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ABSTRACT

In this paper we continue our investigation of symmetric tight framelet filter banks (STFFBs) with a minimum number of generators in [6]. In particular, we shall systematically study STFFBs with three high-pass filters which are derived from the oblique extension principle. To our best knowledge, except the papers [1,10], there are no other papers in the literature so far systematically studying this problem. In this paper we show that there are two different types, called type I and type II, of STFFBs with three high-pass filters. Then we provide a detailed analysis and a complete algorithm to obtain all type I STFFBs with three high-pass filters. Our results not only significantly generalize the results in [1,10], but also help us answer several unresolved problems on STFFBs. Based on [6], we also propose an algorithm to construct all type II STFFBs with three high-pass filters supports. Several examples are given to illustrate the results and algorithms in this paper.

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1. Introduction and motivations

Motivated by the interesting papers by Chui and He [1] and Han and Mo [10], continuing our lines developed in [6,8] on symmetric tight framelet filter banks with a minimum number of generators, in this paper we are particularly interested in systematically studying and developing algorithms to construct all symmetric tight framelet filter banks with three high-pass filters and with the shortest possible filter supports.

To proceed further, let us recall some definitions and notation. By $l_0(\mathbb{Z})$ we denote the linear space of all sequences $u = \{u(k)\}_{k \in \mathbb{Z}} : \mathbb{Z} \to \mathbb{C}$ on \mathbb{Z} such that $\{k \in \mathbb{Z} : u(k) \neq 0\}$ is a finite set. For $u = \{u(k)\}_{k \in \mathbb{Z}} \in l_0(\mathbb{Z})$, its *z*-transform is a Laurent polynomial defined to be $u(z) := \sum_{k \in \mathbb{Z}} u(k) z^k$. For a matrix $P(z) = \sum_{k \in \mathbb{Z}} P_k z^k$ of Laurent polynomials, we define $P^*(z) := \sum_{k \in \mathbb{Z}} \overline{P_k}^T z^{-k}$, where $\overline{P_k}^T$ denotes the complex conjugate of the transpose of the matrix P_k .

The oblique extension principle introduced in [2,3] is a general procedure to construct tight wavelet frames through the design of tight framelet filter banks. Let Θ , a, b_1 , ..., $b_s \in l_0(\mathbb{Z})$ with $\Theta^* = \Theta$. We say that $\{a; b_1, \ldots, b_s\}_{\Theta}$ is a tight framelet filter bank if

$$\begin{bmatrix} b_1(z) & \cdots & b_s(z) \\ b_1(-z) & \cdots & b_s(-z) \end{bmatrix} \begin{bmatrix} b_1(z) & \cdots & b_s(z) \\ b_1(-z) & \cdots & b_s(-z) \end{bmatrix}^{\star} = \mathcal{M}_{a,\Theta}(z),$$
(1.1)

where



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$$\mathcal{M}_{a,\Theta}(z) := \begin{bmatrix} \boldsymbol{\Theta}(z) - \boldsymbol{\Theta}(z^2)\mathbf{a}(z)\mathbf{a}^{\star}(z) & -\boldsymbol{\Theta}(z^2)\mathbf{a}(z)\mathbf{a}^{\star}(-z) \\ -\boldsymbol{\Theta}(z^2)\mathbf{a}(-z)\mathbf{a}^{\star}(z) & \boldsymbol{\Theta}(-z) - \boldsymbol{\Theta}(z^2)\mathbf{a}(-z)\mathbf{a}^{\star}(-z) \end{bmatrix}.$$
(1.2)

In particular we write $\{a; b_1, \ldots, b_s\}$ for $\{a; b_1, \ldots, b_s\}_{\delta}$, where δ is the *Dirac sequence* such that $\delta(0) = 1$ and $\delta(k) = 0$ for all $k \in \mathbb{Z} \setminus \{0\}$. Recall that a sequence $u : \mathbb{Z} \to \mathbb{C}$ has symmetry if

$$u(k) = \epsilon u(c-k), \quad \forall k \in \mathbb{Z} \text{ with } \epsilon \in \{-1, 1\}, \ c \in \mathbb{Z}.$$
(1.3)

The filter *u* is symmetric if (1.3) holds with $\epsilon = 1$, and is antisymmetric if (1.3) holds with $\epsilon = -1$.

Note that (1.1) implies $\mathcal{M}_{a,\Theta}^{\star} = \mathcal{M}_{a,\Theta}$, from which we must have $\Theta^{\star} = \Theta$. Consequently, since $\Theta^{\star} = \Theta$, we see that Θ is symmetric if and only if Θ has real coefficients.

Since filters that we consider in this paper are not necessarily real-valued, there is another closely related but different notion of symmetry. We say that u has complex symmetry if

$$u(k) = \epsilon u(c-k), \quad \forall k \in \mathbb{Z} \text{ with } \epsilon \in \{-1, 1\}, \ c \in \mathbb{Z}.$$
(1.4)

Obviously, for a real-valued sequence u, there is no difference between symmetry and complex symmetry.

