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Acoustic wave motions stabilized by boundary memory damping*

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ABSTRACT

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1. Introduction

Let Ω be a bounded domain in \mathbb{R}^N with (sufficiently) smooth boundary $\Gamma = \Gamma_0 \cup \Gamma_1$; Γ_0 and Γ_1 are closed nonempty disjoint subsets of Γ . The unit outer normal to Γ_1 is denoted by n. We consider the following system:

$$\begin{cases} \phi_{tt} = \Delta \phi, & \text{in } \mathbb{R}^+ \times \Omega, \\ \phi = 0, & \text{on } \mathbb{R}^+ \times \Gamma_0, \\ \partial_n \phi = \delta_t, & \text{on } \mathbb{R}^+ \times \Gamma_1, \\ -\phi_t = \delta + \int_0^t g(t-s)\delta_s(s)ds & \text{on } \mathbb{R}^+ \times \Gamma_1. \end{cases}$$
(1.1)

We consider the linear wave equation with acoustic boundary conditions (ABC) on

a portion Γ_1 of the boundary and Dirichlet conditions on the rest of the boundary.

The ABC contain a damping term of memory type with respect to the normal

displacement of the point of Γ_1 . Under some assumption on the memory kernel, we show that the associated operator matrix generates a strongly continuous semigroup

of contractions on a Hilbert space, and the semigroup is strongly stable.

The system models sound wave propagation in a domain which is full of some kind of medium and with a portion of boundary made of light-weight viscoelastic material. The function $\phi(x,t)$ represents the velocity potential of the fluid, and $\delta(x,t)$ the normal displacement of the point $x \in \Gamma_1$ at time t. Each point of the surface Γ_1 acts like a viscoelastic element, which is characterized as a Maxwell model connected with an

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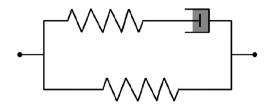


Fig. 1. Maxwell model connected with an elastic element.

elastic element (see Fig. 1), in response to the excess pressure. The points of Γ_1 do not influence one another; such a boundary is called to be *locally reacting* (see Morse and Ingard [1, p. 259]).

Starting from the work in [2], system (1.1) with the last boundary condition replaced by

$$-\rho_0 \phi_t = m\delta_{tt} + d\delta_t + k\delta \quad \text{on } \mathbb{R}^+ \times \Gamma_1$$

 $(\rho_0 > 0, \text{ and } m, d, k \text{ being nonnegative functions on } \Gamma_1 \text{ with } m, k > 0)$ has been studied by virtue of the semigroup theory (cf. [3,4] and the references therein). Recently, [5] investigated the stability of a viscoelastic wave equation with acoustic boundary conditions (see also [6]), where memory damping terms, w.r.t. the velocity potential ϕ , appear both in the interior and boundary, besides the frictional boundary damping term δ_t . In this paper, we will employ the semigroup approach to obtain wellposedness and strong stability of system (1.1) under some condition on the kernel g. For a related work on the wave equation

$$p_{tt} = \Delta p, \quad \text{in } \mathbb{R}^+ \times \Omega,$$

with the boundary condition

$$\partial_n p + \int_0^t g(t-s) p_s(s,\cdot) ds = 0, \quad \text{on } \mathbb{R}^+ \times \Gamma,$$

we refer to [7,8].

2. Preliminaries

We assume the following condition on the kernel g:

• there exists a right-continuous, nondecreasing, and nonconstant function $\lambda(\cdot)$ on $[0, \infty)$ satisfying $\lambda(0) = 0$, and

$$\int_0^\infty s^{-1} d\lambda(s) < \infty \tag{2.1}$$

such that

$$g(t) = \int_0^\infty e^{-st} d\lambda(s), \quad t > 0.$$
(2.2)

The condition means that g is completely monotonic (cf. [9, p. 161, Theorem 12b]), and belongs to $L^1(0,\infty)$. A canonical example of those kernels satisfying the condition is $g(t) = pe^{-qt}$ with constants p, q > 0.

Using (2.2), we have

$$(g * \delta_t)(t, x) = \int_0^t g(t - s)\delta_s(s)ds = \int_0^\infty \psi(t, s, x)d\lambda(s), \quad \forall \delta \in C^1(\mathbb{R}^+; \ L^2(\Gamma_1; \mathbb{C}^n)),$$

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