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Sustainable planning of hybrid microgrid towards minimizing environmental pollution, operational cost and frequency fluctuations

Vahid Sohrabi Tabar, Mehdi Ahmadi Jirdehi*, Reza Hemmati

Department of Electrical Engineering, Kermanshah University of Technology, Kermanshah, Iran

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ABSTRACT

Microgrids mainly use conventional and renewable energy resources at the same time. Conventional energy resources produce environmental pollution and need high cost for operation. In recent years, penetration of renewable resources such as photovoltaic and wind turbine has been rapidly grown in microgrids. Reduction of power losses and pollution are the main advantages of integrating renewable resources into networks. But, the renewable energy resources comprise low inertia and stability of the network integrated with such units is low. As a result, the environmental pollution and stability of microgrid are considered as the main problems and a new modeling of microgrid energy management is proposed by this paper to tackle such drawbacks. In this regard, environmental pollution is reduced by including hydrogen gas station and carbon capture-storage system. As well, the virtual synchronous generator is used to provide sufficient inertia and improving transient stability. The uncertain parameters are incorporated in the planning and stochastic programming is applied to tackle such uncertainties. Problem is mathematically expressed as a stochastic mixed integer linear programming and solved by the augmented Epsilon-constraint method. Finally, a comprehensive sensitivity analysis is carried out to evaluate the results. Based on the simulation results, by installing carbon capture-storage system, operational cost of microgrid is reduced from 64.998 \$ to 56.043 \$ and 1791.75 kg of carbon dioxide is stored. The revenue equal to 24 \$ in one day is achieved by H₂ station without any pollution. The stability of microgrid is also significantly improved by installing virtual synchronous generator. The results demonstrate the viability and effectiveness of the proposed method to minimize environmental pollution, operation cost and frequency fluctuations in microgrid energy management.

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1. Introduction

Microgrids usually include distributed generations (DGs) and local loads that can be isolated or connected to the main grid. The environmental pollution, global warming, and limits of fossil fuel resources are the main reasons for utilizing renewable resources. These resources can be suitably integrated into small networks such as microgrids. In real microgrids, because of limitations on the renewable energy resources such as stochastic generation, it is not possible to supply the demand only by renewable energy resources and the operator has to apply conventional energy resources in addition to the renewable ones. Application of renewable and conventional energy resources causes several problems in microgrids. Conventional energy resources produce environmental

pollution and the network operator is often willing to reduce the conventional energy resources and increase the renewable energy units. On the other hand, high penetration level of renewable resources reduces the inertia of the microgrid and leads to stability problems such as fast frequency deviations and stability collapse. Since the inertia of renewable energy resources is less than the inertia of conventional generators. Thus, if all energy resources are chosen as renewable, the microgrid inertia will be significantly reduced and it is not possible to control the frequency of the microgrid. Therefore, low inertia problem and environmental pollution are occurred by renewable and conventional generators, respectively. As a result, it is required to tackle these two problems (i.e., environmental pollution related to the conventional units and stability problem associated with renewable units) in microgrid scheduling and planning.

Different aspects of microgrids have been investigated by researchers so far. Control and energy management are two important aspects of microgrid studies. Frequency and voltage control

* Corresponding author. Tel.: +98 83 38305000; fax: +98 83 38305006.

E-mail address: m.ahmadi@kut.ac.ir (M.A. Jirdehi).

