# From finite line graphs to infinite derived signed graphs 

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## A R T I C L E I N F O

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## A B S T R A C T

Let $X$ be a subset of $\{ \pm \alpha \pm \beta: \alpha, \beta \in \mathcal{B}$ and $\alpha \neq \beta\}$ where $\mathcal{B}$ is an orthonormal set in an inner product space over $\mathbb{R}$, such that $x \in X \Rightarrow-x \notin X$. Then the signed graph which is defined as described below is called a derived signed graph: its vertex set is $X$; two vertices $x, y$ are joined by a positive (negative) edge when $\langle x, y\rangle$ is positive (negative); when $\langle x, y\rangle=0, x, y$ are not joined. Let $\mathfrak{D}$ denote the family of all derived signed graphs-the order of a member of $\mathfrak{D}$ may be infinite. (The family of all generalized line graphsline graphs belong to this family-is a subfamily of $\mathfrak{D}$.) Let $\mathfrak{M}$ be the class of all minimal nonderivable signed graphs. [ $\mathfrak{M}$ includes the 31 (finite) minimal nongeneralized line graphs computed by various methods in the literature.] In this article, we characterize $\mathfrak{D}$, determine $\mathfrak{M}$ and classify the family of all signed graphs $S$ for which, the following holds: for each finite subset $X$ of $V(S)$, the least eigenvalue of $S[X]$ is at least -2 . The third result substantially generalizes the well known result (Cameron et al. (1976) [1]) on classifying the family of all finite (signed) graphs with least eigenvalues $\geqslant-2$. © 2014 Elsevier Inc. All rights reserved.

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## 1. Preliminaries

For unexplained graph theoretic terms and notation, the reader is referred to [18]. For information on inner product spaces, we rely on [7]. Each graph $G$ considered in this article is simple; its order, denoted by $|G|$, need not be finite. A signed graph is a graph in which each edge is termed as positive or negative; a graph from which a signed graph $S$ has been formed, is called the underlying graph of $S$ and denoted by $S_{u}$. For basic information and various results on the notion of (finite) signed graph, we refer the reader to [19] where this notion is defined in a little more generality: the underlying graph of a signed graph need not be simple. Let $x, y$ be two vertices of a signed graph $S$; to denote that $x$ and $y$ are joined by a positive edge, we write $\langle\langle x, y\rangle\rangle=1$; by writing ' $\langle\langle x, y\rangle\rangle=-1$ ' we mean that they are joined by a negative edge whereas ' $\langle\langle x, y\rangle\rangle=0$ ' implies that they are not adjacent. The signed graph obtained from $S$ by changing the sign of each edge is denoted by $-S$. A signed graph $T$ is called an innergraph of $S$, if $T_{u}$ is an induced subgraph of $S_{u}$ and each edge of $T_{u}$ has the same sign in both signed graphs. To denote that a signed graph $S^{\prime}$ is an innergraph of $S$, we write $S^{\prime} \preccurlyeq S$. If $U \subseteq V(S)$, then the innergraph of $S$ with vertex set $U$ is denoted by $S[U]$. If $X=\left\{x_{1}, x_{2}, \ldots, x_{n}\right\}$ is a subset of $V(S)$, then the innergraph $T$ with vertex set $X$ is denoted by $S\left[x_{1}, x_{2}, \ldots, x_{n}\right]$ also and the product of the values assigned to all edges of $T$ by the function $\langle\langle *, *\rangle\rangle$ is denoted by $\sigma(T)$ or $\sigma\left(x_{1} x_{2} \cdots x_{n}\right)$. A signed graph $T$ is called a triangle (quadrangle) if $T_{u}$ is a cycle of order three (four). Let $T$ be a finite innergraph of $S$; if there is a vertex $p$ in $V(S) \backslash V(T)$ such that $|N(p) \cap V(T)|$ is odd, then $T$ is called odd in $S$; otherwise it is even in $S$. We regard any graph $G$ as a signed graph having only positive edges; i.e., it is 'identified' with the signed graph which has no negative edges and whose underlying graph is $G$.

Normally any term related to graphs is used without any change in its meaning for signed graphs also; however, some terms have to be redefined for signed graphs due to edge-signing; here is one such deviation: The adjacency matrix of a finite signed graph $S$ is obtained from that of its underlying graph by replacing each entry which corresponds to a negative edge by -1 ; i.e., for each $(x, y) \in V(S) \times V(S)$, the entry corresponding to it is $\langle\langle x, y\rangle\rangle$. By an eigenvalue of a finite signed graph, we mean an eigenvalue of its adjacency matrix; since this matrix is real and symmetric, its eigenvalues are real. If $S^{\prime}$ is a finite signed graph and $S^{\prime \prime}$ is an innergraph of $S^{\prime}$, it can be shown that the least eigenvalue of $S^{\prime}$ is not more than that of $S^{\prime \prime}$. (For a proof, see [6, Theorem 9.1.1].) Let $S$ be a signed graph of any order; the infimum of the least eigenvalues of all finite innergraphs of $S$-note that by the preceding fact, when $|S|<\infty$, this infimum coincides with the least eigenvalue of $S$-is defined to be the least eigenvalue of $S$ and denoted by $\lambda(S)$. (For graphs, the notion just defined has been termed in [13] as 'least limiting eigenvalue'.)

A notable property of a finite line graph $G$ is that $\lambda(G) \geqslant-2$. (For a proof, see [6, Lemma 8.6.2]. It is easy to verify that infinite line graphs also have this property.) This fact has prompted many authors to study in detail the family of all finite graphs with least eigenvalues $\geqslant-2$. Hoffman has found an important subfamily of this, whose members are

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