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# High-frequency guided ultrasonic waves for hidden defect detection in multi-layered aircraft structures

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#### ABSTRACT

Aerospace structures often contain multi-layered metallic components where hidden defects such as fatigue cracks and localized disbonds can develop, necessitating non-destructive testing. Employing standard wedge transducers, high frequency guided ultrasonic waves that penetrate through the complete thickness were generated in a model structure consisting of two adhesively bonded aluminium plates. Interference occurs between the wave modes during propagation along the structure, resulting in a frequency dependent variation of the energy through the thickness with distance. The wave propagation along the specimen was measured experimentally using a laser interferometer. Good agreement with theoretical predictions and two-dimensional finite element simulations was found. Significant propagation distance with a strong, non-dispersive main wave pulse was achieved. The interaction of the high frequency guided ultrasonic waves with small notches in the aluminium layer facing the sealant and on the bottom surface of the multilayer structure was investigated. Standard pulse-echo measurements were conducted to verify the detection sensitivity and the influence of the stand-off distance predicted from the finite element simulations. The results demonstrated the potential of high frequency guided waves for hidden defect detection at critical and difficult to access locations in aerospace structures from a stand-off distance.

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#### 44 1. Introduction

During the service life of aerospace structures damage can occur 45 due to cyclic loading conditions [1]. Common maintenance prob-46 lems include disbonds of the sealant layers connecting multiple 47 metallic sheets and the development of fatigue cracks. Such struc-48 49 tures must therefore be regularly inspected non-destructively to 50 detect hidden damage such as fatigue cracks before they have reached a critical length. Recently an ultrasonic-based structural 51 health monitoring method has been developed for real time, 52 53 in situ monitoring of cracks at fastener holes using an angle beam through transmission technique [2]. Standard bulk wave Ultrasonic 54 Testing (UT) has a proven sensitivity for the detection of small 55 defects, e.g., shear wave angle beam measurements [3]. However, 56 57 it often necessitates local access and time-consuming scanning of the inspected part [4]. Rayleigh waves have been used for the 58 59 detection of surface fatigue cracks in metallic plates [5]. Analytical

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http://dx.doi.org/10.1016/j.ultras.2014.04.023 0041-624X/© 2014 Published by Elsevier B.V. models have been developed to describe the interaction of Rayleigh waves with surface cracks [6], as well as numerical simulations complemented by experimental results [7]. Typically damage detection using Rayleigh waves requires access to the side of the structure containing the defect.

Large areas of plate structures can be inspected and monitored from a single, remote access point using guided ultrasonic waves [8]. These are often used in a low frequency-thickness range below the cut-off frequency of the higher wave modes to simplify data interpretation [4]. However, the resulting wavelengths are typically significantly larger than in bulk wave UT, thus limiting the sensitivity for the detection of small defects [9]. The interaction of low frequency guided waves with small surface defects in plates has been studied using Finite Element (FE) simulations and experiments [10]. The propagation of guided ultrasonic waves in bonded components [11] and the interaction with holes in metallic plates has been investigated [12]. Low-frequency guided ultrasonic waves were used for the detection of fatigue cracks at fastener holes [13].

The application of guided ultrasonic wave modes in the higher frequency-thickness range has more recently been investigated

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B. Masserey et al./Ultrasonics xxx (2014) xxx-xxx

81 for non-destructive testing purposes. The S<sub>0</sub> mode (around 82 5 MHz mm) was used for corrosion detection in aircraft structures 83 [14], and longitudinal modes (above 15 MHz mm) were employed 84 for plate inspection [15]. This type of waves allows for the inspec-85 tion of structures over reasonably long distances, and can be used 86 even if local access to the inspected part is not possible [4]. The 87 employed wavelengths are comparable to those commonly used 88 in bulk wave UT, possibly allowing good sensitivity for the detec-89 tion of small defects [15]. High frequency guided waves excited using standard 90° angle beam transducers at around 90 6.75 MHz mm can be interpreted as the superposition of the first 91 92 anti-symmetric A<sub>0</sub> and symmetric S<sub>0</sub> Lamb wave modes [16]. 93 These waves can propagate along the structure and allow for the inspection of both plate surfaces due to an energy transfer 94 95 between the surfaces. A hybrid analytical/numerical model was 96 developed to describe the wave propagation and the reflection 97 at small surface defects in single layer metallic plates [17]. From 98 standard pulse-echo measurements the location and damaged 99 plate side of small surface defects in aluminium plates could be determined using a combination of time-of-flight and frequency 100 101 evaluation of the reflected pulse, [18]. Fatigue crack growth at a 102 fastener hole in tensile, aluminium specimens was detected and monitored in situ using non-contact measurement of high fre-103 104 quency guided ultrasonic waves [19]. The detection of defects in 105 the different layers of multi-layered aircraft structures is one of 106 the requirements for future Structural Health Monitoring (SHM) 107 systems [20]. A UT technique for 2nd layer defect detection has 108 been developed using an angled phase-array probe and auto-109 mated analysis of the acquired ultrasonic signals [21]. However, 2nd layer defect detection using conventional UT techniques 110 can be problematic if the coupling medium (sealant) between 111 the layers around the fastener hole is inadequate or missing 112 [21]. Guided ultrasonic waves have energy distributed through 113 the thickness of the multi-layered structure, making it in princi-114 115 ple possible to inspect the different layers. Low frequency guided 116 ultrasonic waves were employed to monitor fatigue crack growth 117 at a fastener hole in a multi-layered structure [22]. The potential 118 for the detection of real defects in an inaccessible laver was dem-119 onstrated, but a limited sensitivity for the detection of fatigue 120 crack growth initiation was noted. The possibility of fatigue crack 121 detection at fastener holes in multi-layered structures using high 122 frequency guided ultrasonic waves (5 MHz) has been investigated [23]. It was shown that defect detection is possible, but that 123 124 detection sensitivity depends on the interface conditions between the layers. It was also noted that high frequency guided ultrasonic 125 126 waves are attenuated, if a material, such as an adhesive, is pres-127 ent between the metallic layers, making the monitoring of large 128 areas more difficult.

