

## Current Perspectives

## CPP-GMR technology for magnetic read heads of future high-density recording systems

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## ABSTRACT

This paper introduces CPP-GMR technology, its features, routes to output enhancement, problems to be solved and possibilities as a recording head. For instance, use of high spin-dependent bulk scattering, high resistivity, or half-metallic magnetic materials for free and reference magnetic layers were shown as ways to improve the output of CPP-GMR. A current state of CPP-GMR head development was also mentioned in view points of sensor downsizing, magnetic head noise and high-density recording demonstration. CPP-GMR still has some points to be improved, however it is believed that the CPP-GMR will actualize a next high-performance magnetic read head in no distant future.

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## 1. Introduction

One of the present key-technologies for keeping a high growth-rate of magnetic recording density in hard disk drive (HDD) systems is a development of magnetic read heads using a tunneling magnetoresistance (TMR) sensor. The TMR sensor consists of a magnetoresistive film with a thin barrier-layer in a current-perpendicular-to-plane (CPP) structure. However, its high resistance is a critical obstacle to downsizing the sensors for future high-density recording, although the TMR head produces quite a high output signal. Fig. 1 shows the trends of data-transfer rate for high-end HDD systems and allowed resistance-area product ( $RA$ ) of read head sensors with a CPP structure versus areal density. A cut-off frequency of an electrical circuit, which limits the data-transfer rate of a drive system, is inversely proportional to the resistance of the magnetic head. Keeping or reducing this head resistance ( $R$ ) is much important for high areal density. Moreover, the magnetic sensor size ( $A$ ) should be reduced with increasing the areal density. Consequently,  $RA$  of the CPP-type sensor must be reduced as shown in Fig. 1. These trends indicate that the TMR head, whose minimum achievable  $RA$  value is thought to be about  $1\ \Omega\mu\text{m}^2$ , will face the  $RA$  limit at about  $300\text{--}400\ \text{Gbit/in}^2$ .

On the other hand, in terms of sensor resistance, a CPP-GMR (giant magnetoresistance) sensor, which also has a CPP structure, can be applied to much higher areal densities because it uses a metallic spin-valve film and therefore has quite a low  $RA$  of around  $0.1\ \Omega\mu\text{m}^2$ . The CPP-GMR film can be applied to a sensor that is several 10s of nanometers long. Moreover, the CPP structure has advantages such as a short read gap and good

thermal contact with the electrodes. Therefore, the CPP-GMR head is expected to replace the TMR head and enables densities exceeding  $300\ \text{Gbit/in}^2$  [1–4].

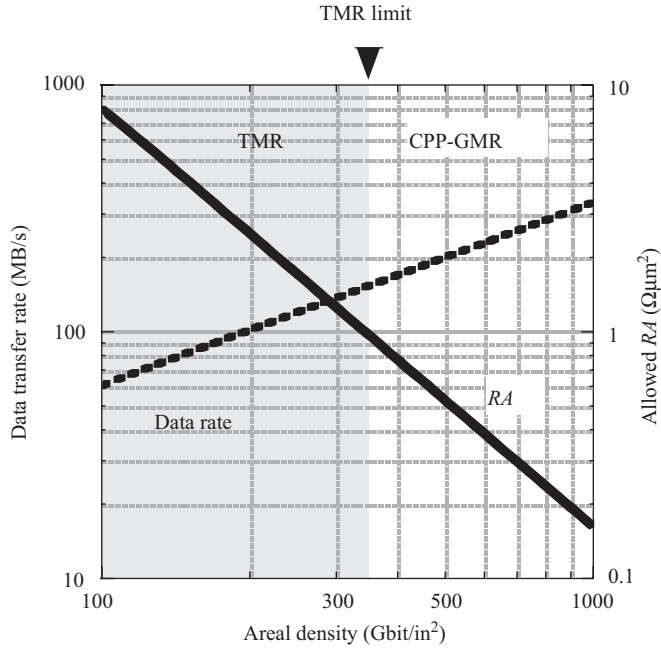
In this paper, I take a general view of several methods for enhancing the CPP-GMR. I also point out the recent state of development and problem of magnetic read heads with the CPP-GMR sensors and give my opinion on the possibility of future high-density magnetic recording.

