Contents lists available at ScienceDirect

Journal of Mathematical Analysis and Applications

www.elsevier.com/locate/jmaa

## Continuous and localized Riesz bases for $L^2$ spaces defined by Muckenhoupt weights

Hugo Aimar<sup>a</sup>, Wilfredo A. Ramos<sup>b,c,\*</sup>

 <sup>a</sup> Instituto de Matemática Aplicada del Litoral, IMAL (UNL-CONICET), CCT CONICET Santa Fe, Predio "Dr. Alberto Cassano", Colectora Ruta Nac. 168, Paraje El Pozo, 3000 Santa Fe, Argentina
<sup>b</sup> Instituto de Matemática Aplicada del Litoral, IMAL (UNL-CONICET), Argentina
<sup>c</sup> Departamento de Matemática, Facultad de Ciencias Exactas Naturales y Agrimensura, Universidad Nacional del Nordeste, Argentina

## A R T I C L E I N F O

Article history: Received 14 January 2015 Available online 6 May 2015 Submitted by R.H. Torres

Keywords: Riesz bases Haar wavelets Basis perturbations Muckenhoupt weights Cotlar's Lemma

## ABSTRACT

Let w be an  $A_{\infty}$ -Muckenhoupt weight in  $\mathbb{R}$ . Let  $L^2(wdx)$  denote the space of square integrable real functions with the measure w(x)dx and the weighted scalar product  $\langle f,g \rangle_w = \int_{\mathbb{R}} fg \ wdx$ . By regularization of an unbalanced Haar system in  $L^2(wdx)$  we construct absolutely continuous Riesz bases with supports as close to the dyadic intervals as desired. Also the Riesz bounds can be chosen as close to 1 as desired. The main tool used in the proof is Cotlar's Lemma.

© 2015 Elsevier Inc. All rights reserved.

## 1. Introduction and statement of the main result

A sequence  $\{f_k, k \in \mathbb{Z}\}$  in a Hilbert space H is said to be a Bessel sequence with bound B if the inequality

$$\sum_{k \in \mathbb{Z}} \left| \langle f, f_k \rangle \right|^2 \le B \left\| f \right\|_H^2$$

holds for every  $f \in H$ . If  $\{f_k, k \in \mathbb{Z}\}$  is a Bessel sequence with bound B and  $\{e_k, k \in \mathbb{Z}\}$  is an orthonormal basis for the separable Hilbert space H, then the operator T on H defined by

$$Tf := \sum_{k \in \mathbb{Z}} \langle f, f_k \rangle e_k$$

is bounded on H with bound  $\sqrt{B}$ . Conversely if T is bounded on H, then  $\{f_k, k \in \mathbb{Z}\}$  is a Bessel sequence with bound  $||T||^2$ .

\* Corresponding author.

 $\label{eq:http://dx.doi.org/10.1016/j.jmaa.2015.05.003 \\ 0022-247X/ © 2015 Elsevier Inc. All rights reserved.$ 







E-mail addresses: haimar@santafe-conicet.gov.ar (H. Aimar), wramos@santafe-conicet.gov.ar (W.A. Ramos).

When  $\{f_k, k \in \mathbb{Z}\}$  itself is an orthonormal basis and  $e_k = f_k$ , T is the identity. Of particular interest is the case of  $H = L^2$  when the Bessel system and the orthonormal basis are built on scaling and translations of the underlying space. In such cases the operator T has a natural decomposition as  $T = \sum_{j \in \mathbb{Z}} T_j$ . Sometimes the orthonormal basis can be chosen in such a way that the  $T_j$ 's become almost orthogonal in the sense of Cotlar. We aim to use Cotlar's Lemma to produce smooth and localized Riesz bases for  $L^2(\mathbb{R}, wdx)$  when w is a Muckenhoupt weight.