For a given low-pass filter *a* and a moment correcting filter Θ , to obtain high-pass filters b_1, \ldots, b_s in a tight framelet filter bank, we have to factorize the given matrix $\mathcal{M}_{a,\Theta}$ in (1.2) so that (1.1) holds. To reduce computational complexity in the implementation of a tight framelet filter bank, we often prefer a small number *s* of high-pass filters. If s = 1, then we must have det($\mathcal{M}_{a,\Theta}(z)$) = 0 for all $z \in \mathbb{C} \setminus \{0\}$ which is too restrictive to be satisfied by many filters *a* and Θ . In fact, a tight framelet filter bank $\{a; b_1\}_{\Theta}$ with s = 1 is essentially an orthogonal wavelet filter bank, see [7, Theorem 7]. When s = 2, a necessary and sufficient condition has been given in [6, Theorem 4.2] (also see [8,11] for special cases) in terms of the filters *a* and Θ such that $\{a; b_1, b_2\}_{\Theta}$ is a tight framelet filter bank with [complex] symmetry. Moreover, several algorithms have been proposed in [6,8] to construct tight framelet filter banks $\{a; b_1, b_2\}_{\Theta}$ with [complex] symmetry. However, for any given low-pass filter *a* and a moment correcting filter Θ , the necessary and sufficient condition in [6] is still too restrictive. As a matter of fact, there are only a handful examples of symmetric tight framelet filter banks $\{a; b_1, b_2\}_{\Theta}$ with two high-pass filters known in the literature ([2,3,6,8,11-14] and references therein).

To have more flexibility in constructing tight framelet filter banks with [complex] symmetry from a given low-pass filter a and a moment correcting filter Θ , it is very natural to consider more than two high-pass filters. This naturally leads us to study in this paper symmetric tight framelet filter banks with three high-pass filters. For the particular case s = 3, the perfect reconstruction condition in (1.1) can be rewritten as

$$\boldsymbol{\Theta}(z^2)\mathbf{a}(z)\mathbf{a}^*(z) + \mathbf{b}_1(z)\mathbf{b}_1^*(z) + \mathbf{b}_2(z)\mathbf{b}_2^*(z) + \mathbf{b}_3(z)\mathbf{b}_3^*(z) = \boldsymbol{\Theta}(z)$$
(1.5)

and

$$\Theta(z^2)a(z)a^*(-z) + b_1(z)b_1^*(-z) + b_2(z)b_2^*(-z) + b_3(z)b_3^*(-z) = 0.$$
(1.6)

Currently, there are two particular constructions proposed in [1,10] for designing symmetric tight framelet filter banks $\{a; b_1, b_2, b_3\}_{\Theta}$ with particular choices of moment correcting filters Θ . For the special case $\Theta = \delta$, Chui and He [1] found a simple solution for constructing a real-valued symmetric tight framelet filter bank $\{a; b_1, b_2, b_3\}$. More precisely, for any real-valued low-pass filter *a* having symmetry and satisfying

$$\mathbf{a}(z)\mathbf{a}^{\star}(z) + \mathbf{a}(-z)\mathbf{a}^{\star}(-z) \leqslant 1, \quad \forall z \in \mathbb{T} := \left\{ \zeta \in \mathbb{C} : |\zeta| = 1 \right\},\tag{1.7}$$

define filters b_1 , b_2 , b_3 by (see [1, Proof of Theorem 3])

$$b_1(z) := \left[u(z^2) + z u^{\star}(z^2) \right] / 2, \qquad b_2(z) := \left[u(z^2) - z u^{\star}(z^2) \right] / 2, \qquad b_3(z) := z a^{\star}(-z), \tag{1.8}$$

where u is a Laurent polynomial with real coefficients obtained via the Fejér-Riesz lemma through

$$1 - a(z)a^{*}(z) - a(-z)a^{*}(-z) = u(z^{2})u^{*}(z^{2}).$$
(1.9)

Then it is straightforward to directly check that $\{a; b_1, b_2, b_3\}$ is a real-valued tight framelet filter bank with symmetry. Conversely, if $\{a; b_1, b_2, b_3\}$ is a tight framelet filter bank, then the condition in (1.7) on the filter *a* must hold [1]. Indeed, from the perfect reconstruction condition in (1.1), we must have det($\mathcal{M}_{a,\delta}(z)$) ≥ 0 for all $z \in \mathbb{T}$. Since det($\mathcal{M}_{a,\delta}(z)$) = $1 - a(z)a^*(z) - a(-z)a^*(-z)$, we see that (1.7) must hold.

We now describe the method in [10]. Let *a* be a real-valued low-pass filter with symmetry. Suppose that there exists a Laurent polynomial θ with symmetry and real coefficients such that

$$\boldsymbol{\theta}^{\star}(-z)\boldsymbol{\theta}(z) = \boldsymbol{\theta}^{\star}(z)\boldsymbol{\theta}(-z), \qquad \boldsymbol{\theta}^{\star}(z)\boldsymbol{\theta}(-z) - \boldsymbol{\Theta}\left(z^{2}\right) \ge 0, \quad \forall z \in \mathbb{T},$$

$$(1.10)$$

where

$$\boldsymbol{\Theta}(z) := \boldsymbol{\theta}^{\star}(z) \left[\mathbf{a}(z) \mathbf{a}^{\star}(z) \boldsymbol{\theta}(-z) + \mathbf{a}(-z) \mathbf{a}^{\star}(-z) \boldsymbol{\theta}(z) \right].$$
(1.11)

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