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# Linear Algebra and its Applications

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# Lie n-derivations of unital algebras with idempotents



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## Yu Wang

Department of Mathematics, Shanghai Normal University, Shanghai 200234, China

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#### ABSTRACT

Let  $\mathcal{A}$  be a unital algebra with nontrivial idempotents. We show that under certain assumptions every Lie *n*-derivation  $\varphi$  on  $\mathcal{A}$  is of the form  $\varphi = d + \delta + \gamma$ , where *d* is a derivation of  $\mathcal{A}$ ,  $\delta$  is both a singular Jordan derivation and an antiderivation of  $\mathcal{A}$ , and  $\gamma$  is a linear map from  $\mathcal{A}$  to its center  $Z(\mathcal{A})$  that vanishes on  $[\cdots [[\mathcal{A}, \mathcal{A}], \mathcal{A}], \ldots, \mathcal{A}]$ . As an application we give a description of Lie *n*-derivations of unital algebras with wide idempotents.

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### 1. Introduction

Throughout the paper, by an algebra we shall mean an algebra over a fixed unital commutative ring R, and we assume without further mentioning that  $\frac{1}{2} \in R$ .

Let  $\mathcal{A}$  be an algebra. Recall that a linear map  $d : \mathcal{A} \to \mathcal{A}$  is called a *derivation* if d(xy) = d(x)y + xd(y) for all  $x, y \in \mathcal{A}$ . Similarly, a linear map  $d : \mathcal{A} \to \mathcal{A}$  is called an *antiderivation* if d(xy) = d(y)x + yd(x) for all  $x, y \in \mathcal{A}$ . Set [x, y] = xy - yx and  $x \circ y = xy + yx$  for  $x, y \in \mathcal{A}$ . A linear map  $d : \mathcal{A} \to \mathcal{A}$  is called *Lie derivation* if

E-mail address: ywang2004@126.com.

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d([x, y]) = [d(x), y] + [x, d(y)] for all  $x, y \in \mathcal{A}$ . Similarly, a linear map  $d : \mathcal{A} \to \mathcal{A}$  is called Jordan derivation if  $d(x \circ y) = d(x) \circ y + x \circ d(y)$  for all  $x, y \in \mathcal{A}$ . Set  $p_1(x) = x$  and

$$p_n(x_1, x_2, \dots, x_n) = [p_{n-1}(x_1, x_2, \dots, x_{n-1}), x_n]$$

for an integer  $n \ge 2$ . Thus,  $p_2(x_1, x_2) = [x_1, x_2], p_3(x_1, x_2, x_3) = [[x_1, x_2], x_3]$ , etc. More generally, a linear map  $\varphi : \mathcal{A} \to \mathcal{A}$  is called a *Lie n-derivation* if

$$\varphi(p_n(x_1, x_2, \dots, x_n)) = \sum_{i=1}^n p_n(x_1, \dots, x_{i-1}, \varphi(x_i), x_{i+1}, \dots, x_n)$$

for all  $x_1, x_2, \ldots, x_n \in \mathcal{A}$ . Lie *n*-derivations were introduced by Abdullaev [1], where the form of Lie *n*-derivations of a certain von Neumann algebra was described. A Lie 3-derivation is said to be a *Lie triple derivation* (see [5] for details).

Lie (triple) derivations on several classes of algebras have been investigated by many authors (see [2,3,7,9–14,16,17]). In most cases it turns out that a Lie (triple) derivation  $\Delta : \mathcal{A} \to \mathcal{A}$  is of the so-called standard form, i.e., the sum  $\Delta = d + \gamma$ , where  $d : \mathcal{A} \to \mathcal{A}$ is a derivation and  $\gamma : \mathcal{A} \to Z(\mathcal{A})$  is a central linear map. In 2012, Benkovič and Eremita [5] gave a sufficient condition for a Lie *n*-derivation on triangular algebras to be of the standard form, which has been generalized to generalized matrix algebras in [18].

We now assume that  $\mathcal{A}$  is an algebra with an idempotent  $e \neq 0, 1$  and let f denote the idempotent 1-e. In this case  $\mathcal{A}$  can be represented in the so-called Peirce decomposition form

$$\mathcal{A} = e\mathcal{A}e + e\mathcal{A}f + f\mathcal{A}e + f\mathcal{A}f,$$

where eAe and fAf are subalgebras with unitary e and f, respectively, eAf is an (eAe, fAf)-bimodule and fAe is an (fAf, eAe)-bimodule. We will assume that A satisfies

$$exe \cdot e\mathcal{A}f = \{0\} = f\mathcal{A}e \cdot exe \quad \text{implies} \quad exe = 0,$$
$$e\mathcal{A}f \cdot fxf = \{0\} = fxf \cdot f\mathcal{A}e \quad \text{implies} \quad fxf = 0 \tag{1}$$

for all  $x \in \mathcal{A}$ . The property (1) was introduced by Benkovič and Širovnik [6]. Some specific examples of unital algebras with nontrivial idempotents having the property (1) are triangular algebras, matrix algebras, and prime algebras with nontrivial idempotents (see [4,6] for details). We remark that generalized matrix algebras can be viewed as special unital algebras with nontrivial idempotents having the property (1) (see [19] for details).

We say that a Jordan derivation  $\delta : \mathcal{A} \to \mathcal{A}$  is a singular Jordan derivation according to the decomposition  $\mathcal{A} = e\mathcal{A}e + e\mathcal{A}f + f\mathcal{A}e + f\mathcal{A}f$ , if

$$\delta(e\mathcal{A}e + f\mathcal{A}f) = 0, \qquad \delta(e\mathcal{A}f) \subseteq f\mathcal{A}e, \qquad \delta(f\mathcal{A}e) \subseteq e\mathcal{A}f.$$

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