



## A finite element method for singular solutions of the Navier–Stokes equations on a non-convex polygon

Hyung Jun Choi<sup>\*,1</sup>, Jae Ryong Kweon

Department of Mathematics, Pohang University of Science and Technology, Pohang 790-784, Gyeongbuk, Republic of Korea

### ARTICLE INFO

#### Article history:

Received 20 May 2014

Received in revised form 31 March 2015

#### MSC:

65N12

65N30

#### Keywords:

Stokes' corner singularity

Finite element method

Error estimate

### ABSTRACT

It is shown in Choi and Kweon (2013) that a solution of the Navier–Stokes equations with no-slip boundary condition on a non-convex polygon can be written as  $[\mathbf{u}, p] = \mathcal{C}_1[\Phi_1, \phi_1] + \mathcal{C}_2[\Phi_2, \phi_2] + [\mathbf{u}_R, p_R]$  near each non-convex vertex, where  $[\mathbf{u}_R, p_R] \in \mathbf{H}^2 \times H^1$ ,  $[\Phi_i, \phi_i]$  are corner singularity functions for the Stokes problem with no-slip condition, and  $\mathcal{C}_i \in \mathbb{R}$  are coefficients which are called the stress intensity factors. We design a finite element method to approximate the coefficients  $\mathcal{C}_i$  and the regular part  $[\mathbf{u}_R, p_R]$ , show the unique existence of the approximations, and derive their error estimates. Some numerical examples are given, confirming convergence rates for the approximations.

© 2015 Elsevier B.V. All rights reserved.

### 1. Introduction

Our concern is with a stable finite element scheme handling the singular behavior at the corner of solutions for the stationary Navier–Stokes equations on a (non-convex) polygon. For this we employ a known decomposition (see [1]) of the solution into a singular part plus a regular part near the non-convex vertex. The singular part consists of the multiplication of the coefficients and the leading corner singularities for the Stokes operator with no-slip boundary condition on the infinite sector. It is seen from [1] that each coefficient of the corner singularities is regarded as a continuous linear functional on the space  $\mathbf{H}^{s-2} \times H^{s-1}$  for  $s\tilde{\gamma}\lambda_i + 1$ , called the stress intensity factor, and the regular part is known to have the  $\mathbf{H}^2 \times H^1$ -regularity provided that the given force has the  $L^2$ -regularity, where  $\lambda_i \in (1/2, 1)$  denotes the singular exponent. In this paper we propose a finite element scheme for the stress intensity factors and the regular part.

Let  $\Omega$  be a non-convex polygon in the plane  $\mathbb{R}^2$  with the boundary  $\Gamma = \partial\Omega$ . The stationary Navier–Stokes equations to be considered in this paper are

$$\begin{aligned} -\mu\Delta\mathbf{u} + (\mathbf{u} \cdot \nabla)\mathbf{u} + \nabla p &= \mathbf{f} \quad \text{in } \Omega, \\ \operatorname{div}\mathbf{u} &= g \quad \text{in } \Omega, \\ \mathbf{u} &= \mathbf{0} \quad \text{on } \Gamma, \end{aligned} \tag{1.1}$$

where  $\mathbf{u}$  is the velocity vector,  $p$  is the pressure;  $\mu$  is a viscous number with  $\mu\tilde{\gamma}0$ ;  $\mathbf{f}$  and  $g$  are given functions with  $\int_{\Omega} g \, dx = 0$ . Usually the right hand side  $g$  is set to be zero for incompressibility but the non-vanishing  $g \neq 0$  is for specifying the regularity of  $g$  in the coefficients of the corner singularities (see (2.1)). In this paper we assume that the boundary  $\Gamma$

\* Corresponding author.

E-mail addresses: [choihjs@gmail.com](mailto:choihjs@gmail.com) (H.J. Choi), [kweon@postech.ac.kr](mailto:kweon@postech.ac.kr) (J.R. Kweon).

<sup>1</sup> Current address: Research Center, Samsung SDS, Seoul 138-240, Republic of Korea.

