



Gene–culture shock waves

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ABSTRACT

A hyperbolic model is presented which generalises Aoki's parabolic system for the combined propagation of a mutant gene together with a cultural innovation. It is shown that this model allows for the propagation of a shock wave and the shock amplitude is calculated numerically. Particular attention is paid to the case where the shock moves into a region where the frequencies of the mutant gene and of the individuals adopting the innovation are zero.

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1. Introduction

In an inspiring piece of work Jordan [20] developed a complete analysis for the evolutionary behaviour of a shock wave for a hyperbolic version of the Fisher equation

$$\frac{\partial \rho}{\partial t} - v \frac{\partial^2 \rho}{\partial x^2} = \gamma \rho \left(1 - \frac{\rho}{\rho_s} \right) \quad (1)$$

where $\rho(x, t)$ is a density with v , γ and ρ_s positive constants. This equation was proposed by Fisher [13] as a model for the spread of an advantageous gene, and was simultaneously discovered and analysed by Kolmogoroff et al. [22]. In fact Jordan [20] and Jordan and Puri [21] refer to Eq. (1) as the Fisher–KPP equation. As Jordan [20] points out Eq. (1) has been studied in various contexts in the biological, physical and social sciences.

Jordan [20], in fact, uses Green and Naghdi [15] thermodynamics (cf. also Jaisaardsuetrong and Straughan [18]) to argue that in many situations Eq. (1) ought to be replaced by a pair of equations which convert it to a hyperbolic system, namely

$$\begin{aligned} \frac{\partial \rho}{\partial t} &= -\frac{\partial q}{\partial x} + \gamma \rho \left(1 - \frac{\rho}{\rho_s} \right), \\ \frac{\partial q}{\partial t} &= -V^2 \frac{\partial \rho}{\partial x}, \end{aligned} \quad (2)$$

where V is a constant which turns out to be the shock speed and q is a flux. It has been noted recently that many diffusion problems ought really to be represented by hyperbolic systems, in the spirit of (2). For example, Herrera and Falcón [16] argue this for a type of

thermosolutal convection in a stellar zone, Jordan [19] eloquently argues for this in traffic flow, Mendez and Camacho [23] show that it is useful in population dynamics, and several other applications are described in detail in Christov and Jordan [9], Christov and Jordan [10–12], and in chapter 9 of the monograph by Straughan [29], including nanoscale heat transport, fish migration, propagation of the hantavirus, chemotaxis, skin burns, and radio frequency heating in a medical context. A key to this development is the realisation that in many real life processes the relaxation time involved is not necessarily small and disturbances propagate with a finite speed. Relatively large relaxation times have been observed in biological tissues by Mitra et al. [24], and by Saidane et al. [27]. It is worth mentioning that while Jordan [20] uses Green and Naghdi [15] thermodynamics to derive a hyperbolic version of Eq. (1) one could employ a derivation along the lines of Cattaneo [7]. The work of Cattaneo [7] is described in detail in Section 1.2 in Straughan [29], where he also notes that a Cattaneo-like derivation was developed earlier by Graffi [14], although for a dielectric rather than in the context of heat transport. The key aspect of the work of Jordan [20], is that he is able to obtain analytically a solution for the amplitude of a shock solution to (2), and, therefore, completely understand the shock behaviour. Such a solution is not possible in typical mechanics contexts such as in gas dynamics, or elasticity, cf. Whitham [30], unless one is analysing some linearised form and is investigating a weak shock.

While Eq. (1) is proposed for the evolution of an advantageous gene, the recent anthropological literature usually links the theory for the evolution of a gene to that of the evolution of a cultural trait. Riede and Bentley [26] note that, ... “the wave of advance model was originally developed by Fisher [13] to represent the spread of advantageous genes ... it provides mathematically detailed predictions about demographic spread over time, with equations that unambiguously characterise the hypothesised migratory activity”. O'Brien and Bentley [25] write, ... “theoretical modelling of cultural transmission is based on the premise that genes and culture provide separate, though linked, systems of inheritance, variation, and evolutionary

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change". The fact that genes and culture are intimately linked is further emphasised by Bentley and O'Brien [2] who write, ... "it is becoming increasingly clear that the interactions of genes and culture – literally, their coevolution – offer a faster and stronger mode of human evolution than either does by itself". They also write that, ... "gene-culture theory is a branch of theoretical population genetics that incorporates cultural traits into models of differential transmission of genes from one generation to the next", and they further write, ... "the two inheritance systems cannot always be treated independently". Further evidence for linking cultural and gene evolution is provided by Bentley et al. [5], Bentley and Ormerod [4], Bentley and O'Brien [3], Bentley et al. [6], and the many references therein. In fact, Aoki [1] developed a partial differential equation model for the propagation of a mutant gene and a cultural innovation. He derives what he calls a logistic attraction–repulsion model, in terms of $y(x, t)$, the frequency of the mutant gene, and $p(x, t)$, the frequency of the individuals adopting the innovation (frequency in this case refers to the number of genes or individuals, normalised in an appropriate way). Aoki's [1] system of equations is

$$\begin{aligned}\frac{\partial y}{\partial t} &= \frac{\partial^2 y}{\partial x^2} + y(1-y)\{(\gamma + 2\sigma)p + \delta\}, \\ \frac{\partial p}{\partial t} &= \frac{\partial^2 p}{\partial x^2} + p(1-p)(\sigma y + \rho),\end{aligned}\quad (3)$$

where γ, σ, δ and ρ are constants, and $x \in \mathbb{R}$. It should be noted that Eqs. (3) are non-dimensionalised so the diffusion coefficient is 1 and y and p lie in $[0, 1]$.

