Contents lists available at ScienceDirect

Information Processing Letters

www.elsevier.com/locate/ipl

Estimating the number of connected components in sublinear time

Petra Berenbrink, Bruce Krayenhoff, Frederik Mallmann-Trenn*

Simon Fraser University, Canada

A R T I C L E I N F O

Article history: Received 18 February 2014 Received in revised form 15 May 2014 Accepted 16 May 2014 Available online 29 May 2014 Communicated by Ł. Kowalik

Keywords: Approximation algorithms Graph algorithms Connected components Sublinear time algorithms Graph theory

ABSTRACT

We present an algorithm that estimates the number of connected components of a graph over *n* vertices within an additive error of εn in (sublinear) time $O(\frac{1}{\varepsilon^2} \log(\frac{1}{\varepsilon}))$. A connected component *C* is the maximal subset of nodes of an undirected graph *G* such that for any two nodes in *C* there is path connecting. We consider graphs without multiple edges. The *Connected Component Problem* is well-known and amongst the first topics taught in graph theory. The number of connected components can be used to calculate the weight of the minimum spanning tree [1]. Moreover, the study of connected components finds its application in Connected-component labelling, which is used in computer vision. An algorithm runs in sublinear time if its running time is o(n) for an input of size *n*. So far, the best known algorithm was provided by [1]. Their running time is $O(d\varepsilon^{-2}\log(\frac{d}{\varepsilon}))$ where *d* is the average degree.

© 2014 Elsevier B.V. All rights reserved.

1. Introduction

Let G = (V, E) be an undirected graph with *n* nodes, without multiple edges. *G* may have self-loops. A connected component *C* is the maximal subset of nodes of an undirected graph *G* such that for any two nodes in *C* there is path connecting them. It is well-known that the problem of finding the number of connected components can be solved in time O(|V|+|E|) using breadth-first search (see [2], for example). In this paper we present a sublinear-time algorithm which estimates the number of connected components of *G* within an additive error of εn in time $O(\frac{1}{\varepsilon^2} \log(\frac{1}{\varepsilon}))$. So far, the best known sublineartime algorithm was provided by [1]. Their running time is $O(d\varepsilon^{-2} \log(d/\varepsilon))$ where *d* is the average degree. Note that our result is independent of the degree of the graph.

The *Connected Component Problem* is well-known and amongst the first topics taught in graph theory. The number of connected components can be used to calculate the weight of the minimum spanning tree [1]. Moreover,

http://dx.doi.org/10.1016/j.ipl.2014.05.008 0020-0190/© 2014 Elsevier B.V. All rights reserved. the study of connected components finds its application in Connected-component labelling, which is used in computer vision.

1.1. Related work

Calculating the number of connected components in o(n) space or time has received a lot of attention: [3] give a deterministic algorithm to solve the *Connected Component Problem* in logarithmic space. The first sublinear time¹ approximation algorithm was provided by [1]. The authors present an algorithm that approximates the number of connected components with constant probability within a factor of εn . The running time of their algorithm is $O(d\varepsilon^{-2}\log(\frac{d}{\varepsilon}))$ where *d* is the average degree. As we explain in Section 2.1, the algorithm presented in this paper uses some of their techniques. The authors of [1] also provide a $\Omega(d\varepsilon^{-2})$ lower bound for estimating the number of connected components for graphs with multiple edges. We note that their lower bound does not apply to graphs





CrossMark

^{*} Corresponding author.

¹ The required time is o(n) for an input of size *n*.

without multiple edges and hence, their lower bound does not apply to the graph class considered in this paper.

The authors of [4] approximate the number of connected components within a multiplicative error in the metric setting, i.e., in graphs with edge weight satisfying the triangle inequality. Their algorithm runs in $\tilde{O}(\frac{n}{n^3})$ time

(\tilde{O} is used to suppress logarithmic factors).

There are also results in the property testing model. The authors of [5] give a property-testing algorithm applicable to graphs of bounded degree D. Their algorithm accepts G if G is connected. If G is ε -far from being connected (meaning that at least εDn edges have to be added in order to make it connected), their algorithm rejects with a probability of at least $\frac{2}{3}$. The property tester presented has a running time of $O(\log^2(1/(\varepsilon D))/\varepsilon)$.

2. The algorithm

Our algorithm uses some ideas of [1]. In the following we first present their algorithm, then we sketch an easy algorithm which has the same approximation as our algorithm, but a running time of $O(\varepsilon^{-4})$. Finally, we present our algorithm in Section 2.3.

