



**Abbreviations and Acronyms**

|                         |  |
|-------------------------|--|
| cMRI                    | = cardiac magnetic resonance imaging                                     |
| CoA                     | = coaptation area  |
| DN                      | = double neochorda   |
| ePTFE                   | = expanded polytetrafluoroethylene                                       |
| FE                      | = finite element   |
| $F_{\text{ePTFE}}$      | = artificial suture tension  |
| $F_{\text{nc}}$         | = native chordal tension   |
| IPP                     | = isolated posterior prolapse  |
| $\Delta l_{\text{NCI}}$ | = millimetric variation in the tuning of neochordal length               |
| MR                      | = mitral regurgitation   |
| MV                      | = mitral valve   |
| NCI                     | = neochordal implantation  |
| Phys-model              | = physiologic model  |
| PM                      | = papillary muscle   |
| Pre-model               | = preoperative model   |
| $S_I$                   | = maximum principal stress   |
| $S_I^{\text{MAX}}$      | = peak value of maximum principal stresses along the leaflet free margin |
| SL                      | = standard loop  |
| SN                      | = single neochorda   |

with excellent results in early and late outcomes.<sup>3-5</sup> Since the clinical introduction of NCI in the late 1980s, the procedure has become an established technique<sup>6,7</sup> proven to be safe and effective for both the anterior and posterior leaflets,<sup>8</sup> allowing for a more physiologic repair with preserved leaflet mobility compared with resection techniques. However, the results of NCI largely depend on the appropriate number and length of the ePTFE sutures,<sup>9</sup> which are still highly demanding issues, almost entirely based on the surgeon's expertise.<sup>10-13</sup> Furthermore, when tuning the proper repair configuration with NCI, surgeons may have to progressively adjust the initially attempted repair to overcome residual mitral regurgitation (MR), although at the price of a longer and more difficult procedure. Therefore, a better understanding of the biomechanical effects of different NCI techniques on the MV apparatus and their relationship with patient-specific features and neochordal suture lengths may lead the way to a more reproducible and effective surgery, thus avoiding potential biomechanical drawbacks associated with a suboptimal repair. This aim can be pursued by means of finite element (FE) modeling, widely adopted today for the numeric analysis of the MV.<sup>14-16</sup>

**MATERIALS AND METHODS****Background of the Present Study**

In a recent study,<sup>17</sup> we adopted patient-specific FE models to quantify the biomechanical effects of different ePTFE neochordal techniques in different morphologies of MV isolated posterior prolapse (IPP). Our results strongly suggested that different NCI techniques may equivalently recover MV coaptation while inducing notably different biomechanical

consequences on the surrounding tissues, potentially affecting postoperative remodeling. These differences were dependent on both NCI techniques and patient-specific IPP. However, "ideal" NCI techniques may require millimetric adjustments, which are difficult to obtain in the "real daily surgical world" because of the subjective nature of manual surgical gestures.

In the present work, using different NCI techniques, we evaluated the biomechanical effects of apparently correct repairs (ie, without residual MR) due to a suboptimal millimetric ePTFE suture length.

**Patient-Specific Mitral Valve Finite Element Modeling**

The institutional review board approved the study, and informed consent was obtained from all patients. Four patients in stable sinus rhythm were selected from 20 contemporary cases affected by fibroelastic deficiency and scheduled for surgical repair of IPP due to chordal rupture. Selected patients fit the paradigm of a candidate for NCI, in that they had P2 prolapse characterized by different IPP mechanisms: single primary chordal rupture anchoring on mid-P2 (patients 1 and 4); triple primary chordal rupture anchoring on mid-P2 (patient 2); and single paracommissural, between P2 and P3 scallops, primary chordal rupture (patient 3).<sup>17</sup> Cardiac magnetic resonance imaging (cMRI) acquisitions were preoperatively performed on the selected patients through a 3.0T TX Achieva system (Philips Medical System, Irvine, Calif), with 1.25-mm in-plane resolution and 8-mm slice thickness, following a well-established protocol of acquisition.<sup>18</sup> With the use of dedicated software (MATLAB, The MathWorks Inc, Natick, Mass), reference points were manually traced on all MV substructures in the end-diastolic frame (ie, the last frame preceding transient leaflets closure) and used to obtain the 3-dimensional model of the MV apparatus, which was assumed to be stress-free in this condition.<sup>14,18</sup> The 3-dimensional model was refined on the basis of intraoperative measurements of the annulus to free edge extent of the MV leaflets at different reference points and on details of the IPP lesion (eg, number and type of the chordae involved, papillary muscle [PM], and posterior leaflet insertion). Models were completed by a realistic description of the stress-strain response of MV tissues and ePTFE neochordae.<sup>17,18</sup>

The mitral annulus and PMs were traced on cMRI frames from end diastole to peak systole (ie, the mid-systolic frame within the R-R interval) to derive the respective motion, which was imposed as a boundary condition together with a standard time-dependent transvalvular pressure load to simulate MV closure from end diastole to peak systole. The commercial solver ABAQUS Explicit 6.10 (SIMULIA, Dassault Systèmes, Vélizy-Villacoublay, France) was used.

With this simulation setup, the following 3 general conditions were analyzed for each MV (Figure 1):

- Physiologic model (Phys-model), characterized by an intact chordal apparatus and providing the physiologic level of MV coaptation and distance between the insertion of the ruptured chordae and the corresponding PM head.
- Preoperative model (Pre-model), reproducing the actual MV lesion and dysfunction (Figure 1, A).
- Postoperative models (NCI models), reproducing 3 different NCI techniques: single neochorda (SN), double neochorda (DN), and a standard loop (SL) consisting of 3 premeasured neochordae of the same length anchored to the PM tip (Figure 1, B and C).<sup>17</sup> For each technique, an "ideal" setting and several suboptimal although realistic settings (named "apparently correct") were simulated. In the "ideal" SN and DN, neochordal length was tuned to reproduce the distance between the PM tip and the "leaflet" sites of NCI, as computed in the Phys-model. In the ideal SL, the length of each loop was equal to the maximal distance ( $L_{\text{max}}$ ) of the 3 insertion points from the PM tip, as computed in the Phys-model (Figure 1, B). Conversely, "apparently correct" settings of NCI techniques were simulated as follows: SN with ideal suture length altered by  $\pm 2$  mm ( $L_P \pm 2$  mm); DN with separate alteration by  $\pm 2$  mm of each single ideal neochorda ( $L_Q \pm 2$  mm,  $L_R \pm 2$  mm) or alteration of both ideal sutures ( $L_Q$  and  $L_R \pm 2$  mm); SL with the length of the 3 loops

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