Nomenclature*Symbols, indexes and parameters*

A	Wind generator blade area (m^2)	$P_{PV, STC}$	Maximum test power for the STC (kW)
C_{M-CHB} , C_{OP-CHP}	CHP maintenance cost (\$) and operation cost (\$/kWh)	P_G and P_L	Total produced and demanded powers (kW)
C_{OP-WT} , $C_{CONS-WT}$	WT operation cost (\$/kWh) and constant cost (\$)	$P_{WT}(t)$	WT power (kW)
C_{OP-PV} , $C_{CONS-PV}$	PV operation cost (\$/kWh) and constant cost (\$)	$P_{VSG}(t)$	VSG output (kW)
C_{M-MT} , C_{OP-MT}	MT maintenance cost (\$) and operation cost (\$/kWh)	$P_{VSG}^d(t)$, $P_{VSG}^d(t)$	Inertia response and damping power (kW)
C_{M-ES} , C_{OP-ES}	ES maintenance cost (\$) and operation cost (\$/kWh)	$P_{PV}(t)$	PV power (kW)
C_{Buy} , C_{Sell}	Constant price of buying and selling energy (\$/kWh)	$P_{CHP}(t)$	CHP power (kW)
C_{M-H2} , C_{M-G}	H ₂ and gasoline stations maintenance costs (\$)	$P_{MT}(t)$	MT power (kW)
C_{M-VSG}	VSG maintenance cost (\$/kWh)	$P_{Buy}(t)$, $P_{Sell}(t)$	Buy and sell powers (kW)
CP_{H2} , CS_{H2}	Cost of producing (\$/kWh) and selling H ₂ (\$/Lit)	$P_{ES}(t)$	ES power (kW)
CS_G , CP_G	Cost of selling and producing gasoline (\$/Lit)	$P_{Gi}(t)$	Produced power by <i>i</i> th generator (kW)
C_{Fuel}	Cost of fuel (\$/kWh)	$R_m(t)$	Reserve margin of the microgrid
$C_{Buy}(t)$, $C_{Sell}(t)$	Cost of buying and selling energy (\$)	$R_m^{max}(t)$, $R_m^{min}(t)$	Maximum and minimum reserve margin (%)
$C_G(t)$	Cost of gasoline station (\$)	$R_{H2}(t)$	Revenue by selling H ₂ (\$)
$C_{CCS}(t)$	Cost of CCS system (\$)	$R_G(t)$	Revenue by selling gasoline (\$)
$C_{H2}(t)$	Cost of H ₂ station (\$)	$R_{CCS}(t)$	Revenue of CCS system (\$)
$C_{CHP}(t)$	Total cost of CHP (\$)	R_p , ST_p	Revenue and store prices by CCS system (\$/kg)
$C_{PV}(t)$	Total cost of PV (\$)	r_i	Range of <i>i</i> th objective function
$C_{MT}(t)$	Total cost of MT (\$)	s_i	Feasible region of <i>i</i> th objective function
$C_{Wind}(t)$	Total cost of WT (\$)	T_{amp} , T_{jstc}	Environmental and reference temperature of PV ($^{\circ}C$)
$C_{ES}(t)$	Total cost of ES (\$)	T	Last time interval
$C_{VSG}(t)$	Cost of VSG (\$)	t	Time (h)
<i>df and dt</i>	Frequency (Hz) and time (s) variations	$T_j(t)$	Cell temperature of PV ($^{\circ}C$)
EF_i	Emission factor for <i>i</i> th generator (kg/kWh)	$V(t)$	Wind speed (m/s)
EF_{CHP}	Emission factor of CHP (kg/kWh)	$VOL_{H2}(t)$, $VOL_G(t)$	Volume of H ₂ and gasoline (Lit)
EF_{MT}	Emission factor of MT (kg/kWh)	v^{nom}	Nominal wind speed (m/s)
EF_{VSG}	Emission factor of VSG (kg/kWh)	v^{cut-in} , $v^{cut-out}$	Minimum and Maximum wind speed (m/s)
EF_{MG}	Emission factor of main grid (kg/kWh)	x	Vector of decision variables
EF_G	Emission factor of gasoline (kg/Lit)	ρ and θ	Air density (kg/m^3) and Time interval
E_S^{max} , E_S^{min}	Maximum and minimum energy of ES (kWh)	η_{CHP}	CHP generator electrical efficiency
$E_{LD}(t)$	Electrical load demand (kW)	η_{MT}	MT generator electrical efficiency
$E_S(t)$, $E_S(0)$	ES energy and Initial state of charge (kWh)	η_G^E , η_D^E	ES charge and discharge efficiency coefficients
$EM_G(t)$	Emission of gasoline station (kg)	η^w	Wind generator power coefficient
$EM_{CHP}(t)$	Emission of CHP (kg)	Abbreviations	
$EM_{MT}(t)$	Emission of MT (kg)	ANN	Artificial neural network
$EM_{VSG}(t)$	Emission of VSG (kg)	BFA	Bellman ford algorithm
$EM_{MG}(t)$	Emission of microgrid (kg)	CCS	Carbon capture and storage
$E_{H2}(t)$	Energy for producing H ₂ (kWh/Lit)	CHP	Combined heat and power
e_i	Constrained objective functions	CA	Clustering algorithm
f , f°	Microgrid frequency and references frequency	CO ₂	Carbon dioxide
$fp(x)$	Objective functions	DG	Distributed generation
GT_{STC} , GT_{NOCT}	Solar radiation for STC and NOCT (kW/m^2)	DVR	Dynamic voltage restorer
$GT(t)$	Solar radiation on tilted module plane (kW/m^2)	ESS	Energy storage system
H	Inertia ($kg.m^2$)	HHA	Hyper heuristic algorithm
k_{vi} , k_r	Virtual inertia ($kg.m^2$) and constant coefficient	MBFO	Modified bacterial foraging algorithm
k_{vd} , k_k	Damping and constant coefficient	MPABC	Multi period artificial bee colony
NOCT	Normal operating cell temperature ($^{\circ}C$)	MPGSA	Multi period gravitational search algorithm
N_{PVs} , N_{PVp}	Number of series and parallel cells in PV module	MILP	Mixed integer linear programming
P_{E-dech}^{max} , P_{E-ch}^{max}	ES maximum discharge and charge rate (kW)	MINLP	Mixed integer non-linear programming
P_{MT}^{max} , P_{CHP}^{max}	Maximum powers of MT and CHP (kW)	MIQP	Mixed integer quadratic programming
P_{Line}	Line transfer power limit (kW)	MT	Micro turbine
		MPP	Maximum power point
		PSO	Particle swarm optimization
		PV	Photovoltaic
		PDF	Probability distribution function
		SQP	Sequential quadratic programming
		VSG	Virtual synchronous generator
		WT	Wind turbine

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