To introduce the problem let us start by some simple illustrations. Let  $\psi$  be a Daubechies compactly supported wavelet in  $\mathbb{R}$ . Assume that  $\operatorname{supp} \psi \subset [-N, N]$ . The system  $\{\tilde{\psi}_k^j(x) = 2^{\frac{j}{2}}\psi(2^jx^3 - k) : j, k \in \mathbb{Z}\}$ is a compactly supported orthonormal basis for  $L^2(\mathbb{R}, 3x^2dx)$ . More generally if w(x) is a non-negative locally integrable function in  $\mathbb{R}$  and  $W(x) = \int_0^x w(y)dy$ , then the system  $\overline{\psi}_k^j(x) = 2^{\frac{j}{2}}\psi(2^jW(x) - k)$  is an orthonormal basis for  $L^2(wdx)$ . In fact, changing variables

$$\begin{split} \int_{\mathbb{R}} \overline{\psi}_k^j(x) \overline{\psi}_m^l(x) w(x) dx &= 2^{\frac{l+j}{2}} \int_{\mathbb{R}} \psi(2^j W(x) - k) \psi(2^l W(x) - m) w(x) dx \\ &= \int_{\mathbb{R}} \psi_k^j(z) \psi_m^l(z) dz \end{split}$$

and we have the orthonormality of the system  $\{\overline{\psi}_k^j : j \in \mathbb{Z}, k \in \mathbb{Z}\}$  in  $L^2(\mathbb{R}, wdx)$ . As it is easy to verify in the case of  $w(x) = 3x^2$ , for j fixed the length of the supports of  $\overline{\psi}_k^j$  tend to zero as  $|k| \to +\infty$ . On the other hand for k = 0 the scaling parameter is  $2^{-\frac{1}{3}}$ .

Notice also that if w is bounded above and below by positive constants the sequence  $\overline{\psi}_k^j$  is an orthonormal basis for  $L^2(wdx)$  with a metric control on the sizes of the supports provided by the scale.

A Riesz basis in  $L^2(wdx)$  is a Schauder basis  $\{f_k\}$  such that there exist two constants A and B called the Riesz bounds of  $\{f_k\}$  for which

$$A\sum |c_k|^2 \le \left\|\sum c_k f_k\right\|_{L^2(wdx)}^2 \le B\sum |c_k|^2$$

for every  $\{c_k\}$  in  $l^2(\mathbb{R})$ , the space of square summable sequences of real numbers. In this note we aim to give sufficient conditions on a weight w defined on  $\mathbb{R}$  more general than  $0 < c_1 \leq w(x) \leq c_2 < \infty$ , in order to construct, for every  $\delta > 0$ , a system  $\Psi = \{\psi_I(x), I \in \mathcal{D}\}$  ( $\mathcal{D}$  are the dyadic intervals in  $\mathbb{R}$ ) with the following properties,

- (i)  $\Psi$  is a Riesz basis for  $L^2(wdx)$  with bounds  $(1 \delta)$  and  $(1 + \delta)$ ,
- (ii) each  $\psi_k^j$  is absolutely continuous,
- (iii) for each I,  $\psi_I$  is supported on a neighborhood  $I^{\epsilon}$  of I such that

$$0 < \frac{|I^{\epsilon}|}{|I|} - 1 < \delta.$$

As we have shown in the above example with  $w(x) = 3x^2$ , we have that  $\{\overline{\psi}_k^j\}$  satisfies (i) and (ii) but not (iii).

An orthonormal basis in  $L^2(\mathbb{R}, wdx)$  satisfying (iii) but not (ii) when w is locally integrable is the following unbalanced version of the Haar system (see [12]). Let  $\mathcal{D} = \bigcup_{j \in \mathbb{Z}} \mathcal{D}^j$  be the family of standard dyadic intervals in  $\mathbb{R}$ . Each I in  $\mathcal{D}^j$  takes the form  $I = [k2^{-j}, (k+1)2^{-j})$  for same integer k. For  $I \in \mathcal{D}^j$  we have that  $|I| = 2^{-j}$ . We shall frequently use  $a_I$  and  $b_I$  to denote the left and right points of I respectively, for each  $I \in \mathcal{D}$ , define Download English Version:

https://daneshyari.com/en/article/4614991

Download Persian Version:

https://daneshyari.com/article/4614991

Daneshyari.com