



An explicit method for systems of equilibrium problems and fixed points of infinite family of nonexpansive mappings[☆]

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ABSTRACT

Let H be a Hilbert space, $\{T_i\}_{i \in \mathbb{N}}$ a family of nonexpansive mappings from H into itself, $G_i : C \times C \rightarrow \mathbb{R}$ a finite family of equilibrium functions ($i \in \{1, 2, \dots, K\}$), A a strongly positive bounded linear operator with coefficient $\tilde{\gamma}$ and f an α -contraction on H . Let W_n be the mapping generated by $\{T_i\}$ and $\{\lambda_n\}$ as in (1.5), let $S_{r_{k,n}}^k$ be the resolvent generated by G_k and $r_{k,n}$ as in Lemma 2.4. Moreover, let $\{r_{k,n}\}_{k=1}^K$, $\{\epsilon_n\}$ and $\{\lambda_n\}$ satisfy appropriate conditions and $F := (\bigcap_{k=1}^K \text{SEP}(G_k)) \cap (\bigcap_{n \in \mathbb{N}} \text{Fix}(T_n)) \neq \emptyset$; we introduce an explicit scheme which defines a suitable sequence as follows:

$$z_{n+1} = \epsilon_n \gamma f(z_n) + (I - \epsilon_n A) W_n S_{r_{1,n}}^1 S_{r_{2,n}}^2 \cdots S_{r_{K,n}}^K z_n \quad \forall n \in \mathbb{N}$$

and $\{z_n\}$ strongly converges to $x^* \in F$ which satisfies the variational inequality $\langle (A - \gamma f)x^*, x - x^* \rangle \geq 0$ for all $x \in F$. The results presented in this paper mainly extend and improve some recent results in [Vittorio Colao, et al., An implicit method for finding common solutions of variational inequalities and systems of equilibrium problems and fixed points of infinite family of nonexpansive mappings, *Nonlinear Anal.* 71 (2009) 2708–2715; S. Plubtieng, R. Punpaeng, A general iterative method for equilibrium problems and fixed point problems in Hilbert spaces, *J. Math. Anal. Appl.* 336 (2007) 455–469; S. Takahashi, W. Takahashi, Viscosity approximation methods for equilibrium problems and fixed point problems in Hilbert spaces, *J. Math. Anal. Appl.* 331 (2007) 506–515].

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1. Introduction

Throughout this paper, we always assume that H is a real Hilbert space with inner product $\langle \cdot, \cdot \rangle$ and norm $\| \cdot \|$, respectively, C is a nonempty closed convex subset of H and P_C is the metric projection of H onto C . In the following, we denote by “ \rightarrow ” strong convergence, by “ \rightharpoonup ” weak convergence and by “ \mathbb{R} ” the real number set.

Let $G : C \times C \rightarrow \mathbb{R}$ be an equilibrium function, that is

$$G(u, u) = 0 \quad \text{for every } u \in C.$$

The equilibrium problem is defined as follows:

$$\text{Find } \tilde{x} \in C \text{ such that } G(\tilde{x}, y) \geq 0 \text{ for all } y \in C. \quad (1.1)$$

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A solution of (1.1) is said to be an equilibrium point and the set of the equilibrium points is denoted by $SEP(G)$. This topic has been considered in [1,2]. We shall assume some mild conditions on G in such a way that results can be applied in several cases including optimization problems, fixed point problems and convex vector minimization problems [3–6].

For solving the equilibrium problem on a bifunction $G : C \times C \rightarrow \mathbb{R}$, let us assume that G satisfies the following conditions:

- (A₁) $G(x, x) = 0$ for all $x \in C$;
- (A₂) G is monotone, i.e., $G(x, y) + G(y, x) \leq 0$ for all $x, y \in C$;
- (A₃) for each $x, y, z \in C$, $\lim_{t \rightarrow 0} G(tz + (1-t)x, y) \leq G(x, y)$;
- (A₄) for each $x \in C$, $y \mapsto G(x, y)$ is convex and lower semicontinuous.