2.1. Chazelle's algorithm

The algorithm of [1] calculates first $r = O(\frac{1}{c^2})$ estimators β_1, \ldots, β_r . Then the algorithm outputs

$$\hat{c} = \frac{n}{2r} \cdot \sum_{i=1}^{r} \beta_i,$$

which is defined as the average of these estimators. The authors show that \hat{c} correctly estimates the number of connected components within an additive factor εn , with probability of at least 3/4. Each β_i is calculated in the following way: A start node u_i is chosen uniformly at random. The algorithm performs a BFS (Breadth-First Search) starting at u_i . The BFS visits all neighbours of u_i unless it has a degree greater than $W = 2/\varepsilon$. Afterwards, the algorithm proceeds in rounds. In every round a coin is flipped and if the outcome is tails, then the algorithm sets $\beta_i = 0$. If the outcome is heads, then the algorithm continues the BFS search by visiting (in the current round) at most as many edges as visited in all previous rounds combined. If all edges in the connected component have been explored, then the algorithm returns

$$\beta_i = \frac{d_{u_i} \cdot 2^{\text{\# of coinflips}}}{\text{\# visited edges}},$$

where d_u denotes the degree of node u. If the connected components size exceeds a threshold of $O(d/\varepsilon)$ or the degree of one of the visited nodes exceeds the estimate of the average degree, then $\beta_i = 0$.

The overall estimator of the number of connected components is the average over all estimators β_i scaled by *n*.

2.2. An easy algorithm

In order to establish some useful intuition, we briefly discuss an easier algorithm, inspired by [1] for achieving an εn -approximation with probability at least 3/4 and with a running time of $O(\varepsilon^{-4})$. The algorithm does the following. Sample $r^* = O(\varepsilon^{-2})$ many starting nodes uniformly at random. Let u_i be the node of sample *i*. Perform a BFS starting at u_i until either the component is explored or $W^* = c'\varepsilon^{-1}$ nodes are visited for some fixed constant *c'*. We set $\beta_{u_i} = 1/c_{u_i}$ if the entire component was discovered where c_{u_i} is the size of the connected component of u_i . Otherwise, i.e., if the connected component of u was not discovered completely, we set $\beta_{u_i} = 0$. Finally, output $\hat{c}^* = n/r^* \sum_i \beta_i$ as an estimate of the number of connected components.

The total number of queries is $O(\varepsilon^{-4})$ since every BFS has $O(\varepsilon^{-2})$ many edges. By using the same ideas as in [1], one can see that $c - \frac{\varepsilon n}{2} < E[\hat{c}^*] \le c$, where *c* is the number connected components. The $\varepsilon n/2$ approximation, is due to the early stopping of explorations visiting W^* many nodes, since the number of connected components having a size of more than W^* is bounded by εn . By observing that the variance of \hat{c}^* is small and by applying Chebyshev's inequality, one can verify that the algorithm approximates c within an additive error of εn with a probability of at least 3/4.

We now use a slightly more sophisticated algorithm to decrease the running time without affecting the error bounds.

2.3. Our algorithm

The core of our algorithm is similar to the algorithm of [1]. Our algorithm of calculates first $r = O(\frac{1}{c^2})$ estimators β_1, \ldots, β_r and outputs \hat{c} as the average of these estimators. The difference between the two algorithms lies in the calculation of β_i . To decide when to stop the BFS walk for a node v_i our algorithm uses a probability distribution inspired by [4]. Let c_{ν} denote the number of nodes in the connected component containing v. For every node v_i we define a random variable X_i and explore the component of v_i for min{ X_i, W } steps. X_i is drawn according to the probability distribution $P(X \ge j) = \frac{1}{j^2}$. If the entire component is explored, our algorithm sets $\beta_i = c_{\nu_i}$. Otherwise, i.e., if our algorithm stops exploring the component, our algorithm sets $\beta_i = 0$.

The probability of visiting the whole component of node v_i is $1/c_i^2$ if $c_i \le W$ and 0 otherwise.

ALGORITHM CC: Set $r = O(\frac{1}{\varepsilon^2})$ and $W = \frac{2}{\varepsilon}$.

for
$$i = 0$$
 to r do

Pick a start node v_i uniformly at random.

Choose X_i according to the prob. distribution $P(X \ge X_i)$ $j) = \frac{1}{i^2}.$

Perform a BFS starting from v_i until one of the following events occurs.

Event 1) All nodes in v_i 's component are explored: Set $\beta_i = c_v$.

Event 2) min{ X_i , W} + 1 nodes are explored: Set $\beta_i = 0.$

end for

Output $\hat{c} = \frac{n}{r} \sum_{i=1}^{r} \beta_i$ as the estimated number of connected components.

Download English Version:

https://daneshyari.com/en/article/428928

Download Persian Version:

https://daneshyari.com/article/428928

Daneshyari.com