



# An extension of Hall's theorem for partitioned bipartite graphs <sup>☆</sup>



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## ABSTRACT

Let  $G = (X, Y, E)$  be a bipartite graph with bipartition  $X$  and  $Y$  and edge set  $E$  such that  $X$  is partitioned into a set of  $k$  pairwise disjoint subsets  $X_1, X_2, \dots, X_k$ . For any sequence  $n_1, n_2, \dots, n_k$  of natural numbers with  $n_i \leq |X_i|$  for all  $i$ , we prove a necessary and sufficient condition for the existence of a semi-perfect matching in  $G$ , a matching that includes, for each  $i$ , at least  $n_i$  edges that are incident to vertices from  $X_i$ . Clearly, this is equivalent to Hall's theorem in the case where  $n_i = |X_i|$  for all  $i$ .

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## 1. Introduction

Let  $G = (X, Y, E)$  be a bipartite graph with bipartition  $X$  and  $Y$  and edge set  $E$  such that an edge  $(x, y)$  in  $E$  means that vertex  $x \in X$  can be assigned to vertex  $y \in Y$ . Let  $n$  and  $m$  denote the cardinalities of the sets of vertices and edges in  $G$ , respectively. A *matching* in graph  $G$  is a set of pairwise non-adjacent edges, and a *maximum* matching in  $G$  is a matching that contains the maximal number of edges.

The problem of finding a maximum matching in  $G$  can be reduced to the maximum flow problem as follows. We first add a source  $s$  with edges to all vertices in  $X$ , and a sink  $t$  with edges from all vertices in  $Y$ . Next, we assign a unit capacity to each edge of the resulting graph, and then compute a maximal flow from  $s$  to  $t$ . It is easy to verify that the set of all edges with nonzero flow from  $X$  to  $Y$  forms a maximum matching in  $G$ . Therefore, algorithms designed for the maximum flow problem can be

used to solve the maximum matching problem in bipartite graphs. Thus, Dinic's algorithm [5] can be used to find a maximum matching in  $G$  in  $O(\sqrt{nm})$  time. Different algorithms of the same running time are proposed for finding maximum matching in general graphs [2,7,12]. By adapting Dinic's algorithm to the maximum matching problem in bipartite graphs, Hopcroft and Karp [10] improved the time complexity to  $O(\sqrt{\kappa}m)$ , where  $\kappa$  denotes the cardinality of a maximum matching in  $G$ . Feder and Motwani [6] applied Dinic's algorithm after compressing  $G$ , reducing the number of edges by about a factor of  $\log n$ . They proved a running time of  $O(\sqrt{nm}^*)$ , where  $m^*$  is the cardinality of the set of edges in the compressed graph. Based on the fast matrix multiplication algorithm, Mucha and Sankowski [13] developed a randomized algorithm with time complexity  $O(n^{2.38})$  for the maximum matching problem in bipartite graphs.

A maximum matching  $M$  in  $G$  is called *perfect matching* if, for every  $x \in X$ , there exists an edge that incident to  $x$  in  $M$ . Hall [4] proposed the following famous theorem that provides a necessary and sufficient condition for the existence of a perfect matching in bipartite graphs. For a subset  $A$  of  $X$ , define  $N_G(A)$  to be the set of all vertices  $y \in Y$  that are endpoints of edges with at least one

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endpoint in  $A$ , and let  $|A|$  and  $|N_G(A)|$  denote the cardinalities of  $A$  and  $N_G(A)$ , respectively.

**Theorem 1** (Hall's theorem). *There exists a perfect matching in the bipartite graph  $G = (X, Y, E)$  if and only if  $|N_G(A)| \geq |A|$  for every subset  $A$  of  $X$ .  $\square$*

Several applications and extensions of Hall's theorem have been considered in the literatures. The rest of this section is devoted for summarizing some of these extensions.

Let  $\mathcal{S} = \{S_1, S_2, S_3, \dots\}$  be a family of subsets of a given set  $A$ . A system of distinct representatives of  $\mathcal{S}$  is an indexed set  $\{a_1, a_2, a_3, \dots\}$  of distinct elements of  $A$  such that  $a_i \in S_i$  for all  $i$ . Hall [8] showed that there exists a system of distinct representatives of  $\mathcal{S}$  if the union of any  $k$  distinct subsets from  $\mathcal{S}$  contains at least  $k$  distinct elements, for every finite  $k$ . He also showed that this condition is sufficient if the number of subsets is finite (i.e.,  $\mathcal{S}$  is finite). Afterward, Hall [9] proved that the above condition is sufficient if every subset  $S_i$  in  $\mathcal{S}$  is finite.

Let  $G = (X, Y, E)$  be a bipartite graph such that  $X = \cup_{1 \leq i \leq k} A_i$  and  $Y = \cup_{1 \leq i \leq k} B_i$ , where  $\{A_1, A_2, \dots, A_k\}$  and  $\{B_1, B_2, \dots, B_k\}$  are two families of finite sets. Pinelis [14] proved a necessary and sufficient condition for the existence of a perfect matching  $M$  in  $G$  such that, for each  $i = 1, 2, \dots, k$ , all vertices of  $A_i$  are assigned in  $M$  to vertices from  $B_i$ .

A  $(1, k)$ -complete matching from  $X$  to  $Y$  in bipartite graph  $G = (X, Y, E)$  is a subgraph of  $G$  in which each vertex in  $X$  is adjacent to exactly  $k$  distinct vertices from  $Y$  and each vertex in  $Y$  is adjacent to at most one vertex from  $X$ . Longani [11] proved a necessary and sufficient condition for the existence of  $(1, k)$ -complete matching in bipartite graphs for any natural number  $k$ .