2. Output ( $\Delta RA$ ) of CPP-GMR sensors2.1.  $\Delta RA$  requirement

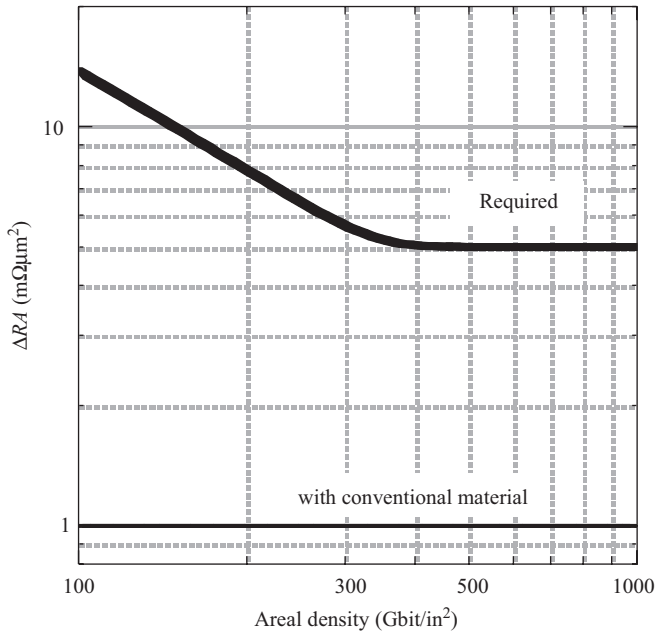
Although CPP-GMR has the advantage of low  $RA$ , the performance of CPP-GMR sensors that use spin-valves made of conventional materials is limited by their small specific magnetoresistance change ( $\Delta RA$ : resistance-change and area product) less than  $1\ \text{m}\Omega\mu\text{m}^2$  (Fig. 2). This is too small to achieve a sufficiently high signal-to-noise ratio (SNR) due to the small change in film resistance that occurs when the relative angle between magnetizations of two magnetic layers is changed. Fig. 2 shows the required  $\Delta RA$  of the CPP-GMR for recording densities as estimated using the following assumed conditions: output signal voltage for sufficient SNR = 1.5 mV, head efficiency = 30%, sense current density =  $100\ \text{MA/cm}^2$ , power consumption of sensor element = 0.6 mW [5].

One of the special features of the CPP-GMR is that an absolute  $\Delta R$  value increases as the sensor is downsized. Because of this feature, the required  $\Delta RA$  becomes smaller as the recording density approaches  $300\text{--}400\ \text{Gbit/in}^2$ , where the power consumption of the sensor causing temperature rise by Joule heating is a dominant factor in limiting the sense current. On the other hand,

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**Fig. 1.** Trends of data-transfer rate for high-end HDD systems and allowed resistance-area product (RA) of read head sensors with current-perpendicular-to-plane (CPP) structure versus areal density.



**Fig. 2.** Estimated required  $\Delta RA$  of CPP-GMR for higher recording densities for output signal voltage = 1.5 mV, head efficiency = 30%, sense current density = 100 MA/cm<sup>2</sup>, and power consumption of sensor element = 0.6 mW.

the current density limit due to an electrical migration or rotational magnetic field becomes dominant over 300–400 Gbit/in<sup>2</sup>, which makes the required  $\Delta RA$  constant, and it is found from this estimation that a  $\Delta RA$  of at least 5 mΩμm<sup>2</sup> is needed.

