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# Asymptotic stability at infinity for bidimensional Hurwitz vector fields $\stackrel{\text{\tiny{$ؿ$}}}{=}$

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#### ABSTRACT

Let  $X : U \to \mathbb{R}^2$  be a differentiable vector field. Set  $Spc(X) = \{$ eigenvalues of  $DX(z): z \in U \}$ . This X is called Hurwitz if  $Spc(X) \subset \{z \in \mathbb{C}: \Re(z) < 0\}$ . Suppose that X is Hurwitz and  $U \subset \mathbb{R}^2$  is the complement of a compact set. Then by adding to X a constant v one obtains that the infinity is either an attractor or a repellor for X + v. That means: (i) there exists a unbounded sequence of closed curves, pairwise bounding an annulus the boundary of which is transversal to X + v, and (ii) there is a neighborhood of infinity with unbounded trajectories, free of singularities and periodic trajectories of X + v. This result is obtained after to proving the existence of  $\tilde{X} : \mathbb{R}^2 \to \mathbb{R}^2$ , a topological embedding such that  $\tilde{X}$  equals X in the complement of some compact subset of U.

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#### 1. Introduction

A basic example of non-discrete dynamics on the Euclidean space is given by a linear vector field. This linear system is infinitesimally hyperbolic if every eigenvalue has nonzero real part, and it has well-known properties [16,3]. For instance, when the real part of its eigenvalues are negative (Hurwitz matrix), the origin is a global attractor rest point. In the nonlinear case, there has been a great interest in the local study of vector fields around their rest points [6,27,7,28]. However, in order to describe a global phase-portrait, as in [22,25,5,8,9] it is absolutely necessary to study its behavior in a neighborhood of infinity [19].

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The Asymptotic Stability at Infinity has been investigated with a strong influence of [18], where Olech showed a connection between stability and injectivity (see also [10,4,11,26,22]). This problem was also researched in [19,12,14,15,23,1]. In [12], Gutierrez and Teixeira consider  $C^1$ -vector fields  $Y: \mathbb{R}^2 \to \mathbb{R}^2$ , the linearizations of which satisfy (i)  $\det(DY(z)) > 0$  and (ii)  $\operatorname{Trace}(DY(z)) < 0$ in a neighborhood of infinity. By using [9], they prove that if Y has a rest point and the Index  $\mathcal{I}(Y) = \int \text{Trace } (DY) < 0 \text{ (resp. } \mathcal{I}(Y) \ge 0), \text{ then } Y \text{ is topologically equivalent to } z \mapsto -z \text{ that is "the } U$ infinity is a repellor" (resp. to  $z \mapsto z$  that is "the infinity is an attractor"). This Gutierrez-Teixeira's paper was used to obtain the next theorem, where  $Spc(Y) = \{eigenvalues of DY(z): z \in \mathbb{R}^2 \setminus \overline{D}_{\sigma}\}$ , and  $\Re(z)$  is the real part of  $z \in \mathbb{C}$ .

**Theorem 1** (*Gutierrez–Sarmiento*). Let  $Y : \mathbb{R}^2 \setminus \overline{D}_{\sigma} \to \mathbb{R}^2$  be a  $C^1$ -map, where  $\sigma > 0$  and  $\overline{D}_{\sigma} = \{z \in \mathbb{R}^2 \mid z \in \mathbb{R}^2 \mid z \in \mathbb{R}^2\}$  $\mathbb{R}^2$ :  $||z|| \leq \sigma$ }. The following is satisfied:

- (i) If for some  $\varepsilon > 0$ , Spc(Y)  $\cap (-\varepsilon, +\infty) = \emptyset$ . Then there exists  $s \ge \sigma$  such that the restriction Y |:  $\mathbb{R}^2 \setminus \overline{D}_s \to \mathbb{R}^2$  is injective.
- (ii) If for some  $\varepsilon > 0$ , the spectrum Spc(Y) is disjoint of the union  $(-\varepsilon, 0] \cup \{z \in \mathbb{C}: \Re(z) \ge 0\}$ . Then there exist  $p_0 \in \mathbb{R}^2$  such that the point  $\infty$  of the Riemann Sphere  $\mathbb{R}^2 \cup \{\infty\}$  is either an attractor or a repellor of  $z' = Y(z) + p_0$ .