Our goal is to propose and analyse a hyperbolic generalisation of system (3) and derive a coupled nonlinear system of ordinary differential equations for the shock amplitudes appropriate to y and p . We then solve this system numerically and are able to fully analyse the shock behaviour. We believe this is the first time a complete analysis has been performed for such a system.

2. The model and shock waves

In this work we adopt a hyperbolic form of the Aoki model (3) by using a Cattaneo [7] type of argument to replace Eqs. (3) by

$$\begin{aligned}\frac{\partial y}{\partial t} &= -\frac{\partial J}{\partial x} + y(1-y)\{(\gamma + 2\sigma)p + \delta\}, \\ \tau \frac{\partial J}{\partial t} + J &= -\frac{\partial y}{\partial x}, \\ \frac{\partial p}{\partial t} &= -\frac{\partial K}{\partial x} + p(1-p)(\sigma y + \rho), \\ \tau \frac{\partial K}{\partial t} + K &= -\frac{\partial p}{\partial x},\end{aligned}\quad (4)$$

where $\tau > 0$ is a relaxation time, and J and K are fluxes for y and p , respectively. Let us observe that Eqs. (4) reduce to the standard problem of Aoki [1] when $\tau = 0$. We restrict attention to the situation when J and K in (4) have the same relaxation time. This gives rise to a shock where the mutant gene and the individuals may propagate simultaneously.

Let S be a singular surface for Eqs. (4), it is actually a singular point when x is in one dimension, or it may be thought of as a plane wave in three space dimensions, moving along the x -axis. Suppose $y(x, t)$ and $p(x, t)$ are C^2 everywhere except across S where they may suffer a finite discontinuity. Define $y^{+, -}$ and $p^{+, -}$, by

$$\begin{aligned}y^- &= \lim_{x \rightarrow S^-} y(x, t), & y^+ &= \lim_{x \rightarrow S^+} y(x, t), \\ p^- &= \lim_{x \rightarrow S^-} p(x, t), & p^+ &= \lim_{x \rightarrow S^+} p(x, t),\end{aligned}$$

where the limits at S^+ and S^- denote limits from the right and the left, respectively. We define the shock amplitudes Y and P by

$$Y(t) = [y] = y^+ - y^-, \quad P(t) = [p] = p^+ - p^-, \quad (5)$$

where the notation for the jump $[\cdot]$ in a function is introduced. From Eqs. (4) one may derive the Rankine–Hugoniot equations

$$\begin{aligned}V[y] &= [J], & V\tau[J] &= [y]; \\ V[p] &= [K], & V\tau[K] &= [p],\end{aligned}\quad (6)$$

cf. Whitham [30], Iesan and Scalia [17]. Thus, from Eqs. (6) one shows that the shock speed V is constant and given by

$$V^2 = \frac{1}{\tau}. \quad (7)$$

(We stress that the diffusion coefficient is really involved in V . Eq. (7) arises because of Aoki's [1] non-dimensionalisation which transforms time and space. Aoki's [1] Eqs. (3) are derived from a discrete system. In his derivation the diffusion coefficient which arises is $k = \tilde{m}(\Delta x)^2/2\Delta t$ where $\tilde{m}/2$ is the probability of emigration to the left and to the right colony in a discrete model of the individuals where Δx is the distance between neighbouring colonies and Δt is the time taken for migration. The non-dimensionalisation used to remove k is involved and analyses three cases depending on the various parameters which arise. Due to this non-dimensionalisation we believe adopting the same value of τ in (4) is acceptable.)

Singular surface theory is covered in depth in Chen [8], and conveniently in chapter 4 of Straughan [29]. From this theory the Hadamard relation shows that

$$\frac{\delta Y}{\delta t} = [y_t] + V[y_x], \quad (8)$$

where y_t and y_x denote partial derivatives, where $\delta/\delta t$ is the derivative at the wavefront, and where V is the shock speed. We also require the relation for the jump of a product, namely,

$$[ab] = a^+[b] + b^+[a] - [a][b]. \quad (9)$$

We commence by taking the jump of Eqs. (4)_{1,2} to find using (8),

$$\frac{\delta}{\delta t}[y] - V[y_x] = -[J_x] + (\gamma + 2\sigma)[py(1-y)] + \delta[y(1-y)], \quad (10)$$

and

$$\tau \frac{\delta}{\delta t}[J] - \tau V[J_x] + [J] = -[y_x]. \quad (11)$$

Now form (10) + V (11) and make repeated use of (9). One then repeats the same procedure for (4)_{3,4}. After some calculation one may arrive at the following system of equations for Y and P ,

$$\begin{aligned}\frac{\delta Y}{\delta t} &= Y \frac{1}{2} \left\{ -\frac{1}{\tau} + (\gamma + 2\sigma)p^+(1 - 2y^+) + \delta(1 - 2y^+) \right\} \\ &\quad + P \frac{y^+}{2} (\gamma + 2\sigma)(1 - y^+) - PY(\gamma + 2\sigma) \left(\frac{1 - 2y^+}{2} \right) \\ &\quad + Y^2 \left\{ \frac{p^+(\gamma + 2\sigma) + \delta}{2} \right\} - PY^2 \left(\frac{\gamma + 2\sigma}{2} \right), \\ \frac{\delta P}{\delta t} &= P \frac{1}{2} \left\{ -\frac{1}{\tau} + \sigma y^+(1 - 2p^+) + \rho(1 - 2p^+) \right\} \\ &\quad + Y \frac{\sigma p^+(1 - p^+)}{2} - YP \frac{\sigma}{2} (1 - 2p^+) \\ &\quad + P^2 \left(\frac{\sigma y^+ + \rho}{2} \right) - \frac{\sigma}{2} YP^2.\end{aligned}\quad (12)$$

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