## 2.2. How to enhance $\Delta RA$

By assuming that the spin-diffusion length is much longer than the layer thickness, RA and  $\Delta RA$  of the CPP structure can be described by a simple two-current model [6–7] derived from

Boltzmann's equation. The  $\Delta RA$  of the CPP configuration, which has a synthetic ferri-coupled magnetic pinned-layer structure for obtaining a strong pinning field and a laminated free-layer structure (Fig. 3, the free-layer structure is single.), can be expressed as follows:

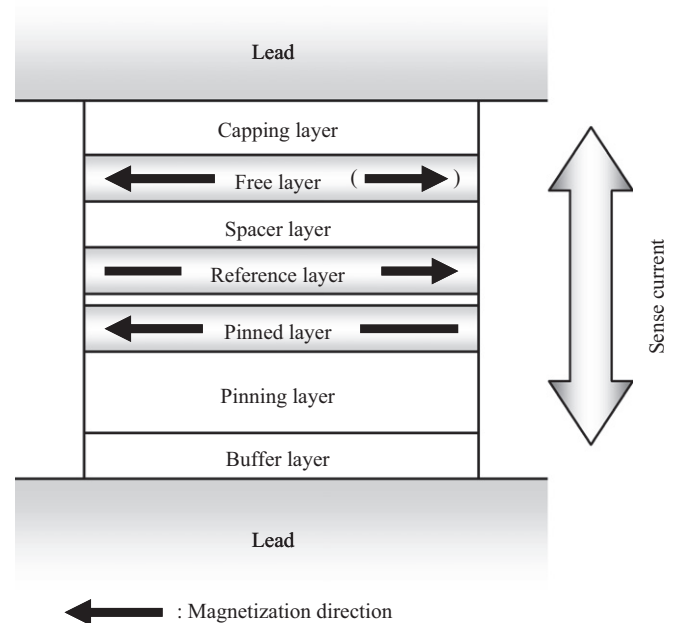
$$\Delta RA = \frac{4(\beta_F \rho_F^* t_F + 2\gamma R_{F/N}^* A n)(\beta_R \rho_R^* t_R - \beta_P \rho_P^* t_P + \gamma R_{F/N}^* A)}{\beta_F^* t_F + \rho_R^* t_R + \rho_P^* t_P + (2n+1)R_{F/N}^* A + (n-1)\rho_{in} t_{in} + R_{para}} \quad (1)$$

Here,  $\beta$  and  $\gamma$  are, respectively, the bulk and interface spin-asymmetry coefficients;  $t$  the thickness of each magnetic layer;  $\rho^* = \rho/(1-\beta^2)$ ; and  $\rho$  the resistivity of the magnetic layer. The suffixes F, R, and P indicate, respectively, the free, reference, and pinned layers.  $R^* A = RA/(1-\gamma^2)$  and RA is the resistance-area product at the interface between the magnetic and non-magnetic layers.  $n$  is the number of the free layer, i.e.,  $n-1$  spacers are inserted in the free-layer structure.  $R_{para}$  is a parasitic resistance in the CPP structure and includes the resistances of terminals, contacts, anti-ferromagnetic pinning layer, and other elements and also crowding resistance. The effect of Ru, which is a typical material, in the synthetic-ferri pinned-layer structure was ignored for simplicity.

Eq. (1) shows there are several methods of enhancing the  $\Delta RA$ ; for example, we could use a material with a high  $\beta \rho^*$  and  $\gamma R^* A$ , thicken the free and reference layers (although this is not practicable because it reduces the free-layer sensitivity and effective strength of the pinning field), or decreases the parasitic resistance. It is also quite effective to use a small or negative  $\beta$  material for the pinned layer. A magnetic/non-magnetic laminated structure of the free (and pinned) layer can be applied, too. It is, however, difficult to use all of these methods in combination because, for example, a high-resistivity material shows little or no spin-dependent scattering. Therefore, realization of a combination in some of these must be a key approach for improving the CPP-GMR.

## 2.3. Magnetic material development

In relation to the above guides to enhance the  $\Delta RA$ , a great deal of effort has therefore been made to improve the  $\Delta RA$  value of CPP



**Fig. 3.** CPP-GMR structure used for calculating  $\Delta RA$ . Spin-valve film is a bottom-type structure with a synthetic ferrimagnet pinned layer.

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