoelectric junction between two linearly piezoelectric or elastic bodies will be indexed by  $p = (p_1, p_2, p_3)$  in  $\{1, 2, 3, 4\}^3$ . Indices  $p_1$  and  $p_2$  are respectively relative to the magnitude of the elastic and dielectric coefficients of the adhesive with respect to that of the constant thickness  $2\varepsilon$  of the layer containing the adhesive. More precisely, we assume that  $h := (\varepsilon, \mu) = (\varepsilon, \mu_{mm}, \mu_{ee}, \mu_{me})$  takes values in a countable set with a sole cluster point  $\bar{h} \in \{0\} \times [0, +\infty]^3$ , so that

$$\left\{ \begin{array}{l} p_1 = 1 : \bar{\mu}_{mm}^1 := \lim_{h \rightarrow \bar{h}} (2\varepsilon \mu_{mm}) \in (0, +\infty) \\ p_1 = 2 : \bar{\mu}_{mm}^1 := \lim_{h \rightarrow \bar{h}} (2\varepsilon \mu_{mm}) = 0 \\ \quad \bar{\mu}_{mm}^2 := \lim_{h \rightarrow \bar{h}} (\mu_{mm}/2\varepsilon) = +\infty \\ p_1 = 3 : \bar{\mu}_{mm}^2 := \lim_{h \rightarrow \bar{h}} (\mu_{mm}/2\varepsilon) \in (0, +\infty) \\ p_1 = 4 : \bar{\mu}_{mm}^2 := \lim_{h \rightarrow \bar{h}} (\mu_{mm}/2\varepsilon) = 0 \end{array} \right. \quad \left\{ \begin{array}{l} p_2 = 1 : \bar{\mu}_{ee}^1 := \lim_{h \rightarrow \bar{h}} (2\varepsilon \mu_{ee}) \in (0, +\infty) \\ p_2 = 2 : \bar{\mu}_{ee}^1 := \lim_{h \rightarrow \bar{h}} (2\varepsilon \mu_{ee}) = 0 \\ \quad \bar{\mu}_{ee}^2 := \lim_{h \rightarrow \bar{h}} (\mu_{ee}/2\varepsilon) = +\infty \\ p_2 = 3 : \bar{\mu}_{ee}^2 := \lim_{h \rightarrow \bar{h}} (\mu_{ee}/2\varepsilon) \in (0, +\infty) \\ p_2 = 4 : \bar{\mu}_{ee}^2 := \lim_{h \rightarrow \bar{h}} (\mu_{ee}/2\varepsilon) = 0 \end{array} \right. \quad (1)$$

\* Corresponding author.

E-mail addresses: [vdplek@hotmail.com](mailto:vdplek@hotmail.com), [Patcharakorn.vi@ssru.ac.th](mailto:Patcharakorn.vi@ssru.ac.th) (P. Viriyasrisuwattana), [licht@univ-montp2.fr](mailto:licht@univ-montp2.fr) (C. Licht), [somsak.ora@mahidol.ac.th](mailto:somsak.ora@mahidol.ac.th) (S. Orankitjaroen), [thibaut.weller@univ-montp2.fr](mailto:thibaut.weller@univ-montp2.fr) (T. Weller).

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The parameters  $\mu_{mm}, \mu_{ee}, \mu_{me}$  respectively characterize the order of magnitude of the elastic, dielectric and piezoelectric coefficients of the adhesive. The case  $p_1 = p_2$  being already treated in [1], in the following we assume  $p_1 \neq p_2$ . As in [1], index  $p_3$  characterizes the status of the adherents but also that of the interfaces between adherents and adhesive:

$$\left\{ \begin{array}{l} p_3 = 1 : \text{the two interfaces are electromechanically perfectly permeable} \\ p_3 = 2 : \text{the two interfaces are electrically permeable} \\ p_3 = 3 : \text{one interface is electrically permeable while the other one bears an electrode} \\ p_3 = 4 : \text{the two interfaces bear an electrode} \end{array} \right. \quad (2)$$

