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A thermodynamic model based on exergy flow for analysis and optimization of pulse tube refrigerators

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Abstract

A thermodynamic model based on exergy flow through pulse tube refrigerators (PTRs) is developed. An exergetic efficiency parameter representing the losses in the pulse tube itself is proposed. The effects of control parameters representing a general phase shifter and their effect on the system performance are discussed. Analytical solutions representing important parameters in the design of PTRs such as the load curve, cooling power and efficiency in terms of basic system input parameters are developed. It is shown that the analytical model is powerful and convenient for optimization of PTRs and in quantifying its operational bound and important losses. Results indicating a compromise between cooling power and efficiency in PTRs under certain conditions are presented and discussed. © 2006 Elsevier Ltd. All rights reserved.

Keywords: Pulse tube; Cryocoolers; Thermodynamics; Cycle optimization; Exergy analysis

1. Introduction

Pulse tube refrigerators (PTRs) play an important role in satisfying the need for cryogenic cooling of space-based infrared detectors as well as electronics requiring coolers with high reliability, low vibration, and high efficiency. The conventional orifice pulse tube refrigerators (OPTRs) rely on a simple phase-shifting mechanism at the orifice where the mass flow rate and pressure are in phase. The thermodynamics of OPTRs has been under study by several investigators [1–5], to just name a few. Exergy analysis is a powerful method for the design of PTRs and for quantifying the losses in the refrigerators [6-8]. Exergy flow and analysis in PTRs for each component shows how the input exergy provided by the power input to the compressor is destroyed as the working fluid goes through its cyclic motion in the system. Recently implementation of more effective phase-shifting mechanisms has resulted in the

* Corresponding author. Tel.: +1 505 277 1325. E-mail address: Razani@unm.edu (A. Razani). developments of high efficiency PTRs approaching the efficiency of Stirling refrigerators [9]. In this paper we concentrate on PTRs and use the exergy method for thermodynamic analysis and optimization of the refrigerators assuming that a controlled phase-shifting mechanism exists. In this manner, we find thermodynamic bounds for cooling capacity and efficiency of the refrigerator. In addition, cooling capacity and efficiency are obtained in terms of important dimensionless numbers convenient for quantifying the important losses and performance evaluation of PTRs at the system level.

Exergy, like energy and entropy, is a property of the state of a system and measures the departure of the state of the system from the state of the environment. In application to PTRs, for each component, considering one channel heat transfer between the system and a thermal reservoir at the temperature $T_{\rm R}$ and one channel of inlet and exit mass transfer, the exergy balance can be written as [6,7]

$$\langle \dot{E}_{\rm D} \rangle = \langle \dot{M}e \rangle_{\rm i} - \langle \dot{M}e \rangle_{\rm e} - \langle \dot{W} \rangle + \left\langle \left(1 - \frac{T_{\rm o}}{T_{\rm R}}\right) \dot{Q} \right\rangle \tag{1}$$

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Nomenclature

$\langle \rangle$	indicates integration over a cycle	ψ_1	dimensionless number, $\dot{m}_2/\overline{C}p_1$
A	area of regenerator	ψ_2	dimensionless number, $\overline{V}\omega/\overline{C}$
В	dimensionless variable, see Eq. (27)	ϕ	phase angle for mass flow rate
\overline{C}	flow conductance	λ	regenerator ineffectiveness
C_p	heat capacity at constant pressure	3	pulse tube irreversibility parameter
$\dot{E}_{\rm D}$	rate of exergy destruction	ω	angular frequency
е	specific exergy	γ	specific heat ratio
f	frequency		
h	specific enthalpy	Subscripts	
H	enthalpy flow rate	а	average
Κ	effective thermal conductivity of regenerator	с	cold
L	length of regenerator	co	no load
'n	amplitude of mass flow rate	cond	conduction
\dot{M}	mass flow rate	cn	cold side normalized
Mr	mass flow rate amplitude ratio across regenera-	e	exit
	tor	ex	exergetic
Р	pressure	i	inlet
р	pressure amplitude	j	general inlet or exit of components
Pr	pressure amplitude ratio across regenerator	n	normalized
Ż	rate of heat transfer	0	environment
S	specific entropy	opt1	optimum for cooling capacity
sl	slope of load curve	opt2	optimum for efficiency
Т	temperature	р	pressure
V	volume of pulse tube	PT	pulse tube component
\overline{V}	average effective void volume of regenerator	R	reservoir
Ŵ	input power	th	thermal
X	cosine of phase angles	1	hot side of regenerator, see Fig. 1
Y	sine of phase angles	2	cold side of regenerator, second law, see Fig. 1
		3	hot side of pulse tube, see Fig. 1
Greeks		0, 1, 2, 3	3,4 used with sine and cosine of phase angles, see
θ	phase angle for pressure		Appendix A
η	efficiency		

where *e* is the specific exergy carried with mass, $\dot{E}_{\rm D}$ is the rate of exergy destruction in the component, and \dot{Q} is the rate of heat transfer. For a single-component working fluid, such as helium, in the absence of chemical, kinetic, or potential exergy, the specific exergy can simply be written as

$$e = h - h_{\rm o} - T_{\rm o}(s - s_{\rm o}) \tag{2}$$

where h is the specific enthalpy and s is the specific entropy and subscript "o" denotes the environment. Substituting Eq. (2) into Eq. (1) and using the vanishing average mass flow rate over a cycle yields

Assuming the ideal gas law is valid and thermophysical properties are constant, the enthalpy and entropy in the above equation can be written, respectively as

$$h = C_p(T - T_o)$$

$$s = C_p \ln(T/T_o) - R \ln(P/P_o)$$
(4)
(5)

2. Exergy based thermodynamic analysis

Fig. 1 shows important components of a PTR used for analysis in this study. Exergy comes into the system at the driver side and is destroyed as it moves into the system. The product exergy is delivered to the cold reservoir at T_c . We assume for purposes of analysis that the pressure and mass flow rate at any location at the inlet and exit of each component are given by

$$\dot{M}_{i} = \dot{m}_{i} \cos(\omega t + \phi_{i}) \tag{6}$$

$$\dot{P}_j = P_a + p_j \text{Cos}(\omega t + \theta_j) \tag{7}$$

Using Eqs. (2), (4), and (5), the pressure component of exergy at any location can be written as

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