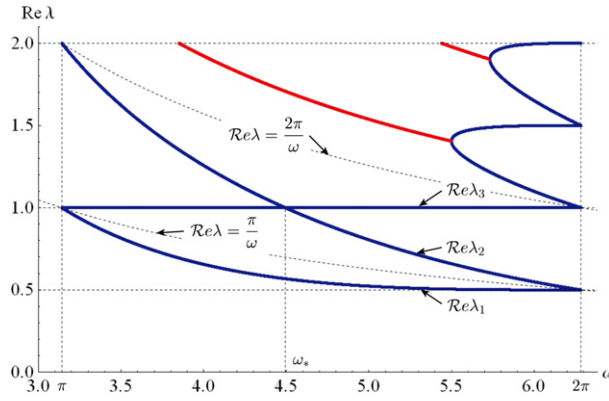


Fig. 1. The singular exponents  $\lambda_i$ .

has only one non-convex vertex  $P$ , for simplicity. Denote by  $\omega := \omega_2 - \omega_1 \tilde{\gamma} \pi$  an opening angle at  $P$ , where  $\omega_i$  are numbers satisfying  $\omega_1 < \omega_2 < \omega_1 + 2\pi$ .

Throughout this paper we will use the corner singularity functions for the Stokes operator  $\mathbf{L}[\mathbf{v}, q] = [-\mu \Delta \mathbf{v} + \nabla q, -\text{div} \mathbf{v}]$  with no-slip boundary condition (see [2, Section 5.1]). The leading singular eigenvalues  $\lambda_i$ , which are the roots of the trigonometric equation:  $\sin^2(\lambda\omega) - \lambda^2 \sin^2 \omega = 0$ , are real and ordered by

$$\text{Case 1: } 1/2 < \lambda_1 < \pi/\omega < \lambda_2 = 1 < \lambda_3 < 2\pi/\omega, \quad \omega \in (\pi, \omega_*), \tag{1.2a}$$

$$\text{Case 2: } 1/2 < \lambda_1 < \pi/\omega < \lambda_2 < \lambda_3 = 1 < 2\pi/\omega, \quad \omega \in (\omega_*, 2\pi), \tag{1.2b}$$

where  $\omega_* \approx 1.4303\pi$  is the solution of the equation:  $\tan \omega = \omega$  in the interval  $(0, 2\pi]$ . Throughout this paper we shall consider Case 2 for a generalization. Letting the non-convex vertex be placed at the origin, the corner singularities for velocity and pressure are given by

$$\Phi_i = \mu^{-1} \chi r^{\lambda_i} \mathcal{T}_i(\theta), \quad \phi_i = \chi r^{\lambda_i - 1} \xi_i(\theta), \tag{1.3}$$

where  $\mathcal{T}_i(\theta)$  and  $\xi_i(\theta)$  are certain smooth trigonometric eigenfunctions for velocity and pressure, corresponding to the eigenvalue  $\lambda_i$ , and  $\chi$  is a smooth cutoff function which has a support near the origin. Obviously the function  $\mathcal{T}_i$  satisfies  $\mathcal{T}_i(\omega_1) = \mathcal{T}_i(\omega_2) = 0$ . In particular, for  $\lambda_i = 1$ , the singularities are  $\Phi_i = 0$  and  $\phi_i = 4\chi$ , which are smooth functions. See Fig. 1.

