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A R T I C L E I N F O

ABSTRACT

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The study of wave chaos using acoustic resonators [1,2] supplies an invaluable additional test of Random Matrix Theory (RMT) [3,4]. In a 1996 paper Ellegaard et al. [5], studied the gradual breaking of the presumed twofold flip symmetry of a quartz crystal by removing an octant of a sphere of an increasing radius at one of the corners and analysing the statistics of the resulting acoustic eigenfrequencies. They found a gradual evolution of the spacing distribution from that of two uncoupled Gaussian Othogonal Ensembles (2GOE) when the crystal is an uncut perfect rectangle, into a single GOE, when a large chunk of the crystal is removed from one of the corners of the rectangle. This constituted a complete breaking of the symmetry present in the crystal in the uncut situation. The spectral rigidity, measured by Dyson's $\Delta_3(L)$ was also measured in this reference. The 2 uncoupled GOEs were found to underestimate by a great amount the large-L data. This was attributed to pseudointegrable trajectories that do not suffer from the symmetry breaking. This point was further analysed by [6]. Using techniques developed by Pandey [7], Leitner [8] treated the symmetry breaking problem with RMT-perturbation. He addressed only the spacing distribution. This work was further extended to the spectral rigidity in [9]. In all of the above treatment of the data of [5], the assumption was made that the uncut crystal has a twofold flip symmetry and thus is describable by two uncoupled GOEs. The treatment of Leitner [8] is found to describe fairly well

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the NNL distribution, but fails for the spectral rigidity, in contrast to the exact numerical simulation using the Deformed Gaussian Orthogonal Ensemble [10], recently performed in [11]. In this Letter we further analyse the perturbative treatment of symmetry breaking within RMT. We find that the data of [5] can be accounted for with 3GOEs which are gradually mixed till a 1GOE limit is attained. We further find that if some levels were missing in the sample of eigenfrequencies whose statistics is analysed, the $\Delta_3(L)$ can be very well accounted for even at large *L* without the need for pseudointegrable trajectories, whose calculation is difficult.

Using appropriate perturbative methods Leitner [8] was able to find a formula for the nearest neighbor distribution (NND) which contains the symmetry braking term. He started basically with the formula for the nearest neighbour spacing distribution for the superposition of m GOE's block matrices [3]

$$P_m(s) = \frac{d^2}{ds^2} E_m(s) \tag{1}$$

where, for the case of all block matrices having the same dimension one has

$$E_m(s) = \left(E_1\left(\frac{s}{m}\right)\right)^m,\tag{2}$$

$$E_1(x) = \int_{-\infty}^{\infty} \left(1 - F(t)\right) dt,$$
(3)

$$F(t) = \int_{0}^{t} P_{1}(z) dz.$$
 (4)



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In the above $P_1(z)$ is the normalized nearest neighbour spacing distribution of one block matrix. It is easy to find for $P_m(s)$, the following

$$P_m(s) = \frac{1}{m} \left[\left(E_1\left(\frac{s}{m}\right) \right)^{m-1} P_1\left(\frac{s}{m}\right) + (m-1) \left(E_1\left(\frac{s}{m}\right) \right)^{m-2} \left(1 - F\left(\frac{s}{m}\right) \right)^2 \right]$$
(5)
$$\equiv P_m^{(1)}(s) + P_m^{(2)}(s).$$
(6)

If all the block matrices belong to the GOE, then one can use the Wigner form for $P_1(z)$

$$P_1(z) = \frac{\pi}{2} z e^{-\frac{\pi}{4}z^2} \approx \frac{\pi}{2} z,$$
(7)

thus

$$F_1(z) = 1 - e^{-\frac{\pi}{4}z^2} \approx \frac{\pi}{4}z^2,$$
(8)

$$E_1(z) = \operatorname{erfc}\left(\frac{\sqrt{\pi}}{2}z\right) \approx 1 - z,\tag{9}$$

where the large-*z* limits of Eqs. (7)–(9) are also indicated above. It is now clear that the above expression for $P_m(s)$, (5) and (6), contains a term $P_m^{(1)}(s)$ with level repulsion, indicating short-range correlation among levels pertaining to the same block matrix and a second term $P_m^{(2)}(s)$ with no level repulsion, implying short-range correlation among NND levels pertaining to different blocks. Notice that for very small spacing, $P_m(s)$ behaves as

$$P_m(s) \approx \frac{\pi}{2m^2} s + \frac{m-1}{m} \tag{10}$$

for m = 1, we get the usual $P_1(0) = 0$, while for m > 1, we get $P_m(0) = (m - 1)/m$.

To account for symmetry breaking, Leitner [8] considered the mixing between levels pertaining to nearest neighbour block matrices and entails using the $2 \times 2 P(s)$ distribution with full mixing. The DGOE result for the 2×2 matrix was derived in [12] and the resulting P(s) is a product of a Poissonian term times a mixing term. Leitner's procedure [8] amounts to multiply the factor $P_m^{(2)}(s)$ of Eq. (6) by only the mixing term of the $2 \times 2 P(s)$ of [12] with the mixing parameter Λ given by [7], $\Lambda = \lambda^2 \rho^2$, with λ^2 being the ratios of the variances of the matrix elements within a block matrix to that of matrix elements pertaining to neighbouring off diagonal block matrices, and ρ is the density of eigenfrequencies. Thus, he found, assuming that $\Lambda \ll 1$,

$$P_m(s,\Lambda) = P_m^{(1)}(s) + P_{2\times 2}(s,\Lambda) P_m^{(2)}(s),$$
(11)

where $P_{2\times 2}(s, \Lambda)$ is given by [8]