Bokal et al. [3] proved a characterization of bipartite graph  $G = (X, Y, E)$  that admits a spanning subgraph in which the degrees of vertices in  $X$  and  $Y$  satisfy specified upper and lower bounds, respectively. Formally, for any two mappings  $f : X \rightarrow \mathbb{N}$  and  $g : Y \rightarrow \mathbb{N}$ , a set  $E' \subseteq E$  of edges is an  $(f, g)$ -quasi-matching of  $G$  if every element  $y$  of  $Y$  has at least  $g(y)$  incident edges from  $E'$ , and every element  $x$  of  $X$  has at most  $f(x)$  incident edges from  $E'$ , where  $\mathbb{N}$  denotes the set of natural numbers. Bokal et al. [3] proved necessary and sufficient conditions for the existence of  $(f, g)$ -quasi-matching in  $G$ .

Another generalization of Hall's theorem was obtained by Aharoni and Haxell [1] for hypergraphs (a graph in which each edge may connect more than two vertices). A matching in the hypergraph is a set of pairwise disjoint edges. They proved a necessary and sufficient condition for the existence of a system of pairwise disjoint representatives for a family of hypergraphs.

Now, consider the situation in which we have a set of projects each of them consists of a finite set of tasks, and a set of machines for carrying out these tasks. Each machine can process at most one task at a time, and a task can be processed by a machine if they satisfy some criteria (e.g., the processing cost is bounded by a given upper bound). The proposed plan may require a certain portion (number of tasks) of each project to be accomplished by the end

of the first stage. It is easy to see that this problem can be formulated as a matching problem in a bipartite graph. Up to our knowledge, this model cannot be reduced to one of the known versions of matching problems. In this note, we prove a necessary and sufficient condition for the existence of a desired matching in this model. We also show that this matching (if one exists) can be computed in polynomial time.

## 2. Hall's theorem for partitioned bipartite graphs

Define a *partitioned bipartite graph*  $(G = (X, Y, E), \mathcal{X}, \mathcal{N})$  in which  $G = (X, Y, E)$  is a bipartite graph,  $\mathcal{X} = \{X_1, X_2, \dots, X_k\}$  is a partition of  $X$ , and  $\mathcal{N}$  is a sequence of  $k$  natural numbers  $n_1, n_2, \dots, n_k$  with  $n_i \leq |X_i|$  for all  $i$ . A matching  $M$  in a partitioned bipartite graph  $(G = (X, Y, E), \mathcal{X}, \mathcal{N})$  is called a *semi-perfect matching* if, for every  $i = 1, 2, \dots, k$ , at least  $n_i$  edges in  $M$  are incident to vertices from the set  $X_i$ . In this section we prove a necessary and sufficient condition for the existences of a semi-perfect matching in partitioned bipartite graphs. We assume without loss of generality that each vertex  $x$  in  $X$  is adjacent to at least one vertex in  $Y$  since otherwise we can simply delete  $x$  from  $X$  without affecting the existence of a semi-perfect matching in  $(G = (X, Y, E), \mathcal{X}, \mathcal{N})$ .

For a subset  $A \subseteq X$ , let  $d_{(G, \mathcal{X}, \mathcal{N})}^A$  denote the maximum number of vertices in  $A$  that might not be included in any semi-perfect matching in  $(G = (X, Y, E), \mathcal{X}, \mathcal{N})$ , i.e.,  $d_{(G, \mathcal{X}, \mathcal{N})}^A = \sum_{1 \leq i \leq k} \min\{|A \cap X_i|, |X_i| - n_i\}$ .

The following theorem is an extension of Hall's theorem in partitioned bipartite graphs. The main idea of the proof is similar to that of the original Hall's theorem.

**Theorem 2.** *There exists a semi-perfect matching in a partitioned bipartite graph  $(G = (X, Y, E), \mathcal{X}, \mathcal{N})$  if and only if*

$$|N_G(A)| \geq |A| - d_{(G, \mathcal{X}, \mathcal{N})}^A \tag{1}$$

for every subset  $A$  of  $X$ .

**Proof.** If the partitioned bipartite graph  $(G = (X, Y, E), \mathcal{X}, \mathcal{N})$  has a semi-perfect matching, then it is easy to verify that it satisfies Condition (1).

Now, assume that the partitioned bipartite graph  $(G = (X, Y, E), \mathcal{X}, \mathcal{N})$  satisfies Condition (1) and we want to show that it has a semi-perfect matching. We prove the theorem by induction on the cardinality of the set  $X$ . If  $X$  contains one vertex  $x$  (i.e.,  $X = \{x\}$ ), then the theorem is trivially true since  $x$  is adjacent to at least one vertex in  $Y$  by the assumptions. Assume that the theorem is true for  $|X| \leq n$ , and consider a bipartite graph  $G$  with  $|X| = n + 1$ . We consider the following two cases.

**Case 1.** In the first case,  $|N_G(A)| \geq |A| - d_{(G, \mathcal{X}, \mathcal{N})}^A + 1$  holds for every subset  $A \subset X$ . Then we choose any vertex  $x \in X$ , say from a subset  $X_i$  in  $\mathcal{X}$ , and any  $y \in N_G(\{x\})$ . Note that  $y$  is well defined since the set  $N_G(\{x\})$  is nonempty by the assumptions. Let  $G' = (X', Y', E')$  be the bipartite graph with bipartition  $X' = X - \{x\}$  and  $Y' = Y - \{y\}$ , and whose set of edges  $E'$  is the same as those in  $E$  after deleting all edges incident to  $x$  and  $y$ . Define a partition  $\mathcal{X}' = \{X'_1, X'_2, \dots, X'_k\}$  of  $X'$  such that

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