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Vertex fault tolerance of optimal- κ graphs and super- κ graphs $^{\Leftrightarrow}$

Yanmei Hong^a, Zhao Zhang^{b,*}

- ^a Department of Mathematics, Shanghai University, Shanghai 200444, China
- ^b College of Mathematics and System Sciences, Xinjiang University, Urumqi, Xinjiang 830046, China

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ABSTRACT

A connected graph G is optimal- κ if $\kappa(G) = \delta(G)$. It is super- κ if every minimum vertex cut isolates a vertex. An optimal- κ graph G is m-optimal- κ if for any vertex set $S \subseteq V(G)$ with $|S| \leqslant m, G-S$ is still optimal- κ . We define the vertex fault tolerance with respect to optimal- κ , denoted by $O_{\kappa}(G)$, as the maximum integer m such that G is m-optimal- κ . The concept of vertex fault tolerance with respect to super- κ , denoted by $S_{\kappa}(G)$, is defined in a similar way. In this paper, we show that $\min\{\kappa_1(G) - \delta(G), \delta(G) - 1\} \leqslant O_{\kappa}(G) \leqslant \delta(G) - 1$ and $\min\{\kappa_1(G) - \delta(G) - 1, \delta(G) - 1\} \leqslant S_{\kappa}(G) \leqslant \delta(G) - 1$, where $\kappa_1(G)$ is the 1-extra connectivity of G. Furthermore, when the graph is triangle free, more refined lower bound can be derived for $O_{\kappa}(G)$.

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1. Introduction

Throughout this paper, all graphs are simple. Let G be a connected graph. A vertex subset $S \subseteq V(G)$ is a *vertex cut* if G - S is disconnected. The minimum cardinality of a vertex cut of G is called the *connectivity* of G, denoted by $\kappa(G)$. A vertex cut S with $|S| = \kappa(G)$ is called a κ -cut. In general, the larger $\kappa(G)$ is, the more reliable the graph is. Since $\kappa(G) \leqslant \delta(G)$, where $\delta(G)$ is the minimum degree of G, a connected graph G with $\kappa(G) = \delta(G)$ is said to be *maximally connected* (or *optimal-\kappa* for short). It is *super-connected* (*super-\kappa* for short) if every minimum vertex cut of G isolates a vertex. A super- κ graph is clearly optimal- κ .

In this paper, we are interested in the vertex fault tolerance with respect to optimal- κ and super- κ , the concept of which is defined in the following.

Definition 1.1. An optimal- κ (resp. super- κ) graph G is m-optimal- κ (resp. m-super- κ) if G-S is still optimal- κ

E-mail addresses: lovely-hym@163.com (Y. Hong), zhzhao@xju.edu.cn (Z. Zhang).

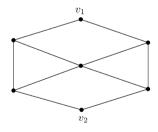


Fig. 1. A graph G with $O_{\kappa}(G) = 1$ and $S_{\kappa}(G) = 0$.

(resp. super- κ) for any vertex set $S \subseteq V(G)$ with $|S| \leqslant m$. We define the *vertex fault tolerance with respect to optimal-\kappa* (resp. *super-\kappa*), denoted by $O_{\kappa}(G)$ (resp. $S_{\kappa}(G)$), as the maximum integer m such that G is m-optimal- κ (resp. m-super- κ).

The graph G in Fig. 1 has $O_{\kappa}(G) = 1$ (notice that $G - \{v_1, v_2\}$ is no longer optimal- κ) and $S_{\kappa}(G) = 0$ (notice that $G - \{v_1\}$ is no longer super- κ).

The two concepts in Definition 1.1 generalize those of optimal- κ and super- κ (the special case when m=0). In this paper, we study bounds for $O_{\kappa}(G)$ and $S_{\kappa}(G)$.

