



On the finiteness of uniform sinks

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Abstract

We study the finiteness of uniform sinks for flows. Precisely, we prove that, for $\alpha > 0$ and $T > 0$, if a vector field X has only hyperbolic singularities or sectionally dissipative singularities, then X can have only finitely many (α, T) -uniform sinks. This is a generalized version of a theorem of Liao [4].

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1. Introduction

In this work, we give a generalized version of a theorem of Liao [4]. It could be seen as an extension of the remarkable Pliss' theorem [7] in the setting of singular flows. A natural question of dynamical systems is when we can have the coexistence of infinitely many periodic sinks. Newhouse [6] constructed an example for locally C^2 generic surface diffeomorphisms. On the other hand, under the star condition,³ Pliss [7] proved that one can only have finitely many periodic sinks for diffeomorphisms or non-singular flows. For singular flows, this was known by Liao [4].

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³ This is a weaker condition than structural stability.

Let M be a compact smooth Riemannian manifold and X be a smooth vector field on M . We know that X will generate a smooth flow ϕ_t . If $X(\sigma) = 0$, σ is called a *singularity* of X . If $\phi_t(p) = p$ for some $t > 0$ and $X(p) \neq 0$, p is called a *periodic point*. We use $\text{Sing}(X)$ and $\text{Per}(X)$ to denote the sets of singularities and periodic points.

The flow $\Phi_t = d\phi_t : TM \rightarrow TM$ is called the *tangent flow*. Note that every periodic orbit has at least one zero Lyapunov exponent w.r.t. Φ_t . To understand the dynamics in a small neighborhood of a periodic orbit, Poincaré used the Poincaré return map: for any point in the periodic orbit, one takes a cross section at that point, then the flow defines a local diffeomorphism in a small neighborhood of the cross section. The dynamics of the flow in a small neighborhood of the periodic orbit can be understood by the dynamics of the diffeomorphism.

By extending this idea to the general non-periodic case, for any regular point x and any $t \in \mathbb{R}$, one considers local normal cross sections at x and $\phi_t(x)$, then the flow gives a local diffeomorphism between these two cross sections. Its linearization is the *linear Poincaré flow* ψ_t , which is defined as the following: given a regular point $x \in M$, consider a vector v in the orthogonal complement of $X(x)$, one defines

$$\psi_t(v) = \Phi_t(v) - \frac{\langle \Phi_t(v), X(\phi_t(x)) \rangle}{|X(\phi_t(x))|^2} X(\phi_t(x)).$$

Note that ψ_t cannot be defined on the singularities.

Given $\alpha > 0$ and $T > 0$, a periodic orbit Γ is called an (α, T) -uniform sink if there are $m \in \mathbb{N}$ and times $0 = t_0 < t_1 < t_2 \cdots < t_n = m\pi(\Gamma)$ ($\pi(\Gamma)$ is the period of Γ) satisfying $t_i - t_{i-1} \leq T$ for any $1 \leq i \leq n$ such that for any $x \in \Gamma$, one has

$$\prod_{i=1}^n \|\psi_{t_i - t_{i-1}}(\phi_{t_{i-1}}(x))\| \leq e^{-\alpha m \pi(\Gamma)}.$$

A singularity σ is called *sectionally dissipative* if the following is true: when we list all the eigenvalues of $DX(\sigma)$ as $\{\lambda_1, \lambda_2, \dots, \lambda_d\}$, we have $\text{Re}(\lambda_i) + \text{Re}(\lambda_j) \leq 0$ for any $1 \leq i < j \leq d$. Here d is the dimension of the manifold M .

Notice that for a sectionally dissipative non-hyperbolic singularity, the maximal of the real parts of its eigenvalues should be zero.

Theorem A. *Let $\alpha > 0$, $T > 0$. If a vector field X has only hyperbolic singularities or sectionally dissipative singularities, then X can have only finitely many (α, T) -uniform sinks.*

Similar results for diffeomorphisms or non-singular flows were got by Pliss [7]. If X has no singularities and X has infinitely many (α, T) -uniform sinks $\{\gamma_n\}$, then by using Pliss Lemma, for any γ_n , there is a point $x_n \in \gamma_n$ such that x_n has its stable manifold of uniform size which is independent with n . From the fact that M has finite volume, we can get a contradiction.

Liao [4] proved Theorem A with an additional assumption: X is a *star* vector field.⁴ As X is star, every singularity of X is hyperbolic. If every singularity of X is hyperbolic and X has infinitely many (α, T) -uniform sinks γ_n , then by his estimation, for each n , there is a point

⁴ For proving the finiteness of (α, T) -uniform sinks, Liao didn't use the full strength of the star condition: what he needed are the uniform estimations on sinks.

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