



Periodic second order superlinear Hamiltonian systems



Martin Schechter

Department of Mathematics, University of California, Irvine, CA 92697-3875, USA

ARTICLE INFO

Article history:

Received 1 May 2014
Available online 28 January 2015
Submitted by P.J. McKenna

Keywords:

Critical points
Linking
Dynamical systems
Periodic solutions

ABSTRACT

We consider periodic solutions for superlinear second order non-autonomous dynamical systems including both kinetic and potential terms. We study the existence of nontrivial and ground state solutions.

© 2015 Published by Elsevier Inc.

1. Introduction

We consider the following problem. One wishes to solve

$$-\ddot{x}(t) = B(t)x(t) + \nabla_x V(t, x(t)), \tag{1}$$

where

$$x(t) = (x_1(t), \dots, x_n(t)) \tag{2}$$

is a map from $I = [0, T]$ to \mathbb{R}^n such that each component $x_j(t)$ is a periodic function in H^1 with period T , and the function $V(t, x) = V(t, x_1, \dots, x_n)$ is continuous from \mathbb{R}^{n+1} to \mathbb{R} , continuously differentiable with respect to the x_j with

$$\nabla_x V(t, x) = (\partial V / \partial x_1, \dots, \partial V / \partial x_n) \in C(\mathbb{R}^{n+1}, \mathbb{R}^n). \tag{3}$$

For each $x \in \mathbb{R}^n$, the function $V(t, x)$ is periodic in t with period T .

We shall study this problem under several sets of assumptions. The elements of the symmetric matrix $B(t)$ are to be real-valued functions $b_{jk}(t) = b_{kj}(t)$. Our assumption on $B(t)$ is:

E-mail address: mschecht@math.uci.edu.

(B1) Each component of $B(t)$ is an integrable function on I , i.e., for each j and k , $b_{jk}(t) \in L^1(I)$.

This assumption implies that there is an extension \mathcal{D} of the operator

$$\mathcal{D}_0x = -\ddot{x}(t) - B(t)x(t)$$

having a discrete, countable spectrum consisting of isolated eigenvalues of finite multiplicity with a finite lower bound $-L$

$$-\infty < -L \leq \lambda_0 < \lambda_1 < \lambda_2 < \dots < \lambda_l < \dots \tag{4}$$

Let λ_l be the first positive eigenvalue of \mathcal{D} . We allow $\lambda_{l-1} = 0$. Let H be the set of vector functions $x(t)$ described above. It is a Hilbert space with norm satisfying

$$\|x\|_H^2 = \sum_{j=1}^n \|x_j\|_{H^1}^2.$$

We also write

$$\|x\|^2 = \sum_{j=1}^n \|x_j\|^2,$$

where $\|\cdot\|$ is the $L^2(I)$ norm. Define the subspaces M and N of H as,

$$N = \bigoplus_{k < l} E(\lambda_k), \quad M = N^\perp, \quad H = M \oplus N,$$

where $E(\lambda_k)$ is the eigenspace of λ_k . Let

$$G(x) = d(x) - 2 \int_I V(t, x) dt, \tag{5}$$

where $d(x) = (\mathcal{D}x, x)$ (cf. the next section). Let

$$x(t) = w(t) + v(t), \quad w(t) \in M, \quad v(t) \in N.$$

We write

$$G_\lambda(x) = \lambda d(w) + d(v) - 2 \int_I V(t, x) dt, \quad 0 < \lambda < \infty. \tag{6}$$

We let \mathcal{D}_λ be the operator corresponding to $d_\lambda(x) = \lambda d(w) + d(v)$. We have

Theorem 1.1. *Assume*

1.

$$2V(t, x) \geq \lambda_{l-1}|x|^2, \quad t \in I, \quad x \in \mathbb{R}^n.$$

2.

$$V(t, x)/|x|^2 \rightarrow \infty, \quad \text{as } |x| \rightarrow \infty.$$

Download English Version:

<https://daneshyari.com/en/article/4615515>

Download Persian Version:

<https://daneshyari.com/article/4615515>

[Daneshyari.com](https://daneshyari.com)