A related work is [7], where Hong and Meng first proposed the concept of edge fault tolerance for super edge connected graphs. A graph is *super edge connected* if ev-

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^{*} Corresponding author.

ery minimum edge cut isolates a vertex. A super edge connected graph G is m-super edge connected if G-S is still super edge connected for any edge set $S \subseteq E(G)$ with $|S| \leq m$. The maximum integer of such m, denoted by $S_{\lambda}(G)$, is the edge fault tolerance with respect to super edge connectedness. In [7], the authors showed that $\{\lambda'(G) - \delta(G) - 1, \delta(G) - 1\} \leq S_{\lambda}(G) \leq \delta(G) - 1$, where $\lambda'(G)$ is the restricted edge connectivity of G (which was first proposed by Esfahanian and Hakimi in [2]). More refined bounds are given for regular graphs and Cartesian product graphs. Furthermore, exact value of $S_{\lambda}(G)$ is determined for edge transitive graph.

Although our bounds for $O_K(G)$ and $S_K(G)$ are similar to those for $S_\lambda(G)$ in [7], the derivation is much more complicated. For this purpose, we need the concept of extra connectivity first proposed by Fabrega and Fiol [4,5]. A vertex set S of a connected graph G is an i-extra cut if each component of G-S has order at least i+1. The minimum cardinality of all i-extra cuts (if any) is the i-extra connectivity of G, denoted by $\kappa_i(G)$. An i-extra cut S with $|S| = \kappa_i(G)$ is called a κ_i -cut. In general, $\kappa_i(G)$ does not always exist and the graphs in which $\kappa_i(G)$ exist are said to be κ_i -connected. For a graph G which is not κ_i -connected, we define $\kappa_i(G) = \infty$. By the definition, it is easy to see that $\kappa_i(G)$ is monotone non-decreasing in i, that is, $\kappa_1(G) \leq \kappa_2(G) \leq \kappa_3(G) \leq \cdots$.

In this paper, we show that $\min\{\kappa_1(G) - \delta(G), \delta(G) - 1\}$ $\leqslant O_{\kappa}(G) \leqslant \delta(G) - 1$ and $\min\{\kappa_1(G) - \delta(G) - 1, \delta(G) - 1\} \leqslant S_{\kappa}(G) \leqslant \delta(G) - 1$. Furthermore, when the graph is triangle free, more refined lower bound can be derived for $O_{\kappa}(G)$ in terms of $\kappa_i(G)$.

Next, we introduce some notion which will be used in this paper. For two disjoint vertex sets $U_1, U_2 \subset V(G)$, denote by $[U_1, U_2]_G$ the set of edges of G with one end in U_1 and the other end in U_2 . For a vertex set $U \subseteq V(G)$, G[U] is the subgraph of G induced by U, $\overline{U} = V(G) \setminus U$ is the complement of U, $\omega_G(U) = |[U, \overline{U}]_G|$ is the number of edges between U and \overline{U} , $N_G(U) = \{v \in V(G) \setminus U \mid v \text{ is adjacent with some vertex in } U\}$ is the neighborhood of U, $N_G[U] = N_G(U) \cup U$ is the the closed neighborhood of U. If U has exactly one vertex v, we use $N_G(v)$ instead of $N_G(\{v\})$, etc. The degree of a vertex v in G is $d_G(v) = |N_G(v)|$. When the graph under consideration is obvious, we use N(U), δ , etc. instead of $N_G(U)$, $\delta(G)$, etc.

For more studies on connectivity of graphs, we refer the reader to survey articles by Fàbrega and Fiol [3], Mader [8], Oellermann [9] and Hellwig and Volkmann [6]. For terminology not given here, we refer [1] for references.

2. Bounds for $O_{\kappa}(G)$

For a vertex set $S \subseteq V(G)$, to measure whether G - S is optimal- κ , we need the following necessary and sufficient condition for a graph to be optimal- κ .

Lemma 2.1. A connected graph G is optimal- κ if and only if $|N(X)| \ge \delta(G)$ for any non-empty vertex set X with $V(G) \setminus (X \cup N(X)) \ne \emptyset$.

