



ELSEVIER

Available online at www.sciencedirect.com

SCIENCE @ DIRECT®

LINEAR ALGEBRA
AND ITS
APPLICATIONS

Linear Algebra and its Applications 412 (2006) 161–221

www.elsevier.com/locate/laa

Trace-minimal graphs and D-optimal weighing designs

Bernardo M. Ábrego, Silvia Fernández-Merchant,
Michael G. Neubauer, William Watkins *

*Department of Mathematics, California State University—Northridge, Northridge,
CA 91330-8313, United States*

Received 10 May 2004; accepted 20 June 2005

Available online 24 August 2005

Submitted by R.A. Brualdi

Abstract

Let $\mathcal{G}(v, \delta)$ be the set of all δ -regular graphs on v vertices. Certain graphs from among those in $\mathcal{G}(v, \delta)$ with maximum girth have a special property called trace-minimality. In particular, all strongly regular graphs with no triangles and some cages are trace-minimal. These graphs play an important role in the statistical theory of D-optimal weighing designs.

Each weighing design can be associated with a $(0, 1)$ -matrix. Let $M_{m,n}(0, 1)$ denote the set of all $m \times n$ $(0, 1)$ -matrices and let

$$G(m, n) = \max \left\{ \det X^T X : X \in M_{m,n}(0, 1) \right\}.$$

A matrix $X \in M_{m,n}(0, 1)$ is a D-optimal design matrix if $\det X^T X = G(m, n)$. In this paper we exhibit some new formulas for $G(m, n)$ where $n \equiv -1 \pmod{4}$ and m is sufficiently large. These formulas depend on the congruence class of $n \pmod{n}$. More precisely, let $m = nt + r$ where $0 \leq r < n$. For each pair n, r , there is a polynomial $P(n, r, t)$ of degree n in t , which depends only on n, r , such that $G(nt + r, n) = P(n, r, t)$ for all sufficiently large t . The polynomial $P(n, r, t)$ is computed from the characteristic polynomial of the adjacency matrix of a trace-regular graph whose degree of regularity and number of vertices depend only on n and r . We obtain explicit expressions for the polynomial $P(n, r, t)$ for many pairs n, r . In particular we obtain formulas for $G(nt + r, n)$ for $n = 19, 23$, and 27 , all $0 \leq r < n$, and all

* Corresponding author.

E-mail address: bill.watkins@csun.edu (W. Watkins).

sufficiently large t . And we obtain families of formulas for $P(n, r, t)$ from families of trace-minimal graphs including bipartite graphs obtained from finite projective planes, generalized quadrilaterals, and generalized hexagons.

© 2005 Elsevier Inc. All rights reserved.

AMS classification: Primary: 05C50, 62K05; Secondary: 15A36, 05B25, 15A15, 05B20

Keywords: D-optimal weighing design; Trace-minimal graph; Regular graph; Strongly regular graph; Girth; Cages; Generalized polygons

1. Introduction

In [1], the present authors established a relationship between certain regular graphs and D-optimal designs for weighing $n \equiv -1 \pmod{4}$ objects. We now further develop the graph-theoretic concept of trace-minimality and use it to obtain additional results on D-optimality.

1.1. Trace-minimal graphs

Let $\mathcal{G}(v, \delta)$ be the set of all δ -regular graphs on v vertices. We call $\mathcal{G}(v, \delta)$ a *graph class*. Let $A(G)$ be the adjacency matrix of a graph G . The characteristic polynomial of $A(G)$ is denoted by $\text{ch}(G, x)$ and the spectrum of $A(G)$ is denoted by $\text{spec}(A(G))$. We also refer to $\text{ch}(G, x)$ as the characteristic polynomial of the graph G and $\text{spec}(A(G))$ as the spectrum of G . Since $A(G)$ is a symmetric $(0, 1)$ -matrix with zeros on the diagonal and δ ones in each row, $\text{tr } A(G) = 0$ and $\text{tr } A(G)^2 = \delta v$. These traces do not depend on the structure of the graph G . However, for $i \geq 3$, $\text{tr } A(G)^i$ does depend on the structure of the graph. Indeed the (j, j) entry of $A(G)^i$ equals the number of closed walks of length i that start and end at vertex j . For $G \in \mathcal{G}(v, \delta)$ define the *trace sequence* of G by $\text{TR}(G) = (\text{tr } A(G)^3, \text{tr } A(G)^4, \dots, \text{tr } A(G)^n)$.

The trace sequence induces an order relation on the graphs in $\mathcal{G}(v, \delta)$. Let $G, H \in \mathcal{G}(v, \delta)$. We say G is *trace-dominated* by H if $\text{TR}(G)$ is less than or equal to $\text{TR}(H)$ in lexicographic order. In other words, G is trace-dominated by H if either $\text{tr } A(G)^i = \text{tr } A(H)^i$ for all i (in which case $\text{spec}(A(G)) = \text{spec}(A(H))$) or there exists a positive integer $3 \leq k \leq n$ such that $\text{tr } A(G)^i = \text{tr } A(H)^i$, for $i < k$ and $\text{tr } A(G)^k < \text{tr } A(H)^k$. If G is trace-dominated by all graphs in $\mathcal{G}(v, \delta)$, then we say that G is *trace-minimal* in $\mathcal{G}(v, \delta)$. Since $\mathcal{G}(v, \delta)$ is finite, there always exist trace-minimal graphs in $\mathcal{G}(\delta, v)$ and clearly they all have the same characteristic polynomial. Some graph classes $\mathcal{G}(v, \delta)$, contain non-isomorphic graphs, each of which is trace-minimal. However, the smallest example known to us are two non-isomorphic cages in the graph class $\mathcal{G}(70, 3)$. (See Sections 4.5 and 4.4.1.)

In addition to their application to the theory of D-optimal weighing designs, trace-minimal graphs are of independent interest. Indeed many well-known classes of

Download English Version:

<https://daneshyari.com/en/article/4603953>

Download Persian Version:

<https://daneshyari.com/article/4603953>

[Daneshyari.com](https://daneshyari.com)