In what follows, for an open set  $D \subset \mathbb{R}^2$ ,  $W^{s,q}(D)$  denotes the usual fractional Sobolev space with norm  $\|v\|_{s,q,D}$  and  $L^\infty(D)$  the measurable space with norm  $|v|_{\infty,D} := \text{ess sup}\{|v(\mathbf{x})| : \mathbf{x} \in D\}$  (see [3]). If  $q = 2$ , denote by  $H^s(D) = W^{s,2}(D)$  and  $\|v\|_{s,D} = \|v\|_{s,2,D}$ . Also we define  $H_0^1(D) = \{v \in H^1(D) : v|_{\partial D} = 0\}$ ,  $L_0^2(D) = \{v \in L^2(D) : \int_D v \, dx = 0\}$ ,  $H_0^s(D) = H^s(D) \cap H_0^1(D)$  for  $s \geq 1$ , and  $\tilde{H}^s(D) = H^s(D) \cap L_0^2(D)$  for  $s \geq 0$ . Let  $H^{-s}(D)$  be the dual space of  $H_0^s(D)$  with  $\|f\|_{-s,D} := \sup\{\langle f, v \rangle / \|v\|_{s,D} : 0 \neq v \in H_0^s(D)\}$ , where  $\langle \cdot, \cdot \rangle$  means the duality pairing. Similarly  $\tilde{H}^{-s}(D)$  denotes the dual space of  $\tilde{H}^s(D)$  and  $H'$  also means the dual space of  $H$ . Furthermore denote by  $\mathbf{H}^s(D) = H^s(D) \times H^s(D)$  and similar for other spaces. If  $D = \Omega$ , we will omit the domain  $\Omega$  in spaces and norms such as  $H^s = H^s(\Omega)$  and  $\|v\|_s = \|v\|_{s,\Omega}$ . Throughout this paper let  $C\tilde{\gamma}0$  be a generic constant only depending on the domain  $\Omega$ . Define the number  $s_i = \lambda_i + 1$ , which is used in classifying the regularity order space of the solution depending on the corner singularity.

We state a basic corner singularity result for the Navier–Stokes equations (1.1).

**Theorem 1.1** (Theorem 1.2 in [1]). Suppose that  $\mathbf{f} \in \mathbf{H}^{-1}$  and  $g \in L_0^2$ . Let

$$\mathcal{N} = \sup_{\mathbf{u}, \mathbf{v}, \mathbf{w} \in \tilde{\mathbf{V}}} \frac{\int_\Omega [(\mathbf{w} \cdot \nabla) \mathbf{u}] \cdot \mathbf{v} \, dx}{\|\nabla \mathbf{u}\|_0 \|\nabla \mathbf{v}\|_0 \|\nabla \mathbf{w}\|_0},$$

where  $\tilde{\mathbf{V}} = \{\mathbf{v} \in \mathbf{H}_0^1 : \text{div} \mathbf{v} = 0\}$ . If  $\mu \tilde{\gamma} [C_1 \mathcal{N} (\|\mathbf{f}\|_{-1} + \mu \|g\|_0)]^{1/2} + C_1 \|g\|_0$  for some given constant  $C_1 \tilde{\gamma} 0$ , there is a unique solution  $[\mathbf{u}, p] \in \mathbf{H}_0^1 \times L_0^2$  of the problem (1.1), with  $\mu \|\mathbf{u}\|_1 + \|p\|_0 \leq C_a (\|\mathbf{f}\|_{-1} + \mu \|g\|_0)$  for some constant  $C_a$ .

Furthermore, for a number  $s$  satisfying  $\pi/\omega + 1 < s_2 < s \leq 2$  we assume that  $\mathbf{f} \in \mathbf{H}^{s-2}$  and  $g \in \tilde{H}^{s-1}$ . If  $\mu \tilde{\gamma} C_b (\|\mathbf{f}\|_{s-2} + \mu \|g\|_{s-1})^{1/2}$  for some given constant  $C_b \tilde{\gamma} 0$ , there are some coefficients  $c_i$  and a regular part  $[\mathbf{u}_R, p_R] \in \mathbf{H}_0^s \times H^{s-1}$  such that the solution  $[\mathbf{u}, p]$  can be split by

$$\mathbf{u} = \sum_{i=1}^2 c_i \Phi_i + \mathbf{u}_R, \quad p = \sum_{i=1}^2 c_i \phi_i + p_R, \tag{1.4}$$

and the remainder  $[\mathbf{u}_R, p_R]$  and the coefficients  $c_i$  satisfy the regularity estimate:

$$\mu \|\mathbf{u}_R\|_s + \|p_R\|_{s-1} + \sum_{i=1}^2 |c_i| \leq C_b (\|\mathbf{f}\|_{s-2} + \mu \|g\|_{s-1}). \tag{1.5}$$

Download English Version:

<https://daneshyari.com/en/article/4638234>

Download Persian Version:

<https://daneshyari.com/article/4638234>

[Daneshyari.com](https://daneshyari.com)