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An analogue to a result of Takahashi $\stackrel{\scriptscriptstyle \leftrightarrow}{\approx}$

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A R T I C L E I N F O

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ABSTRACT

In this paper we completely answer the following question: for given $A \in \mathcal{B}(\mathcal{H}, \mathcal{K})$, $C \in \mathcal{B}(\mathcal{L}, \mathcal{K})$ does there exist $X \in \mathcal{B}(\mathcal{H}, \mathcal{L})$ such that A + CX is injective? As an application of the obtained results, for given operators $A \in \mathcal{B}(\mathcal{H})$, $B \in \mathcal{B}(\mathcal{K})$ and $C \in \mathcal{B}(\mathcal{K}, \mathcal{H})$, separate necessary conditions and sufficient conditions on the triple (A, B, C) for the existence of an operator X such that the 2 × 2 operator matrix $M_X = \begin{bmatrix} A & C \\ X & B \end{bmatrix}$ is injective are presented.

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1. Motivation

Let \mathcal{H}, \mathcal{K} be separable Hilbert spaces and let $\mathcal{B}(\mathcal{H}, \mathcal{K})$ denote the set of all bounded linear operators from \mathcal{H} to \mathcal{K} . For simplicity, we also write $\mathcal{B}(\mathcal{H}, \mathcal{H})$ as $\mathcal{B}(\mathcal{H})$. If $A \in \mathcal{B}(\mathcal{H}), B \in \mathcal{B}(\mathcal{K})$ and $C \in \mathcal{B}(\mathcal{K}, \mathcal{H})$ are fixed, by M_X we denote the operator in $\mathcal{B}(\mathcal{H} \oplus \mathcal{K})$ given by

$$M_X = \begin{bmatrix} A & C \\ X & B \end{bmatrix} : \begin{bmatrix} \mathcal{H} \\ \mathcal{K} \end{bmatrix} \to \begin{bmatrix} \mathcal{H} \\ \mathcal{K} \end{bmatrix},$$

which depends on $X \in \mathcal{B}(\mathcal{H}, \mathcal{K})$.

Completion of partially given operator matrices to operators of fixed prescribed type is an extensively studied area of operator theory, which is a topic of many various currently undergoing investigations.

As for completions of the operator matrices of the above given form M_X , the first to ever address any kind of questions (for separable Hilbert spaces not necessarily of finite dimension) related to it was Takahashi. More specifically, in his paper [14] he gave necessary and sufficient conditions for the existence of $X \in \mathcal{B}(\mathcal{H})$ such that M_X is invertible.

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The key result obtained in [14] that allowed for him to completely solve the problem of completion of M_X to invertibility was the one that characterizes the pairs of operators (A, C) for which the operator A + CX is invertible for some $X \in \mathcal{B}(\mathcal{H}, \mathcal{K})$, which is a result also of interest in connection with the spectrum assignment problem in systems theory.

Although Takahashi's paper was published in '95 there have only been several papers since, namely [3, 8,9,13,17,18], which deal with various completions of the operator matrix of the form M_X . Actually in [17] exactly the same problem as in [14] was considered but using methods of geometrical structure of operators and in it some necessary and sufficient conditions were given different than those from [14]. Of all the cited papers the only one that addresses completion to injectivity is [3], and it does it under the special assumption that the operator C is with closed range. So, the problem of completing the operator matrix M_X to injectivity is still open.

In attempt to answer this open question, we have run into a similar problem as Takahashi did. More precisely, instead of the question of existence of an operator X for which A + CX is invertible, we have faced ourselves with the following one: given $A \in \mathcal{B}(\mathcal{H}, \mathcal{K}), C \in \mathcal{B}(\mathcal{L}, \mathcal{K})$ does there exist an operator $X \in \mathcal{B}(\mathcal{H}, \mathcal{L})$ such that A + CX is injective?

In this paper we completely answer the above question. As an application of the obtained results we partially solve the problem of completion of the operator matrix M_X to injectivity.

2. Notation and preliminaries

All Hilbert spaces under consideration are assumed to be separable.