Theorem 1, given in [14], has been extended to differentiable maps  $X : \mathbb{R}^2 \setminus \overline{D}_{\sigma} \to \mathbb{R}^2$  in [13,15]. In both papers the eigenvalues also avoid a real open neighborhood of zero. In [23], the author examine the intrinsic relation between the asymptotic behavior of Spc(X) and the global injectivity of the local diffeomorphism given by *X*. He uses  $Y_{\theta} = R_{\theta} \circ Y \circ R_{-\theta}$ , where  $R_{\theta}$  is the linear rotation of angle  $\theta \in \mathbb{R}$ , and (motivated by [11]) introduces the so-called *B*-condition [24,26], which claims:

for each  $\theta \in \mathbb{R}$ , there does not exist a sequence  $(x_k, y_k) \in \mathbb{R}^2$  with  $x_k \to +\infty$  such that  $Y_{\theta}((x_k, y_k)) \to \infty$  $p \in \mathbb{R}^2$  and  $DY_{\theta}(x_k, y_k)$  has a real eigenvalue  $\lambda_k$  satisfying  $x_k \lambda_k \to 0$ .

By using this, [23] improves the differentiable version of Theorem 1. In the present paper we prove that the condition

$$\operatorname{Spc}(X) \subset \{z \in \mathbb{C}: \Re(z) < 0\}$$

is enough in order to obtain Theorem 1 for differentiable vector fields  $X : \mathbb{R}^2 \setminus \overline{D}_{\sigma} \to \mathbb{R}^2$ .

Throughout this paper,  $\mathbb{R}^2$  is embedded in the Riemann Sphere  $\mathbb{R}^2 \cup \{\infty\}$ . Thus  $(\mathbb{R}^2 \setminus \overline{D}_{\sigma}) \cup \{\infty\}$  is the subspace of  $\mathbb{R}^2 \cup \{\infty\}$  with the induced topology, and 'infinity' refers to the point  $\infty$  of  $\mathbb{R}^2 \cup \{\infty\}$ . Moreover given  $C \subset \mathbb{R}^2$ , a closed (compact, no boundary) curve (1-manifold),  $\overline{D}(C)$  (respectively D(C)) is the compact disc (respectively open disc) bounded by C. Thus, the boundaries  $\partial \overline{D}(C)$  and  $\partial D(C)$ are equal to *C*, homeomorphic to  $\partial D_1 = \{z \in \mathbb{R}^2 : ||z|| = 1\}$ .

#### 2. Statement of the results

For every  $\sigma > 0$  let  $\overline{D}_{\sigma} = \{z \in \mathbb{R}^2 : ||z|| \leq \sigma\}$ . Outside this compact disk we consider a differentiable vector field  $X: \mathbb{R}^2 \setminus \overline{D}_{\sigma} \to \mathbb{R}^2$ . As usual, a trajectory of X starting at  $q \in \mathbb{R}^2 \setminus \overline{D}_{\sigma}$  is defined as the integral curve determined by a maximal solution of the Initial Value Problem  $\dot{z} = X(z), z(0) = q$ . This is a curve  $I_q \ni t \mapsto \gamma_q(t) = (x(t), y(t))$ , satisfying:

- *t* varies on some open real interval containing the zero, the image of which  $\gamma_q(0) = q$ ;
- $\gamma_q(t) \in \mathbb{R}^2 \setminus \overline{D}_\sigma$  and there exist the real derivatives  $\frac{dx}{dt}(t)$ ,  $\frac{dy}{dt}(t)$ ;
- $\dot{\gamma}_q(t) = (\frac{dx}{dt}(t), \frac{dy}{dt}(t))$ , the velocity vector field of  $\gamma_q$  at  $\gamma_q(t)$  equals  $X(\gamma_q(t))$ , and  $I_q \subset \mathbb{R}$  is the maximal interval of definition.

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