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Bounds for α -optimal partitioning of a measurable space based on several efficient partitions



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ABSTRACT

We provide a two-sided inequality for the α -optimal partition value of a measurable space according to a finite number of nonatomic finite measures. The result extends and often improves Legut [Inequalities for α -optimal partitioning of a measurable space, Proc. Amer. Math. Soc. 104 (1988)] since the bounds are obtained considering several partitions that maximize the weighted sum of the partition values with varying weights, instead of a single one. Furthermore, we show conditions that make these bounds sharper.

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1. Introduction

Let (C, \mathcal{C}) be a measurable space, μ_1, \ldots, μ_n be *n* nonatomic finite measures defined on the same σ -algebra \mathcal{C} , and let \mathscr{P} be the set of all measurable partitions (A_1, \ldots, A_n) of C $(A_i \in \mathcal{C} \text{ for all } i = 1, \ldots, n, \bigcup_{i=1}^n A_i = C, A_i \cap A_j = \emptyset$ for all $i \neq j$). Let Δ_{n-1} denote the (n-1)-dimensional simplex. For this definition, and the many others taken from convex analysis, we refer to [9].

Definition 1. A partition $(A_1^*, \ldots, A_n^*) \in \mathscr{P}$ is said to be α -optimal, for $\boldsymbol{\alpha} = (\alpha_1, \ldots, \alpha_n)^T \in \operatorname{ri} \Delta_{n-1}$, the relative interior of Δ_{n-1} , if

$$v^{\alpha} := \min_{i=1,\dots,n} \left\{ \frac{\mu_i(A_i^*)}{\alpha_i} \right\} = \sup \left\{ \min_{i=1,\dots,n} \left\{ \frac{\mu_i(A_i)}{\alpha_i} \right\} : (A_1,\dots,A_n) \in \mathscr{P} \right\}.$$
(1)

This problem has a consolidated interpretation in mathematical economics. We adopt the model considered in Dubins and Spanier [6]. C is a non-homogeneous, infinitely divisible good to be distributed

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among *n* agents with idiosyncratic preferences, represented by the measures. A partition $(A_1, \ldots, A_n) \in \mathscr{P}$ describes a possible division of the good, with portion A_i (not necessarily connected) given to agent *i*. A satisfactory compromise between the conflicting interests of the agents, each having a relative claim α_i , $i = 1, \ldots, n$, over the cake, is given by the α -optimal partition. It can be shown that the proposed solution coincides with the Kalai–Smorodinsky solution for bargaining problems (see Kalai and Smorodinsky [11] and Kalai [10]). When $\{\mu_i\}_{i=1,\ldots,n}$ are all probability measures, i.e. $\mu_i(C) = 1$ for all $i = 1, \ldots, n$, the claim vector $\boldsymbol{\alpha} = (1/n, \ldots, 1/n)^T$ describes a situation of perfect parity among agents. The necessity to consider finite measures stems from game theoretic extensions of the models. For such extensions we refer to Legut [13], Legut et al. [14] and Dall'Aglio et al. [4].

When all the μ_i are probability measures, Dubins and Spanier [6] showed that if $\mu_i \neq \mu_j$ for some $i \neq j$, then $v^{\alpha} > 1$. This bound was improved, together with the definition of an upper bound by Elton et al. [8]. A further improvement for the lower bound was given by Legut [12]. More recently, Legut and Wilczyńsky [16] gave an explicit formula for the value of v^{α} (and of the corresponding optimal partition) for the case n = 2, based on the Neyman–Pearson lemma.

The aim of the present work is twofold: We provide further refinements for Legut's bounds for any n, and we show conditions that make these bounds sharper. We consider here the same geometrical setting employed by Legut [12], i.e. the partition range, also known as Individual Pieces Set (IPS) (see Barbanel [2] for a thorough review of its properties), defined as

$$\mathcal{R} := \left\{ \left(\mu_1(A_1), \dots, \mu_n(A_n) \right) : (A_1, \dots, A_n) \in \mathscr{P} \right\} \subset \mathbb{R}^n_+.$$

Let us consider some of its features. The set \mathcal{R} is compact and convex (see Dvoretzky et al. [7]). The supremum in (1) is therefore attained. Moreover, as shown by Legut and Wilczyńsky [15],

$$v^{\alpha} = \max\{r \in \mathbb{R}_{+} : (r\alpha_{1}, r\alpha_{2}, \dots, r\alpha_{n})^{T} \cap \mathcal{R} \neq \emptyset\}.$$
(2)

So, the vector $(v^{\alpha}\alpha_1, \ldots, v^{\alpha}\alpha_n)^T$ is the intersection between the Pareto frontier of \mathcal{R} and the ray $r\boldsymbol{\alpha} = \{(r\alpha_1, \ldots, r\alpha_n)^T : r \geq 0\}.$

To find both bounds, Legut locates the solution of the maxsum problem $\sup\{\sum_{i=1}^{n} \mu_i(A_i) : (A_1, \dots, A_n) \in \mathscr{P}\}$ on the partition range. Then, he finds the convex hull of this point with the corner points of the partition range to find a lower bound, and uses a separating hyperplane argument to find the upper bound. We keep the same framework, but consider the solutions of several maxsum problems with weighted coordinates to find better approximations. Fix $\boldsymbol{\beta} = (\beta_1, \dots, \beta_n)^T \in \Delta_{n-1}$ and consider

$$\sum_{i=1}^{n} \beta_i \mu_i \left(A_i^{\beta} \right) = \sup \left\{ \sum_{i=1}^{n} \beta_i \mu_i (A_i) : (A_1, \dots, A_n) \in \mathscr{P} \right\}.$$
(3)

Let η be a non-negative finite-valued measure with respect to which each μ_i is absolutely continuous (for instance we may consider $\eta = \sum_{i=1}^{n} \mu_i$). Then, by the Radon–Nikodym theorem, for each $A \in \mathcal{C}$,

$$\mu_i(A) = \int_A f_i d\eta \quad \forall i = 1, \dots, n,$$

where f_i is the Radon–Nikodym derivative of μ_i with respect to η .

Finding a solution for (3) is straightforward:

Proposition 1. (See [6, Theorem 2], [1, Theorem 2], [3, Proposition 4.3].) Let $\beta \in \Delta_{n-1}$ and let $B^{\beta} = (A_1^{\beta}, \ldots, A_n^{\beta})$ be a partition of C. If

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