129 In this contribution the potential of high frequency guided 130 ultrasonic waves for the detection of hidden defects in multi-lay-131 ered aerospace structures has been investigated. These waves can 132 propagate over medium distances and are in principle sensitive for defect detection through the complete specimen thickness. 133 The wave propagation characteristics of high frequency guided 134 135 wave modes excited using a standard 90° angle beam wedge in a multi-layered model structure have been studied. The structure 136 consists of two adhesively bonded aluminium plates with an epoxy 137 based sealant layer [24]. Interference occurs between the wave 138 modes during propagation along the structure, resulting in a fre-139 140 quency dependent variation of the energy through the thickness 141 with distance. Finite Element (FE) simulations have been carried 142 out and compared to laboratory measurements using a laser inter-143 ferometer. The sensitivity for the detection of an internal notch at 144 the sealant layer and on the bottom surface of the multilayer struc-145 ture from a stand-off distance using pulse-echo (P/E) measure-146 ments has been demonstrated.

### 2. Experimental details 147

#### 2.1. Specimen preparation

The multilayer structure model investigated in this contribution 149 was made of two 3 mm thick aluminium plates with a width of 150 70 mm and a length of 600 mm connected with an approximately 151 0.25 mm thick epoxy based sealant layer, see Fig. 1. The plate 152 material is an aluminium alloy 2014 T6 widely used for aerospace 153 applications, having a Young's modulus of 73.1 GPa, Poisson's ratio 154 of 0.33, and density of 2800 kg/m<sup>3</sup>. The sealant is a two-part struc-155 tural paste adhesive Hysol EA 9394 with a Young's modulus of 156 4.237 GPa (data from supplier), density of 1360 kg/m<sup>3</sup>, and Pois-157 son's ratio of 0.45. Measurements of the Young's modulus have 158 been performed on a moulded  $120 \text{ mm} \times 15 \text{ mm} \times 3 \text{ mm}$  epoxy 159 specimen in a standard tensile machine to confirm the material 160 properties specified by the supplier. The relative error between 161 the measured and the supplier value was below 1%. The thickness 162 of the sealant layer was controlled by mixing approximately 4% 163 volume fraction of spacer beads with a maximum diameter of 164 0.249 mm into the epoxy paste and clamping the specimen during 165 curing at room temperature. To control the accuracy and the repro-166 ducibility of the sealant layer, the thicknesses of the different lay-167 ers were measured along the centreline of the specimens in 1 mm 168 step size using a coordinate measuring machine. The sealant thick-169 ness was obtained by subtraction of the aluminium thicknesses 170 (measured before application of the epoxy paste) from the total 171 multilayer thickness (measured after curing). The resultant thick-172 ness on the centreline was measured as varying between 173 0.22 mm and 0.28 mm, with an average sealant thickness of 174 approximately 0.25 mm. Multiple specimens without defects were 175 manufactured in order to investigate the high frequency guided 176 ultrasonic wave generation and propagation in multilayer struc-177 tures. More specimens were manufactured with an artificial defect. 178 The notch was placed either in one of the aluminium plates at the 179 interface between aluminium and sealant, as illustrated schemati-180 cally in Fig. 1(b), or on the bottom surface of the multilayer struc-181 ture. The notch was cut across the width of the specimen to a depth 182 of 0.3 mm using an Electro-Discharge Machining (EDM) device. 183 Restrictions of the EDM device imposed a notch width of approxi-184 mately 0.4 mm and a maximum specimen length of 550 mm. The 185 notch was placed at 150 mm from one end of the specimen. A wire 186 covered with Teflon tape was placed into the notch to avoid sealant 187 ingress during sealant application. The tape was removed after cur-188 ing of the epoxy paste. 189

#### 2.2. Measurement setup

The high frequency ultrasonic guided wave was generated on the surface of the multilayer specimen using a standard 1 MHz half inch transducer mounted on a 90° angle beam wedge for steel. The spatial period of the generated ultrasonic field at the interface wedge-aluminium can be evaluated on the basis of the Rayleigh wavelength: performing the calculation for the transducer centre frequency leads to a wavelength  $\lambda_R$  of 3.0 mm, about half the thickness of the multilayer specimen. The wedge was clamped on the specimen so that the main propagation axis is the centre line of the multilayer specimen, as displayed in Fig. 1(a).

For the investigation of the wave propagation characteristics a five cycle tone burst at 1 MHz centre frequency (sinusoid in a Hanning window) was generated in an arbitrary waveform generator and amplified using a broadband power amplifier. The out-of-plane component of the surface velocity was measured along the centre line of the specimen (step size: 1 mm) using a heterodyne laser interferometer mounted on a scanning rig. The origin (x = 0)

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