

Global attractivity of a positive periodic solution for a nonautonomous stage structured population dynamics with time delay and diffusion [☆]

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Abstract

By employing the continuation theorem of coincidence degree theory, the existence of a positive periodic solution for a nonautonomous stage structured population dynamics with time delay and diffusion is established. Further, by constructing a Lyapunov functional and using the result of the existence of positive periodic solution, the attractivity of a positive periodic solution for above system is obtained.

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1. Introduction

In the study of the population dynamics, in order to make the population models more practical and accurate, more and more realistic factors have been considered, such as stage-structure (see [1–4,12,13]), diffusion (see [2,5–7,13]), time delay (see [1,5–7,10,11]), but the models with all the factors seem to be rarely considered.

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To consider all these factors, Li et al. [8] introduced the following nonautonomous population model with stage-structure, diffusion and time delay:

$$\left\{ \begin{array}{l} x_1'(t) = \alpha_1(t)y_1(t) - r_1(t)x_1(t) - \alpha_1(t-\tau) \exp\left(-\int_{t-\tau}^t r_1(s) ds\right) y_1(t-\tau), \\ y_1'(t) = \alpha_1(t-\tau) \exp\left(-\int_{t-\tau}^t r_1(s) ds\right) y_1(t-\tau) - \beta_1(t)y_1^2(t) \\ \quad + D_1(t)(y_2(t) - y_1(t)) + R(t)y_1(t)z(t), \\ z'(t) = \alpha_3(t)z(t) - r_3(t)z^2(t) - \theta(t)y_1(t)z(t), \\ x_2'(t) = \alpha_2(t)y_2(t) - r_2(t)x_2(t) - \alpha_2(t-\tau) \exp\left(-\int_{t-\tau}^t r_2(s) ds\right) y_2(t-\tau), \\ y_2'(t) = \alpha_2(t-\tau) \exp\left(-\int_{t-\tau}^t r_2(s) ds\right) y_2(t-\tau) - \beta_2(t)y_2^2(t) + D_2(t)(y_1(t) - y_2(t)), \end{array} \right. \quad (1.1)$$

where $x_i(t)$, $y_i(t)$, $i = 1, 2$, represent the immature and mature predator population densities in the path i , respectively. $z(t)$ represents the prey population density in the patch 1, and $y_1(t)$, in patch 1, is its predator. The mature population $y_i(t)$, $i = 1, 2$, can disperse between the two patches. τ denotes the length of time that predator i ($i = 1, 2$) grow from the birth to maturity, $\alpha_i(t)$ denotes the bearing rate of immature predator in patch i , $i = 1, 2$, $\alpha_i(t - \tau)$ denotes the bearing rate of mature predator in patch i , $i = 1, 2$, $r_i(t)$ is the death rate of immature predator in patch i , $i = 1, 2$, $\beta_i(t)$ denotes the death rate of mature predator in patch i , $i = 1, 2$, $R(t)$ denotes the preying effective rate in patch 1, $D_i(t)$ is the diffusive coefficients of mature predator in patch i , $i = 1, 2$, α_3 denotes the bearing rates of prey in patch 1, r_3 denotes the death rate of prey in patch 1, θ denotes the preying rate in patch 1, $\alpha_i(t)$, $r_i(t)$ ($i = 1, 2, 3$), $\beta_i(t)$, $D_i(t)$ ($i = 1, 2$), $R(t)$, $\theta(t)$ are positive continuous functions on $[0, +\infty)$.

In [8], the authors first established the existence of a positive periodic solution by using a fixed point theorem (see [8]) and the persistent result drawn by them. Then obtained the sufficient condition for a unique positive periodic solution which is globally attractive by using Lyapunov functional. To state the result in [8], we make two assumptions and a notation:

(H1) all the coefficients in system (1.1) are positive continuous ω -periodic functions with $\omega > 0$;

(H2) $0 < \min\{\underline{\alpha}_i, \underline{r}_i \ (i = 1, 2, 3), \underline{\beta}_i, \underline{D}_i \ (i = 1, 2), \underline{R}, \underline{\theta}\}$
 $\leq \max\{\bar{\alpha}_i, \bar{r}_i \ (i = 1, 2, 3), \bar{\beta}_i, \bar{D}_i \ (i = 1, 2), \bar{R}, \bar{\theta}\} < +\infty.$

For a positive continuous ω -periodic function $f(t)$, we set

$$\bar{f} = \max_{t \in [0, \omega]} \{f(t)\}, \quad \underline{f} = \min_{t \in [0, \omega]} \{f(t)\}, \quad \tilde{f} = \frac{1}{\omega} \int_0^\omega f(t) dt.$$

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