



Shear banding modelling in cross-anisotropic rocks



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ABSTRACT

Sedimentary geomaterials such as rocks frequently exhibit cross-anisotropic properties and their behaviour depends on the direction of loading with respect to their microstructure. As far as material rupture is concerned, localised deformation in shear band mode appears generally before cracks and material failure. The influence of cross-anisotropy on the shear strain localisation remains an important issue and is investigated in the present study. To do so, a constitutive elastoplastic cross-anisotropic model that includes anisotropy both on the elastic and plastic characteristics is defined. For the plastic part of the model, the anisotropy of a strength parameter is introduced with a microstructure fabric tensor. Then, the fractures are modelled with finite element methods by considering the development of shear strain localisation bands and an enriched model is used to properly reproduce the shear banding. The cross-anisotropy influence on shear banding is studied through numerical applications of small and large-scale geotechnical problems that engender fractures. The two considered applications are a plane-strain biaxial compression test and an underground gallery excavation. The numerical results provide information about the influence of cross-anisotropy on the appearance and development of shear bands. It has been noticed, among other observations, that the material strength vary with the loading direction and that the development and the shape of the excavation fractured zone that develops around a gallery is strongly influenced by the material anisotropy.

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1. Introduction

Geomaterials frequently feature an anisotropic behaviour related to their original fabric (Casagrande and Carillo, 1944). Among them, sedimentary materials are vertically deposited in a succession of layers and their structures are composed of bedding planes. Due to this structural arrangement, the anisotropic properties of such materials often exhibit a certain type of symmetry with isotropic properties in the bedding planes. These materials are said to be transversely isotropic or cross-anisotropic (Amadei, 1983) and their behaviour and response to external solicitations depend on the loading direction with respect to their microstructure.

Since the material behaviour and failure constitute crucial issues in many geotechnical problems, various theories and failure criteria have been developed (Graham and Houlsby, 1983; Duveau et al., 1998; Abelev and Lade, 2004; Lade, 2007). Concerning the material rupture, it is commonly accepted that damage and localised deformation appear before the failure in many cases. Under

a compressive regime when the rupture is essentially governed by shear failure, strain can accumulate in limited zones, generally in shear band mode (Desrues, 2005), and this accumulation can lead to material damage, to the development of macro-cracks (fractures) and to material rupture (Diederichs, 2003).

The influence of cross-anisotropy on the material behaviour and on the shear strain localisation has been investigated by different authors (Abelev and Lade, 2003; Tejchman et al., 2007; Lade et al., 2008). They concluded that the material strength as well as the shear band pattern on small-scale specimens may vary with the direction of loading or with the orientation of the bedding planes. On a large scale, the material cross-anisotropy may also influence the development of fractures around underground galleries as indicated by Armand et al. (2014) and Marschall et al. (2008).

The main objective of this study is to analyse the influence of the material cross-anisotropic features on the fracturing modelled with shear strain localisation bands. It will be investigated with finite element methods for a cross-anisotropic rock, both on a small and on a large scales. Firstly, evidences of the material anisotropy influence on the fracturing is discussed in Section 2. Secondly, the theoretical models are detailed in Section 3 where

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List of symbols

General notations

\dot{a}	time derivative of quantity a	s^{-1}
$a^{e/p}$	elastic/plastic component of quantity a	–
$^{\#}a$	quantity a in orthotropic axes	–
$a_{\parallel/\perp}$	quantity a in parallel/perpendicular direction related to the isotropic planes	–
$a_{0/f}$	initial/final value of quantity a	–
a^t	current configuration of quantity a at a given time t	–
a^*	virtual quantity a	–
$a^{0/1}$	quantity a outside/inside a shear band	–