For subspaces \mathcal{X} and \mathcal{Y} of \mathcal{H} with $\mathcal{X} \subseteq \mathcal{Y}$, we set $\operatorname{codim}_{\mathcal{Y}} \mathcal{X} = \dim \mathcal{Y}/\mathcal{X}$ and, if \mathcal{X} is closed, use the symbol $P_{\mathcal{X}}$ to denote the orthogonal projection onto \mathcal{X} . For a set M by 1_M we denote the identity function on M; we write simply 1 if M is understood. For a given operator $A \in \mathcal{B}(\mathcal{H}, \mathcal{K})$, the symbols $\mathcal{N}(A)$ and $\mathcal{R}(A)$ denote the null space and the range of A, respectively. We use the standard notation $n(A) = \dim \mathcal{N}(A)$, $\beta(A) = \operatorname{codim}_{\mathcal{R}}(A)$ and $d(A) = \dim \mathcal{R}(A)^{\perp}$. As usual, $\sigma(A) = \{\lambda \in \mathbb{C} : A - \lambda \text{ is not invertible}\}$ is the spectrum of A, $\sigma_p(A) = \{\lambda \in \mathbb{C} : \mathcal{N}(\lambda - A) \neq \{0\}\}$ is the point spectrum of A and $\sigma_e(A) = \{\lambda \in \mathbb{C} : A - \lambda \text{ is not invertible}\}$ is the essential spectrum of A. Analogously, left (right) spectrum and left (right) essential spectrum of A can be defined.

If $A \in \mathcal{B}(\mathcal{K}, \mathcal{H})$ and \mathcal{M} is a subspace of \mathcal{K} then the restriction of operator A to the subspace \mathcal{M} will be denoted by $A|_{\mathcal{M}}$.

By an *operator range* we shall mean a subspace $\mathcal{K} \subseteq \mathcal{H}$ of a separable Hilbert space \mathcal{H} such that $\mathcal{R}(A) = \mathcal{K}$ for some separable Hilbert space \mathcal{H}_0 and some $A \in \mathcal{B}(\mathcal{H}_0, \mathcal{H})$.

In the lemma below we collect a few basic facts about operator ranges that will be used in the paper without any explicit mention.

Lemma 2.1. (i) If $L \subseteq \mathcal{H}$ is an operator range and $A \in \mathcal{B}(\mathcal{H}_1, \mathcal{H})$, then A[L] is an operator range as well.

(ii) If $L_1, L_2 \subseteq \mathcal{H}$ are operator ranges then $L_1 + L_2$ is an operator range as well.

- (iii) If $L_1, L_2 \subseteq \mathcal{H}$ are operator ranges then $L_1 \cap L_2$ is an operator range as well.
- (iv) If $L \subseteq \mathcal{H}$ is an operator range and $A \in \mathcal{B}(\mathcal{H}_1, \mathcal{H})$, then $A^{-1}[L]$ is an operator range as well.

Proof. (i) is immediate from the definition and (ii) and (iii) are proved e.g. in [4].

To prove (iv) let $B \in \mathcal{B}(\mathcal{H}_2, \mathcal{H})$ be such that $L = \mathcal{R}(B)$. Consider the operators $A_1 \in \mathcal{B}(\mathcal{H}_1, \mathcal{H}_1 \oplus \mathcal{H})$ and $B_1 \in \mathcal{B}(\mathcal{H}_1 \oplus \mathcal{H}_2, \mathcal{H}_1 \oplus \mathcal{H})$ given by

$$A_1 = \begin{bmatrix} 1\\ A \end{bmatrix} : \mathcal{H}_1 \to \begin{bmatrix} \mathcal{H}_1\\ \mathcal{H} \end{bmatrix} \quad \text{and} \quad B_1 = \begin{bmatrix} 1 & 0\\ 0 & B \end{bmatrix} : \begin{bmatrix} \mathcal{H}_1\\ \mathcal{H}_2 \end{bmatrix} \to \begin{bmatrix} \mathcal{H}_1\\ \mathcal{H} \end{bmatrix}$$

and let $P_1 \in \mathcal{B}(\mathcal{H}_1 \oplus \mathcal{H}, \mathcal{H}_1)$ be the orthogonal projection onto \mathcal{H}_1 . From

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