The physical situation is that of [1], which we recall as follows. Let  $\Omega$  be a domain, with Lipschitz-continuous boundary, of  $\mathbb{R}^3$ , assimilated with the physical Euclidean space with basis  $\{e_1, e_2, e_3\}$ , whose intersection  $S$  with  $\{x_3 = 0\}$  is a domain of  $\mathbb{R}^2$  of positive two-dimensional Hausdorff measure  $\mathcal{H}_2(S)$ . Let  $\Omega_{\pm} := \Omega \cap \{\pm x_3 > 0\}$  and  $\varepsilon$  be a small positive number, then adhesive and adherents occupy  $B^{\varepsilon} := S \times (-\varepsilon, \varepsilon)$ ,  $\Omega_{\pm}^{\varepsilon} := \Omega_{\pm} \pm \varepsilon e_3$ , respectively; let  $\Omega^{\varepsilon} = \Omega_{+}^{\varepsilon} \cup \Omega_{-}^{\varepsilon}$ ,  $S_{\pm}^{\varepsilon} := S \pm \varepsilon e_3$ ,  $\mathcal{O}^{\varepsilon} := \Omega^{\varepsilon} \cup B^{\varepsilon} \cup_{\pm} S_{\pm}^{\varepsilon}$ . Let  $(\Gamma_{mD}, \Gamma_{eD})$ ,  $(\Gamma_{eD}, \Gamma_{eN})$  be two partitions of  $\partial\Omega$  with  $\mathcal{H}_2(\Gamma_{mD}), \mathcal{H}_2(\Gamma_{eD}) > 0$  and  $0 < \delta := \text{dist}(\Gamma_{eD}, S)$ . For all  $\Gamma$  in  $\{\Gamma_{mD}, \Gamma_{mN}, \Gamma_{eD}, \Gamma_{eN}\}$ ,  $\Gamma_{\pm}, \Gamma_{\pm}^{\varepsilon}, \Gamma^{\varepsilon}$  denotes  $\Gamma \cap \{\pm x_3 > 0\}$ ,  $\Gamma_{\pm} \pm \varepsilon e_3, \cup_{\pm} \Gamma_{\pm}^{\varepsilon}$ , respectively; if  $(\gamma_D, \gamma_N)$  is a partition of  $\gamma := \partial S$ , we denote  $\{\gamma_D, \gamma_N, \gamma\} \times (-\varepsilon, \varepsilon)$  by  $\{\Gamma_{DI}^{\varepsilon}, \Gamma_{NI}^{\varepsilon}, \Gamma_{lat}^{\varepsilon}\}$ . The structure made of the adhesive and the two adherents, perfectly stuck together along  $S_{\pm}^{\varepsilon}$ , is clamped on  $\Gamma_{mD}^{\varepsilon}$  and subjected to body forces of density  $f^{\varepsilon}$  and to surface forces of density  $F^{\varepsilon}$  on  $\Gamma_{mD}^{\varepsilon}$  that vanishes on  $\Gamma_{lat}^{\varepsilon}$ . Moreover, a given electric potential  $\varphi_{p_0}^h$  is applied on  $\Gamma_{DI}^{\varepsilon}$  (and also on  $\Gamma_{eD}^{\varepsilon}$  when  $p_3 = 1$ ), while electric charges of density  $d^{\varepsilon}$  appear on  $\Gamma_{NI}^{\varepsilon}$  (and also on  $\Gamma_{eN}^{\varepsilon}$  when  $p_3 = 1$ ).

If  $\sigma_p^h, u_p^h, e(u_p^h), D_p^h, \varphi_p^h$  respectively stand for the fields of stress, displacement, strain, electric displacement and electric potential, the constitutive equations of the structure, for all  $\hat{p} := (p_1, p_2)$ , read as:

$$\left\{ \begin{array}{l} (\sigma_p^h, D_p^h) = M_1^{\mu}(e(u_p^h), \nabla \varphi_p^h) \quad \text{in } B^{\varepsilon} \quad \forall p_3 \in \{1, 2, 3, 4\} \\ \left\{ \begin{array}{l} (\sigma_p^h, D_p^h) = M_E^{\varepsilon}(e(u_p^h), \nabla \varphi_p^h) \quad \text{in } \Omega^{\varepsilon} \text{ if } p_3 = 1 \\ \sigma_p^h = a_E^{\varepsilon} e(u_p^h) \quad \text{in } \Omega^{\varepsilon} \text{ if } p_3 > 1 \end{array} \right. \end{array} \right. \quad (3)$$