Greek letters

α	Euler's rotation angle for isotropic planes orientation	$^{\circ}$
β	Lode angle	$^{\circ}$
Γ	porous material boundary	m^2
Γ_{σ}	part of Γ on which \bar{t}_i and \bar{T}_i are applied	m^2
Γ_q	part of Γ on which \bar{q} is prescribed	m^2
δ_{ij}	Kronecker symbol	–
ϵ_{ij}	total strain field	–
$\tilde{\epsilon}_{ij}$	deviatoric total strain field	–
ϵ_{eq}	Von Mises' equivalent deviatoric total strain (total deviatoric strain)	–
ϵ_z	vertical strain for biaxial compression test	–
ζ	stress confinement rate for gallery excavation	–
ζ_w	pore water pressure deconfinement rate for gallery excavation	–
η	yield surface convexity parameter	–
ϑ	tangential coordinate	m
Θ	shear band orientation	$^{\circ}$
$\Theta_{A/C/R}$	Arthur's, Coulomb's and Roscoe's angles for Θ	$^{\circ}$
κ	deviatoric strain increment	–
λ_{ij}	Lagrange multipliers field	Pa
Λ	plastic multiplier	–
μ_w	water dynamic viscosity	$Pa \cdot s$
$\nu_{\parallel/\perp/\parallel/\perp}$	Poisson's ratios	–
ξ	cohesion softening ratio	–
ρ_s	solid grains density	kg/m^3
ρ_w	water density	kg/m^3
σ_{ij}	Cauchy total stress field	Pa
σ'_{ij}	Biot's effective stress field	Pa
$\tilde{\sigma}'_{ij}$	Jaumann effective stress rate	Pa/s
$\hat{\sigma}'_{ij}$	deviatoric total stress field	Pa
σ_i	principal total stresses	Pa
σ'_i	principal effective stresses	Pa
$\sigma_{H/h/v}$	Callovo-Oxfordian claystone <i>in situ</i> principal stresses	Pa
σ_c	uniaxial compressive strength	Pa
σ_x	confinement pressure for biaxial compression test	Pa
σ_z	vertical total stress for biaxial compression test	Pa
$\sigma_{r,0}$	initial pressure on gallery wall	Pa
σ_r^{Γ}	fictive pressure on gallery wall	Pa
Σ_{ijk}	double stress dual of h_{ijk}	$Pa \cdot m$
$\tilde{\Sigma}_{ijk}$	Jaumann double stress rate	$Pa \cdot m/s$
τ_{ij}	microstructure stress field (microstress)	Pa
ν_{ij}	microkinematic gradient field	–
φ	friction angle	$^{\circ}$
φ_{bif}	friction angle at bifurcation	$^{\circ}$
φ_c	compression friction angle	$^{\circ}$
φ_e	extension friction angle	$^{\circ}$
Φ	porosity	–
ψ	dilatancy angle	$^{\circ}$
ψ_{bif}	dilatancy angle at bifurcation	$^{\circ}$
ψ_c	compression dilatancy angle	$^{\circ}$
ψ_e	extension dilatancy angle	$^{\circ}$

ω_{ij}	spin rate tensor	s^{-1}
Ω	porous material configuration (volume)	m^3

Roman letters

I_{σ}	first stress invariant	Pa
$II_{\hat{\sigma}}$	second deviatoric stress invariant	Pa
$II_{\hat{\sigma}}^p$	second deviatoric stress invariant at plastic state	Pa
$III_{\hat{\sigma}}$	third deviatoric stress invariant	Pa
a_{ij}	microstructure fabric tensor for cohesion	Pa
\hat{a}_{ij}	deviatoric microstructure fabric tensor for cohesion	Pa
A_{ij}	reduced deviatoric microstructure fabric tensor for cohesion	–
A_{\parallel}	component of A_{ij} in the isotropic planes	–
A_{ijkl}	elastoplastic constitutive tangent tensor for large strain and rotations	Pa
A_{ijkl}^J	Jaumann's correction tensor for large strain and rotations	Pa
b_{ij}	Biot's tensor	–
$b_{\parallel/\perp}$	Biot's coefficients	–
b	generalised Biot's coefficient	–
$b_{1/2}$	cohesion evolution parameters	–
B_{ρ}	friction angle hardening coefficient	–
B_c	cohesion softening coefficient	–
c	cohesion	Pa
\bar{c}	cohesion under isotropic loading	Pa
C_{ijkl}	elastoplastic constitutive tangent tensor for small strain and rotations	Pa
$d_{1/2}$	yield surface parameters	–
D	second gradient elastic modulus	N
D_{ijkl}^e	compliance elastic tensor	Pa^{-1}
dec_c	cohesion softening shifting	–
dec_{φ}	friction angle hardening shifting	–
Du_i	normal derivative of u_i	–
e_i	orthotropic coordinate axes	m
$E_{\parallel/\perp}$	young's moduli	Pa
F	yield surface	Pa
F_{ij}	macrodeformation gradient field	–
g_i	shear band velocity gradient field	s^{-1}
G	plastic potential	Pa
$G_{\parallel/\perp/\parallel/\perp}$	shear moduli	Pa
h_{ijk}	microkinematic second gradient field	m^{-1}
k_{ij}	intrinsic water permeability tensor	m^2
$k_{\parallel/\perp}$	intrinsic water permeabilities	m^2
K	generalised bulk modulus of the poroelastic material	Pa
K_s	isotropic bulk modulus of the solid grains	Pa
l_i	generalised loading vector	–
L_{ij}	velocity gradient field	s^{-1}
m	yield surface parameter	–
m_G	plastic potential parameter	–
$m_{w,i}$	water mass flow	$kg/m^2 \cdot s$
M_w	water mass inside unit volume Ω	kg/m^3
n_i	normal unit vector	–
p_w	pore water pressure	Pa
p_w^{Γ}	pore water pressure on gallery wall	Pa
q	global deviatoric stress for biaxial compression test	Pa
\bar{q}	input water mass per unit area	$kg/m^2 \cdot s$
$q_{w,i}$	average speed of water relative to the solid grains	m/s
Q	water sink term	$kg/m^3 \cdot s$
r	gallery radius	m
r_c	compression reduced radius of the yield surface	–
$r_{c,G}$	compression reduced radius of the plastic potential	–
r_e	extension reduced radius of the yield surface	–

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