

# A nonconforming covolume method for elliptic problems

Yun K. Hyon <sup>a</sup>, Ho J. Jang <sup>b</sup>, Do Y. Kwak <sup>a,\*,1</sup>

<sup>a</sup> *Department of Mathematics, KAIST, Daejeon, Republic of Korea*

<sup>b</sup> *Department of Mathematics, HanYang University, Seoul, South Korea*

---

## Abstract

We consider a control volume (covolume) method for second-order elliptic PDEs with the rotated- $Q_1$  nonconforming finite element on rectangular grids. The coefficient  $\kappa$  may a variable, diagonal tensor, or discontinuous. We prove first-order convergence in  $H^1$  norm and second order convergence in  $L^2$  norm when the partition is square. Our numerical experiments show that our covolume scheme has about 30% less error than FEM even when  $\kappa$  is discontinuous tensor.  
© 2007 Elsevier Inc. All rights reserved.

**Keywords:** Covolume method; Rotated bilinear finite element method; Duality; Optimal order

---

## 1. Introduction

In this paper, we consider a covolume scheme with  $Q_1$  nonconforming finite element method (FEM) for the second-order elliptic equations with tensor coefficients. We prove first-order convergence in  $H^1$  norm and second-order convergence in  $L^2$  norm. This scheme was first introduced for Stokes problems in [3,6]. We apply it to elliptic problems with variable, discontinuous, and tensor coefficient. For other type of finite volume methods, we refer to [1,2,4–7,11–13,15] and for finite element method, we refer to [8,9,14].

The analysis of these covolume methods can be well described if we introduce a transfer operator  $\gamma$  from usual FEM space to the space of piecewise constant. As a result, the scheme can be viewed as a Galerkin scheme rather than a Petrov–Galerkin scheme.

Let  $\Omega$  be a bounded polygonal domain in  $\mathbb{R}^2$  with the boundary  $\partial\Omega$ . We consider the following second-order elliptic boundary value problem:

$$\begin{aligned} -\operatorname{div}(\kappa \nabla u) &= f, & \text{in } \Omega, \\ u &= 0, & \text{on } \partial\Omega, \end{aligned} \tag{1}$$

where  $\kappa = \kappa(x) := \operatorname{diag}(\kappa_1(x), \kappa_2(x))$  is a diagonal and uniformly positive definite matrix. For  $Q_1$  nonconforming finite element method, we only consider the case where  $\Omega$  is a union of axi-parallel domain. Let  $h > 0$  be a

---

\* Corresponding author.

E-mail addresses: [hyon70@kaist.ac.kr](mailto:hyon70@kaist.ac.kr) (Y.K. Hyon), [hjjang@hanyang.ac.kr](mailto:hjjang@hanyang.ac.kr) (H.J. Jang), [kdy@kaist.ac.kr](mailto:kdy@kaist.ac.kr) (D.Y. Kwak).

<sup>1</sup> This work supported by a grant from Korea Research Foundation, KRF-2005-013-c00009.

parameter and let  $\mathcal{T}_h = \{K\}$  be a regular family of partition into rectangles of  $\Omega$  in the sense that there exist constants  $c > 0$ ,  $C > 0$  such that

$$ch^2 \leq |K| \leq Ch^2 \quad \text{for all } K \in \mathcal{T}_h.$$

Now we describe a  $Q_1$  nonconforming finite element method. Let  $S_K = \{v_h = a + bx_1 + cx_2 + d(x_1^2 - x_2^2) \text{ on } K\}$  and let

$$N_h = \left\{ v_h|_K \in S_K, \int_{K \cap \partial K} v_h d\sigma = \int_{K' \cap \partial K'} v_h d\sigma \text{ if } K, K' \text{ are adjacent, and } \int_{\partial K \cap \partial \Omega} v_h d\sigma = 0 \right\}. \quad (2)$$

The usual nonconforming variational formulation of (1) is defined through element-wise form, i.e, we let

$$a_h(v_h, w_h) = \sum_K (\kappa \nabla v_h, \nabla w_h)_K, \quad \text{for } v_h, w_h \in N_h.$$

Let  $\|\cdot\|_{0,D}$  (dropping  $D$  when  $D = \Omega$ ) denote the usual  $L^2(D)$  norm on a domain  $D$ ;  $D = K$  or  $\Omega$ ,  $\partial K$ ,  $\partial \Omega$ , etc., and  $|\cdot|_{1,h} = |a_h(\cdot, \cdot)|^{1/2}$  be the discrete energy norm induced by  $a_h(\cdot, \cdot)$ . Then it is well-known [14,4,12,8] that the nonconforming finite element solution defined by

$$a_h(\tilde{u}_h, v_h) = (f, v_h), \quad \text{for all } v_h \in N_h,$$

satisfies

$$\|u - \tilde{u}_h\|_0 + h|u - \tilde{u}_h|_1 \leq Ch^2 \|f\|_0. \quad (3)$$

Now we consider a covolume formulation of the problem (1). For that purpose, we need to subdivide the given partition by connecting the vertices of each element with its center  $C$ , resulting in four subtriangles. Now the region consisting of two adjacent triangles sharing a common edge is denoted by  $K^*$ , called a covolume. The midpoints of edges are denoted by  $m_i, i = 1, \dots, 4$ . To define the covolume method, we need another space (Fig. 1)

$$W_h = \{v_h|_{K^*} \text{ is constant on each } K^*, \text{ and } 0 \text{ on the boundary covolumes}\} \quad (4)$$

and an operator connecting  $N_h$  to  $W_h$ . Let  $K_j^*$  be the covolume with associated edge  $e_j$ , and  $m_j$  denote its midpoint. Let  $\bar{v}_h = \frac{1}{|e_j|} \int_{e_j} v_h d\sigma$  be the average of  $v_h$  on the edge  $e_j$ . Then we introduce a transfer operator  $\gamma : N_h \rightarrow W_h$  by

$$\gamma v_h|_{K^*} = \sum_{K_j^*} \bar{v}_h(m_j) \chi_j(x),$$

where  $\chi_j$  is the characteristic function of  $K_j^*$ .

Find  $u_h^* \in N_h$  such that

$$a_h^*(u_h^*, v_h) = (f, \gamma v_h) \quad \text{for all } v_h \in N_h, \quad (5)$$

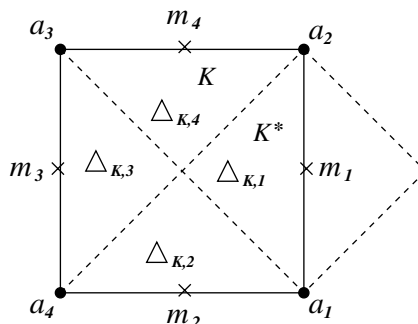


Fig. 1. A typical element  $K$  and its covolume partition  $K^*$ .

Download English Version:

<https://daneshyari.com/en/article/4634652>

Download Persian Version:

<https://daneshyari.com/article/4634652>

[Daneshyari.com](https://daneshyari.com)