(1)

$$P_{2\times 2}(s,\Lambda) = \sqrt{\frac{\pi}{8\Lambda}} I_0\left(\frac{s^2}{16\Lambda}\right) \exp\left(-\frac{s^2}{16\Lambda}\right),\tag{12}$$

where I_0 is the modified Bessel function of order 0. Though $P_m(s)$ is normalized, $P_m(s, \Lambda)$ is not. Accordingly one supplies coefficients c_N and c_D such that

$$P_m(s,\Lambda,c_N,c_D) \equiv c_N P_m(c_D s,\Lambda)$$
(13)

is normalized to unity. Similarly, $\langle s \rangle$ should be unity too. Eq. (11) can certainly be generalized to consider the effect of mixing of levels pertaining to next to nearest neighbour blocks, and accordingly, $P_{3\times3}(s, \Lambda)$, given in Ref. [12] would be used in Eq. (11) instead of $P_{2\times2}(s, \Lambda)$. In the following, however, we use Eqs. (11), (13) as Leitner did [8].

In [8], Leitner also obtained approximate expression for the spectral rigidity $\Delta_3(L)$ using results derived by French et al. [13].

Leitner's approximation to Δ_3 is equal to the GOE spectral rigidity plus perturbative terms, that is

$$\Delta_{3}^{(m)}(L;\Lambda) \approx \Delta_{3}(L;\infty) + \frac{m-1}{\pi^{2}} \bigg[\bigg(\frac{1}{2} - \frac{2}{\epsilon^{2}L^{2}} - \frac{1}{2\epsilon^{4}L^{4}} \bigg) \\ \times \ln(1 + \epsilon^{2}L^{2}) + \frac{4}{\epsilon L} \tan^{-1}(\epsilon L) + \frac{1}{2\epsilon^{2}L^{2}} - \frac{9}{4} \bigg], \quad (14)$$

where

$$\epsilon = \frac{\pi}{2(\tau + \pi^2 \Lambda)}.$$
(15)

For the cut off parameter we use the value [9] $\tau = c_m e^{\pi/8-\gamma-1}$, where $c_m = m^{m/(m-1)}$ and $\gamma \approx 0.5772$ is Euler's constant. This choice guarantees that when the symmetry is not broken, $\Lambda = 0$, $\Delta_3^{(m)}(L,0) = m\Delta_3(L/m,\infty)$. In Ref. [14], Leitner fitted Eq. (13) for m = 2 to the NND from Ref. [5], however, he did not fit the spectral rigidity. It is often the case that there are some missing levels in the statistical sample analysed. Such a situation was addressed recently by Bohigas and Pato [15]. These authors have started from the general expression of $\Delta_3(L)$ derived by Dyson and Mehta [4], namely,

$$\Delta_3(L) = \frac{L}{15} - \frac{1}{15L^4} \int_0^L dx \, (L-x)^3 \left(2L^2 - 9xL - 3x^4\right) Y_2(x), \tag{16}$$

where the two-point cluster function, $Y_2(x_1, x_2)$, which owing to translational invariance becomes a function of the difference $x = |x_1 - x_2|$, is defined by the usual expression,

$$Y_2(x_1, x_2) = 1 - \frac{R_2(x_1, x_2)}{R_1(x_1)R_1(x_2)},$$
(17)

where R_2 is the 2-point correlation function and R_1 is the density of the spectrum.

If a fraction, 1 - g, of the levels were actually analysed, the cluster function remains invariant, apart from a rescaling of the relevant variables, when the unfolded spectrum is employed, namely

$$Y_2^g(x_1, x_2) = 1 - \frac{(1-g)^2 R_2(x_1^g, x_2^g)}{(1-g)R_1(x_1^g)(1-g)R_1(x_2^g)} = Y_2(x_1^g, x_2^g), \quad (18)$$

where the scaled variables x_i^g are just $\frac{x_i}{(1-g)}$.

Using the above equation for the cluster function in the general expression for $\Delta_3(L)$, we obtain the Missing-Level (ML) expression of [15]

$$\Delta_3^g(L) = g \frac{L}{15} + (1 - g)^2 \Delta_3 \left(\frac{L}{1 - g}\right).$$
(19)

In the application to our current problem of *m*-coupled GOE's, the above formula continue to be valid since the basic input into its derivation, namely the invariance of Y_2 , apart from the scaling of the argument *x* into x^g , is quite general. Accordingly, we have the desired ML formula of $\Delta_3(L)$ for *m*-coupled GOEs,

$$\Delta_3^{(m)g}(L;\Lambda) = g \frac{L}{15} + (1-g)^2 \Delta_3^{(m)} \left(\frac{L}{1-g};\Lambda\right).$$
(20)

The presence of the linear term, even if small, could explain the large *L* behavior of the *measured* $\Delta_3(L)$. We call this effect the Missing-Level (ML) effect. Another possible deviation of Δ_3 from Eq. (14) could arise from the presence of pseudo-integrable effect (PI) [6,16]. This also modifies Δ_3 by adding a Poisson term just like Eq. (19).

The results of our analysis are shown in Figs. 1 and 2. In Fig. 1, the sequence of six measured NNDs were fitted for m = 2 and m = 3. It can be seen that the Leitner model with three coupled GOEs give a comparable and in some cases even better fit than the

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