where

$$(M_E^{\varepsilon}, a_E^{\varepsilon})(x) = (M_E, a_E)(x \mp \varepsilon e_3) \quad \forall x \in \Omega_{\pm}^{\varepsilon} \quad (4)$$

$$\left\{ \begin{array}{l} (M_1, M_E) \in L^{\infty}(S \times \Omega; \text{Lin}(\mathbb{K})) \text{ such that} \\ M_1^{\mu} := \begin{bmatrix} \mu_{mm} a_1 & -\mu_{me} b_1 \\ \mu_{me} b_1^T & \mu_{ee} c_1 \end{bmatrix}, \quad M_E := \begin{bmatrix} a_E & -b_E \\ b_E^T & c_E \end{bmatrix} \\ M_P := \begin{bmatrix} a_P & -b_P \\ b_P^T & c_P \end{bmatrix}; \exists \kappa > 0 \quad \kappa |k|^2 \leq M_P(x) k \cdot k \quad \forall k \in \mathbb{K} := \mathbb{S}^3 \times \mathbb{R}^3 \text{ a.e. } x \in \Omega, \quad \forall P \in \{I, E\} \end{array} \right. \quad (5)$$

and  $\text{Lin}(\mathbb{K})$  is the space of linear operators on  $\mathbb{K}$  whose inner product and norm are noted  $\cdot$  and  $|\cdot|$  as in  $\mathbb{R}^3$  (the same notations for the norm and inner product also stand for  $\mathbb{S}^N$  the space of  $N \times N$  symmetric matrices).

Lastly we have to add the following conditions on  $S_{\pm}^{\varepsilon}$ :

$$\left\{ \begin{array}{l} p_3 = 2 \quad D_p^h \cdot e_3 = 0 \quad \text{on } S_{\pm}^{\varepsilon} \\ p_3 = 3 \quad D_p^h \cdot e_3 = 0 \quad \text{on } S_{+}^{\varepsilon}, \quad \varphi_p^h = \varphi_{p_0}^h \quad \text{on } S_{-}^{\varepsilon} \\ p_3 = 4 \quad \varphi_p^h = \varphi_{p_0}^h \quad \text{on } S_{\pm}^{\varepsilon} \end{array} \right. \quad (6)$$

the electric potential  $\varphi_{p_0}^h$  being given on  $S_{+}^{\varepsilon}$  or  $S_{\pm}^{\varepsilon}$ .

It will be convenient to use the following notations:

$$\left\{ \begin{array}{l} \hat{k} := (\hat{e}, \hat{g}) \quad \hat{e} := e_{\alpha\beta}, \quad 1 \leq \alpha, \beta \leq 2, \quad \hat{g} := (g_1, g_2), \quad \forall k = (e, g) \in \mathbb{K} \\ k(r) = k(v, \psi) := (e(v), \nabla \psi) \quad \forall r \in H^1(\mathcal{O}; \mathbb{R}^3 \times \mathbb{R}) \\ e(v) \in \mathcal{D}'(S; \mathbb{S}^2); \quad (e(v))_{\alpha\beta} = \frac{1}{2}(\partial_{\alpha} v_{\beta} + \partial_{\beta} v_{\alpha}), \quad 1 \leq \alpha, \beta \leq 2, \quad \forall v \in \mathcal{D}'(S; \mathbb{R}^3) \end{array} \right. \quad (7)$$

and the same symbol  $e(\cdot)$  shall also stand for the symmetrized gradient in the sense of distributions of  $\mathcal{D}'(\mathcal{O}; \mathbb{R}^3)$ ,  $\mathcal{O} \in \{\mathcal{O}^{\varepsilon}, \Omega, \Omega \setminus S, B^{\varepsilon}, \Omega^{\varepsilon}\}$  or  $\mathcal{D}'(S; \mathbb{R}^2)$ . An electromechanical state with vanishing electric potential on  $\Gamma_{DI}^{\varepsilon}$  and on  $\Gamma_{eD}^{\varepsilon}$  when  $p_3 = 1$  will belong to  $V_p^{\varepsilon} := H_{\Gamma_{mD}^{\varepsilon}}^1(\mathcal{O}^{\varepsilon}; \mathbb{R}^3) \times \Phi_{p_3}^{\varepsilon}$ , with

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