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Hamiltonian formulation of 2 bounded immiscible media with constant non-zero vorticities and a common interface

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HIGHLIGHTS

- A Bernoulli condition and kinematic boundary conditions are derived for a bound 2 media rotational water-wave system with free common interface
- Non-canonical Hamiltonian equations of motion are derived
- Under a variable transformation the equations are presented in a canonical Hamiltonian form

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1. Introduction

ABSTRACT

We examine a 2-dimensional water-wave system, with gravitationally induced waves, consisting of a lower medium bound underneath by an impermeable flat bed and an upper medium bound above by an impermeable lid such that the 2 media have a free common interface. Both media have constant density and constant (non-zero) vorticity. By examining the governing equations of the system we calculate the Hamiltonian of the system in terms of its conjugate variables and perform a variable transformation to show that it has canonical Hamiltonian structure.

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In 1968 Zakharov published a paper [1] showing the canonical Hamiltonian structure of an infinitely deep irrotational fluid system, i.e. with zero vorticity, with a free surface with gravitationally induced waves. Further relevant studies of the irrotational case were carried out in [2–6]. At the beginning of the 19th century Gerstner [7] had studied vorticity and more recently there have been several papers of interest which consider the rotational case, i.e. with non-zero constant vorticity, e.g. [8–17]. In particular Constantin et al. [18] showed that a consideration of non-zero vorticity gives a *nearly* Hamiltonian structure (with a linear dependency on a vorticity term). Wahlén [19] then showed that, in fact, the system does indeed have *fully* Hamiltonian structure, which can be transformed into canonical form.

A consideration of a system consisting of 2 unbounded media with a free common interface was given by Benjamin and Bridges [20,21]. Craig et al. [22,23] considered an irrotational system consisting of a lower medium bound underneath by a flat bed and an upper medium bound above by an impermeable lid such that the 2 media have a free common interface and also the case in which the upper media itself has a free surface. The aim of this paper is to show that, in the rotational case, the 2 media bounded system has canonical Hamiltonian structure.

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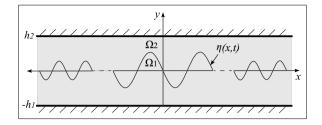


Fig. 1. The system under study.

2. Preliminaries

As per Fig. 1 we define the lower medium Ω_1 as the domain $\{(x, y) \in \mathbb{R}^2 : -h_1 < y < \eta(x, t)\}$, the upper medium Ω_2 as the domain $\{(x, y) \in \mathbb{R}^2 : \eta(x, t) < y < h_2\}$ and the entire system Ω as the domain $\{(x, y) \in \mathbb{R}^2 : -h_1 < y < h_2\}$ where $\{y = \eta(x, t)\}$ describes the elevation of the common interface. The subscript *c* will be used to denote evaluation at the common interface.

We use the subscript notation $i = \{1, 2\}$ to represent the lower and upper media respectively and thus can consider a velocity potential φ_i which is defined by:

$$\begin{cases} u_i = \partial_x \varphi_i - \omega_i y \\ v_i = \partial_y \varphi_i \end{cases}$$
(1)

where non-lateral velocity flow, with propagation in the positive *x*-direction, is given by $\mathbf{V}_{\mathbf{i}}(x, y, z) = (u_i, v_i, 0)$ and ω_1 and ω_2 are the respective non-zero constant vorticities.

Additionally, the stream function ψ_i is introduced, defined by:

$$\begin{cases} u_i = -\partial_y \psi_i \\ v_i = \partial_x \psi_i. \end{cases}$$
(2)

 ρ_1 and ρ_2 are the respective constant densities of the lower and upper media and stability is given by the condition that $\rho_1 > \rho_2$.

We assume that for large |x| the amplitude of η attenuates and hence make the following assumptions

$$\lim_{|x| \to \infty} \eta(x, t) = 0,$$
(3)
$$\lim_{|x| \to \infty} \varphi_i(x, y, t) = 0,$$
(4)

(5)

and

 $-h_1 < \eta(x, t) < h_2$ for all *x* and *t*.

3. Governing equations

We write Euler's momentum-conserving equation as:

$$\partial_t \mathbf{V}_i + (\mathbf{V}_i \cdot \nabla) \mathbf{V}_i = -\frac{1}{\rho_i} \nabla P_i + \mathbf{g}$$
(6)

where $P_i = \rho_i gy + p_{atm} + p_i$ is the pressure at a depth y, p_{atm} is (constant) atmospheric pressure, p_i is the dynamic pressure due to the wave motion, g is the acceleration due to gravity (where y points in the opposite direction to the center of gravity) and **g** is the force due to gravity per unit mass.

Applying Eqs. (1) and (2) this can be written as

$$\nabla \left(\partial_t \varphi_i + \frac{1}{2} (\nabla \psi_i)^2 - \omega_i \psi_i\right) = \nabla \left(-gy - \frac{p_i}{\rho_i}\right) \tag{7}$$

where $\nabla = (\partial_x, \partial_y)$.

At the interface $p_1 = p_2 = p_c$ therefore we write Euler's equation in terms of the velocity potentials, stream functions, densities and vorticities as the energy conserving equality

$$\rho_1 \nabla \left((\partial_t \varphi_1)_c + \frac{1}{2} (\nabla \psi_1)_c^2 - \omega_1 \chi_1 + g\eta \right) - \rho_2 \nabla \left((\partial_t \varphi_2)_c + \frac{1}{2} (\nabla \psi_2)_c^2 - \omega_2 \chi_2 + g\eta \right) = 0, \tag{8}$$

where χ_i is the stream function evaluated at the interface.

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