Proof. In fact, $\kappa(G) = \min\{|N(X)|: X \subset V(G), V(G) \setminus (X \cup N(X)) \neq \emptyset\}$. The lemma follows from the definition of optimal- κ . \square

The following lemma is an easy observation.

Lemma 2.2. Let S, X be two subsets of V(G) with $X \nsubseteq S$. Then $N_G(X) - S \supseteq N_{G-S}(X - S)$. Furthermore, equality holds if $S \cap X = \emptyset$.

If G-S is not optimal- κ , then by Lemma 2.1, there exists a non-empty vertex set $X\subseteq V(G)-S$ such that $|N_{G-S}(X)|<\delta(G-S)$ and $N_{G-S}(X)\cup X\neq V(G-S)$. The next lemma characterizes a special set of such an X.

Lemma 2.3. For a vertex set $S \subseteq V(G)$, suppose X is a non-empty vertex set such that

- (a) $X \subseteq V(G) S$, $|N_{G-S}(X)| < \delta(G S)$, $N_{G-S}(X) \cup X \neq V(G S)$, and
- (b) under the condition of (a), |X| is as small as possible.

Then

- (i) *G*[*X*] is connected;
- (ii) for any component C of G N(X) with |V(C)| < |X|, $V(C) \subseteq S$;
- (iii) $|X| \geqslant 2$;
- (iv) for any $y \in N_{G-S}(X)$, $|N_{G-S}(y) \cap X| \ge 2$.

Proof. (i) Suppose that G[X] is not connected. Let C be a component of G[X]. Then V(C) is a non-empty vertex set of G - S with $N_G(V(C)) \subseteq N_G(X)$. By Lemma 2.2, we have

$$N_{G-S}(V(C)) = N_G(V(C)) - S \subseteq N_G(X) - S$$
$$= N_{G-S}(X). \tag{1}$$

It follows that $|N_{G-S}(V(C))| \le |N_{G-S}(X)| < \delta(G-S)$ and $N_{G-S}(V(C)) \cup V(C) \subseteq N_{G-S}(X) \cup X \ne V(G-S)$. Hence V(C) is a smaller non-empty vertex set satisfying condition (a), contradicting condition (b).

- (ii) The proof is similar to that of (i) by showing that if $V(C) \nsubseteq S$, then $X_1 = V(C) S$ is a smaller non-empty set satisfying condition (a). There are two differences here. The first is that $N_{G-S}(X_1) \subseteq N_G(V(C)) S$ (by Lemma 2.2) is used to replace the first equality of Eq. (1); the second is that the third condition of (a) is satisfied by noting that $X \subseteq V(G-S) (N_{G-S}(X_1) \cup X_1)$ is non-empty.
- (iii) Suppose *X* has only one vertex *x*. Then $|N_{G-S}(X)| = d_{G-S}(x) \geqslant \delta(G-S)$, contradicting condition (a).
- (iv) Suppose there exists a vertex $y \in N_{G-S}(X)$ such that $|N_{G-S}(y) \cap X| = 1$. Suppose x is the only vertex in $N_{G-S}(y) \cap X$. Set $X_1 = X \{x\}$. By (i), we see that $x \in N_G(X_1)$. By Lemma 2.2 and the observation $N_G(X_1) \subseteq N_G(X) \cup \{x\} \{y\}$, we have $|N_{G-S}(X_1)| = |N_G(X_1) S| \le |N_G(X) \cup \{x\} \{y\} S| = |N_G(X) S| = |N_{G-S}(X)| < \delta(G-S)$. Furthermore, $N_{G-S}(X_1) \cup X_1 = (N_G(X_1) S) \cup X_1 \subseteq (N_G(X) \cup \{x\} \{y\} S) \cup (X \{x\}) \subseteq N_{G-S}(X) \cup X \ne V(G-S)$. A contradiction occurs as before. \square

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