

Contents lists available at ScienceDirect

Linear Algebra and its Applications



www.elsevier.com/locate/laa

Diagonal Riccati stability and applications



Alexander Aleksandrov^a, Oliver Mason^{b,c,*}

ARTICLE INFO

Article history: Received 17 February 2015 Accepted 4 November 2015 Available online 21 November 2015 Submitted by V. Mehrmann

MSC: 15A24 93D05

Keywords: Riccati stability Time-delay systems Lotka-Volterra systems

ABSTRACT

We consider the question of diagonal Riccati stability for a pair of real matrices A,B. A necessary and sufficient condition for diagonal Riccati stability is derived and applications of this to two distinct cases are presented. We also describe some motivations for this question arising in the theory of generalised Lotka–Volterra systems.

© 2015 Elsevier Inc. All rights reserved.

1. Introduction and preliminaries

We consider the following problem. Given $A, B \in \mathbb{R}^{n \times n}$, determine conditions for the existence of diagonal positive definite matrices P, Q in $\mathbb{R}^{n \times n}$ such that

$$A^T P + PA + Q + PBQ^{-1}B^T P \prec 0, \tag{1}$$

^a Faculty of Applied Mathematics and Control Processes, Saint Petersburg State University, Saint Petersburg, Russia

Dept. of Mathematics and Statistics/Hamilton Institute, Maynooth University –
National University of Ireland Maynooth, Maynooth, Co. Kildare, Ireland
Lero - the Irish Software Research Centre, Limerick, Ireland

^{*} Corresponding author. Tel.: +353 (0)1 7083672; fax: +353 5(0)1 7083913. E-mail address: oliver.mason@nuim.ie (O. Mason).

where $M \prec 0$ denotes that $M = M^T$ is negative definite. Throughout the paper, $M \succ 0$ $(M \succeq 0)$ denotes that M is positive definite (positive semi-definite); $M \preceq 0$ denotes that M is negative semi-definite.

When diagonal positive definite solutions P, Q of (1) exist, we say that the pair A, B is diagonally Riccati stable.

Our interest in the question stems from the stability of time-delay systems. Specifically, when such a pair P,Q exists, the linear time-delay system associated with A,B admits a Lyapunov–Krasovskii functional of a particularly simple form [8]. The more general question of when positive definite solutions of (1), not necessarily diagonal, exist was highlighted in [17] and some preliminary results on this question were also described in this reference.

We now introduce some notation and terminology, and recall some basic results that will be needed later in the paper.

A matrix A in $\mathbb{R}^{n\times n}$ is Metzler if its off-diagonal elements are nonnegative: formally, $a_{ij} \geq 0$ for $i \neq j$. As is standard, a nonnegative matrix A is one satisfying $a_{ij} \geq 0$ for $1 \leq i, j \leq n$. For vectors v, w in \mathbb{R}^n , $v \geq w$ is understood componentwise and means that $v_i \geq w_i$ for $1 \leq i \leq n$. Similarly, v > w means $v \geq w$, $v \neq w$ and $v \gg w$ means $v_i > w_i$ for $1 \leq i \leq n$. Similar notation is used for matrices of compatible dimensions. In particular, $A \geq 0$, $A \leq 0$ denotes that A is entrywise nonnegative (nonpositive).

For a positive integer n, we denote by $Sym(n,\mathbb{R})$ the space of $n \times n$ real symmetric matrices. For $A \in \mathbb{R}^{n \times n}$, A^T denotes the transpose of A. A matrix $A \in \mathbb{R}^{n \times n}$ is Hurwitz if all of its eigenvalues have negative real parts. It is classical that A is Hurwitz if and only if there exists some $P \succ 0$ with $A^TP + PA \prec 0$.

The following result recalls some well-known facts concerning Metzler matrices [11].

Proposition 1.1. Let $A \in \mathbb{R}^{n \times n}$ be Metzler. The following are equivalent:

- (i) A is Hurwitz;
- (ii) there exists some vector $v \gg 0$ in \mathbb{R}^n with $Av \ll 0$;
- (iii) there exists some positive definite diagonal matrix $D \in \mathbb{R}^{n \times n}$ with $A^TD + DA \prec 0$;
- (iv) for every non-zero $v \in \mathbb{R}^n$, there is some index i with $v_i(Av)_i < 0$;
- (v) $A^{-1} \leq 0$.

The next result concerning the Riccati equation is based on the Schur complement and follows from Theorem 7.7.6 in [10].

Lemma 1.1. Let $A \in \mathbb{R}^{n \times n}$, $B \in \mathbb{R}^{n \times n}$ be given. Then the matrices $P \succ 0$, $Q \succ 0$ in $\mathbb{R}^{n \times n}$ satisfy (1) if and only if:

$$S := \begin{pmatrix} A^T P + PA + Q & PB \\ B^T P & -Q \end{pmatrix} \prec 0.$$
 (2)

Download English Version:

https://daneshyari.com/en/article/4598780

Download Persian Version:

https://daneshyari.com/article/4598780

Daneshyari.com