Let A be a bounded linear operator on H , a mapping $f : H \rightarrow H$ an α -contraction (i.e. $\|f(x) - f(y)\| \leq \alpha \|x - y\|$, $\forall x, y \in H$). The following variational inequality problem with viscosity is of great interest [7,8]. Find x^* in C such that

$$\langle (A - \gamma f)x^*, x - x^* \rangle \geq 0, \quad \forall x \in C \quad (1.2)$$

which is the optimality condition for the minimization problem

$$\min_{x \in C} \frac{1}{2} \langle Ax, x \rangle - h(x),$$

where h is a potential function for γf (i.e., $h'(x) = \gamma f(x)$ for $x \in H$).

On the other hand, given a nonexpansive map T , from H into itself (i.e. $\|Tx - Ty\| \leq \|x - y\|$ for all $x, y \in H$) and using $\text{Fix}(T) := \{x \in H : Tx = x\}$ denote the fixed point set of T , finding an optimal point in $\text{Fix}(T)$ is a matter of interest in various branches of science (see [9–11]).

Recently, Plubtieng and Punpaeng [12] proved a strong convergence theorem for an implicit iterative sequence $\{x_n\}$ obtained from the viscosity approximation iteration method (1.3) for finding a common element in $SEP(G) \cap \text{Fix}(T)$:

$$\begin{cases} G(y_n, u) + \frac{1}{r_n} \langle u - y_n, y_n - x_n \rangle \geq 0, & \forall u \in C, \\ x_n = \alpha_n f(x_n) + (1 - \alpha_n)Ty_n. \end{cases} \quad (1.3)$$

And recently, S. Takahashi and W. Takahashi [13] introduced the following explicit iterative scheme (1.4)

$$\begin{cases} G(y_n, u) + \frac{1}{r_n} \langle u - y_n, y_n - x_n \rangle \geq 0, & \forall u \in C, \\ x_{n+1} = \alpha_n f(x_n) + (1 - \alpha_n)Ty_n \end{cases} \quad (1.4)$$

and also proved that the sequence $\{x_n\}$ defined by (1.4) strongly converges to a common element of $SEP(G) \cap \text{Fix}(T)$.

Let C be a nonempty convex subset of a Banach space X . Let $\{T_i\}$ be an infinite family of nonexpansive mappings of C into itself and let $\{\lambda_i\}$ be a real sequence such that $0 \leq \lambda_i \leq 1$ for every $i \in \mathbb{N}$. Following [14], for any $n \geq 1$, we define a mapping W_n of C into itself as follows:

$$\begin{aligned} U_{n,n+1} &:= I, \\ U_{n,n} &:= \lambda_n T_n U_{n,n+1} + (1 - \lambda_n)I, \\ &\vdots \\ U_{n,k} &:= \lambda_k T_k U_{n,k+1} + (1 - \lambda_k)I, \\ &\vdots \\ U_{n,2} &:= \lambda_2 T_2 U_{n,3} + (1 - \lambda_2)I, \\ W_n &:= U_{n,1} = \lambda_1 T_1 U_{n,2} + (1 - \lambda_1)I. \end{aligned} \quad (1.5)$$

Very recently, Colao [15] studied the following implicit iterative sequence $\{z_n\}$ defined by (1.6), with the initial guess $z_0 \in H$ chosen arbitrarily and satisfying appropriate conditions,

$$z_n = \epsilon_n \gamma f(z_n) + (I - \epsilon_n A)W_n S_{r_{1,n}}^1 S_{r_{2,n}}^2 \cdots S_{r_{k,n}}^k z_n \quad \forall n \in \mathbb{N} \quad (1.6)$$

and proved that the sequence $\{z_n\}$ converges strongly to $x^* \in F := (\bigcap_{k=1}^K SEP(G_k)) \cap (\bigcap_{n \in \mathbb{N}} \text{Fix}(T_n))$ which also satisfies the variational inequality (1.2).

In this paper, motivated in [15,12,13], we study an explicit approximation process as follows:

$$z_{n+1} = \epsilon_n \gamma f(z_n) + (I - \epsilon_n A)W_n S_{r_{1,n}}^1 S_{r_{2,n}}^2 \cdots S_{r_{k,n}}^k z_n \quad \forall n \in \mathbb{N}. \quad (1.7)$$

2. Preliminaries

In a real Hilbert space H , the following inequality holds

$$\|x + y\|^2 \leq \|x\|^2 + 2\langle y, x + y \rangle, \quad \text{for all } x, y \in H. \quad (2.1)$$

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