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# Numerical methods for a quadratic matrix equation with a nonsingular M-matrix $^{\bigstar}$



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## ABSTRACT

We consider numerical solution of a quadratic matrix equation associated with a nonsingular M-matrix (M-QME), which arises in study of noisy Wiener–Hopf problems for Markov chain. We first transform the M-QME to a nonsymmetric algebraic Riccati equation (NARE) of special form, and then solve this special NARE by fixed-point iteration. Theoretical analysis and numerical experiments show that our method is effective and efficient.

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### 1. Introduction and preliminaries

In this paper, we consider the quadratic matrix equation (QME) of the form

$$X^2 - EX - F = 0, (1)$$

where  $E, F \in \mathbb{R}^{n \times n}, E = diag(e_1, e_2, \dots, e_n)$  is a diagonal matrix and  $F = (f_{ij})$  is a nonsingular M-matrix. The QME of this special form is called M-QME. The study of M-QME is motivated by noisy Wiener-Hopf problems for Markov chains, where a specific Q-matrix (-Q is an M-matrix) is needed to satisfy M-QME (1), see [1,2] for more details.

[2] showed that M-QME (1) has a unique nonsingular M-matrix solution, which is of practical interest. Some methods have been developed for solving M-QME by transforming it into an equivalent nonsymmetric algebraic Riccati equation (NARE) to solve (see [2–4]). In this paper, our main aim is to develop a more efficient transformation method.

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In the following, we first review some basic results on M-matrices and regular splitting.

For any matrices  $A = (a_{ij}), B = (b_{ij}) \in \mathbb{R}^{n \times n}$ , we write  $A \ge B(A > B)$ , if  $a_{ij} \ge b_{ij}(a_{ij} > b_{ij})$  for all i, j. A is called a Z-matrix if  $a_{ij} \le 0$  for all  $i \ne j$ . A Z-matrix A is called an M-matrix if there exists a nonnegative matrix B such that A = sI - B and  $s \ge \rho(B)$ . Here and in the following,  $\rho(C)$  denotes the spectral radius of C. In particular A is called a nonsingular M-matrix if  $s > \rho(B)$  and singular M-matrix if  $s = \rho(B)$ . The following results on M-matrices can be found in [5,6].

**Lemma 1.1.** Let A be a Z-matrix, then the following statements are equivalent:

- (1) A is a nonsingular M-matrix;
- (2) There exists a vector v > 0 such that Av > 0.

**Lemma 1.2.** If A is an irreducible nonsingular M-matrix, then  $A^{-1} > 0$ .

Let  $A \in \mathbb{R}^{n \times n}$  be a nonsingular matrix, then A = M - N is called a splitting of A if M is nonsingular; a regular splitting if M is nonsingular,  $M^{-1} \ge 0$ , and  $N \ge 0$ . The following lemma is a basic result for regular splitting (see [6]).

**Lemma 1.3.** Let  $A = M_1 - N_1 = M_2 - N_2$  be two regular splittings of A, where A is nonsingular and  $A^{-1} \ge 0$ . If  $N_2 \ge N_1 \ge 0$ , then  $1 > \rho(M_2^{-1}N_2) \ge \rho(M_1^{-1}N_1) \ge 0$ . If, moreover,  $A^{-1} > 0$  and if  $N_2 \ge N_1 \ge 0$ , equality excluded, then  $1 > \rho(M_2^{-1}N_2) > \rho(M_1^{-1}N_1) > 0$ .

We now review some basic results on nonsymmetric algebraic Riccati equation (NARE)

$$XCX - XD - AX + B = 0, (2)$$

where A, B, C and D are real matrices of sizes  $m \times m$ ,  $m \times n$ ,  $n \times m$  and  $n \times n$  respectively. The NARE of this kind appears in transport theory, Wiener–Hopf factorization of Markov chains and etc., for which one can refer to [7,8,2,9] and the references therein. For the NARE (2), the solution of practical interest is its (entrywise) minimal nonnegative solution.

**Lemma 1.4** ([8]). From the NARE (2), we define an  $(m+n) \times (m+n)$  matrix

$$M = \begin{pmatrix} D & -C \\ -B & A \end{pmatrix}.$$
 (3)

If M is a nonsingular M-matrix, then (2) has a unique minimal nonnegative solution S, and both D - CSand A - CS are nonsingular M-matrices. Moreover, both D - CS and A - CS are irreducible when M is an irreducible (singular or nonsingular) M-matrix.

There have been many effective methods proposed for solving numerically NARE (2) with M being an M-matrix, see [7,3,8,10]. Among them, the fixed-point iteration is the simplest and feasible one.

To compute the M-matrix solution of M-QME (1), Guo in [2] turned it into a special NARE to solve by the transformation

$$X = \alpha I - Y. \tag{4}$$

The motivational thought behind this is that many effective numerical methods for NARE can be fully utilized for M-QME (1). In this paper, we use a more general transformation than (4) to expect to achieve better effectiveness.

The rest of the paper is organized as follows. In Section 2, a new transformation is introduced to turn M-QME (1) into a special NARE and theoretical analysis is given. In Section 3, the special NARE is solved by

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