

Contents lists available at SciVerse ScienceDirect

Linear Algebra and its Applications

journal homepage: www.elsevier.com/locate/laa

The finite-step realizability of the joint spectral radius of a pair of $d \times d$ matrices one of which being rank-one^{*}

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ARTICLEINFO

Article history: Received 3 April 2011 Accepted 29 April 2012 Available online 30 May 2012

Submitted by Ludwig Elsner

AMS classification: Primary 15B52 Secondary 15A60 93D20 65F15

Keywords: Joint/generalized spectral radius Rank-one matrix Finiteness property Exponential stability

ABSTRACT

We study the finite-step realizability of the joint/generalized spectral radius of a pair of real square matrices S₁ and S₂, one of which has rank 1, where $2 \le d < +\infty$. Let $\rho(A)$ denote the spectral radius of a square matrix *A*. Then we prove that there always exists a finite-length word $(i_1^*, \ldots, i_m^*) \in \{1, 2\}^m$, for some finite $m \ge 1$, such that

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$$\sqrt[m]{\rho(\mathsf{S}_{i_1^*}\cdots\mathsf{S}_{i_m^*})} = \sup_{n\geq 1} \left\{ \max_{(i_1,\dots,i_n)\in\{1,2\}^n} \sqrt[n]{\rho(\mathsf{S}_{i_1}\cdots\mathsf{S}_{i_n})} \right\}.$$

In other words, there holds the spectral finiteness property for $\{S_1, S_2\}$. Explicit formula for computation of the joint spectral radius is derived. This implies that the stability of the switched system induced by $\{S_1, S_2\}$ is algorithmically decidable in this case. © 2012 Elsevier Inc. All rights reserved.

1. Introduction

Let $S = \{S_1, \ldots, S_K\} \subset \mathbb{R}^{d \times d}$ be an arbitrary finite set of real *d*-by-*d* matrices and $\|\cdot\|$ a matrix norm on the space $\mathbb{R}^{d \times d}$ of all real $d \times d$ matrices, where $2 \le d < +\infty$ and $K \ge 2$. To capture the maximal growth rate of the trajectories generated by random products of matrices S_1, \ldots, S_K in S, in 1960 [38] Rota and Strang introduced an important concept – *joint spectral radius of* S – by

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^{*} This work was supported in part by National Science Foundation of China (Grant Nos. 11071112 and 11071263), PAPD of Jiangsu Higher Education Institutions and in part by NSF 1021203 of the United States.

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$$\hat{\rho}(\boldsymbol{s}) = \lim_{n \to +\infty} \left\{ \max_{(i_1, \dots, i_n) \in \mathbb{K}^n} \sqrt[n]{\|\mathbf{S}_{i_1} \cdots \mathbf{S}_{i_n}\|} \right\}.$$

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Here and in the future

$$\mathbb{K}^n := \overbrace{\{1, \ldots, K\} \times \cdots \times \{1, \ldots, K\}}^{n-\text{times}}$$

stands for the set of all words (i_1, \ldots, i_n) of finite-length *n*, composed of the letters $1, \ldots, K$, for any integer $n \ge 1$. Let

$$\Sigma_{\mathcal{K}}^+ = \{i_{(\boldsymbol{\cdot})} \colon \mathbb{N} \to \mathbb{K}\}, \text{ where } \mathbb{N} = \{1, 2, \dots\}$$

be the set of all the one-sided infinite sequences (also called switching signals of S). We write $i_{(\cdot)}$ as i. for simplicity. Then we see, from Barabanov [1] for example, that $\hat{\rho}(S) < 1$ if and only if

$$\|\mathbf{S}_{i_1}\cdots\mathbf{S}_{i_n}\| \to 0 \text{ as } n \to +\infty \quad \forall i_* \in \Sigma_K^+,$$

In other words, $\hat{\rho}(\mathbf{S}) < 1$ if and only if the linear switched dynamical system, also written as \mathbf{S} ,

$$x_n = x_0 \cdot S_{i_1} \cdots S_{i_n}, \ x_0 \in \mathbb{R}^d, n \ge 1, \text{ and } i_{\cdot} \in \Sigma_K^+,$$

is absolutely asymptotically stable, where the initial state $x_0 \in \mathbb{R}^d$ is an arbitrary given *d*-dimensional row vector. In fact, from [14] there follows

$$\hat{\rho}(\boldsymbol{S}) = \max_{i, \in \Sigma_{K}^{+}} \left\{ \limsup_{n \to +\infty} \sqrt[n]{\|\mathbf{S}_{i_{1}} \cdots \mathbf{S}_{i_{n}}\|} \right\}$$

It is a well-known fact that the joint spectral radius $\hat{\rho}$ plays a critical role in a variety of applications such as switched dynamical systems, differential equations, coding theory, wavelets, combinatorics, and so on; see, for example, [27].

It is easily seen that $\hat{\rho}(\mathbf{S})$ is a nonnegative real number, independent of the norm $\|\cdot\|$ used here. Although $\hat{\rho}(\mathbf{S})$ is independent of the norm $\|\cdot\|$ chosen, its approximation based on the above limit definition does rely upon an explicit choice of the norm $\|\cdot\|$. How to construct an appropriate norm to realize $\hat{\rho}(\mathbf{S})$ has been becoming an important and challenging topic, see e.g. [42]. In many cases, computing $\hat{\rho}$ by definition cannot halt at some finite-time step *n*, as shown by the single matrix system

$$A = \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix}$$

where $\hat{\rho}(A) = \lim_{n \to +\infty} \sqrt[n]{||A^n||} = 1$ by the classical Gel'fand spectral radius formula, however, there holds $\sqrt[n]{||A^n||} > 1$ for all $n \ge 1$. For that reason in part, Daubechies and Lagarias in 1992 [16] defined the equally important concept – generalized spectral radius of **S** – by

$$\rho(\mathbf{S}) = \limsup_{n \to +\infty} \left\{ \max_{(i_1, \dots, i_n) \in \mathbb{K}^n} \sqrt[n]{\rho(\mathsf{S}_{i_1} \cdots \mathsf{S}_{i_n})} \right\},\,$$

where $\rho(A)$ stands for the usual spectral radius for any matrix $A \in \mathbb{R}^{d \times d}$. And they conjectured there that a Gel'fand-type formula should hold for **S**. This was proved by Berger and Wang in 1992 [2], i.e., there holds the following Gel'fand-type formula.

Berger–Wang Formula 1.1. $\rho(S) = \hat{\rho}(S)$, for any bounded subset $S \subset \mathbb{R}^{d \times d}$.

Because of its importance, this Gel'fand-type spectral-radius formula has been reproved by using different interesting approaches, for example, in [17,39,7,5,9,11], in order to gain the inside characteristics of this relationship. According to this formula, the computation of $\rho(\mathbf{S})$ has more flexibility,

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